# OMRON

## **Machine Automation Controller**

**NX-series** 

# **Digital I/O Units**

## **User's Manual**

NX-ID

NX-IA

NX-OC .

NX-OD

NX-MD

Digital I/O Units





W521-E1-10

#### NOTE

All rights reserved. No part of this publication may be reproduced, stored in a retrieval system, or transmitted, in any form, or by any means, mechanical, electronic, photocopying, recording, or otherwise, without the prior written permission of OMRON.

No patent liability is assumed with respect to the use of the information contained herein. Moreover, because OMRON is constantly striving to improve its high-quality products, the information contained in this manual is subject to change without notice. Every precaution has been taken in the preparation of this manual. Nevertheless, OMRON assumes no responsibility for errors or omissions. Neither is any liability assumed for damages resulting from the use of the information contained in this publication.

#### Trademarks

- · Sysmac and SYSMAC are trademarks or registered trademarks of OMRON Corporation in Japan and other countries for OMRON factory automation products.
- · Microsoft, Windows, Windows Vista, Excel, and Visual Basic are either registered trademarks or trademarks of Microsoft Corporation in the United States and other countries.
- EtherCAT® is registered trademark and patented technology, licensed by Beckhoff Automation GmbH, Germany.
- Safety over EtherCAT® is registered trademark and patented technology, licensed by Beckhoff Automation GmbH, Germany.
- ODVA, CIP, CompoNet, DeviceNet, and EtherNet/IP are trademarks of ODVA.
- The SD and SDHC logos are trademarks of SD-3C, LLC.





Other company names and product names in this document are the trademarks or registered trademarks of their respective companies.

#### Copyrights

Microsoft product screen shots reprinted with permission from Microsoft Corporation.

## Introduction

Thank you for purchasing an NX-series Digital I/O Unit.

This manual contains information that is necessary to use the NX-series Digital I/O Unit. Please read this manual and make sure you understand the functionality and performance of the NX-series Digital I/O Unit before you attempt to use it in a control system.

Keep this manual in a safe place where it will be available for reference during operation.

### **Intended Audience**

This manual is intended for the following personnel, who must also have knowledge of electrical systems (an electrical engineer or the equivalent).

- · Personnel in charge of introducing FA systems.
- · Personnel in charge of designing FA systems.
- · Personnel in charge of installing and maintaining FA systems.
- · Personnel in charge of managing FA systems and facilities.

For programming, this manual is intended for personnel who understand the programming language specifications in international standard IEC 61131-3 or Japanese standard JIS B 3503.

### **Applicable Products**

This manual covers the following product.

NX-series Digital I/O Unit

NX-IDDDDDD /IADDDD /ODDDDDD/OCDDDD/MDDDDD

# **CONTENTS**

	Introduction		
	Intended Audience		
	Applicable Products	1	
	Relevant Manuals	7	
	Manual Structure	8	
	Page Structure and Icons		
	Special Information		
	Terms and Conditions Agreement	12	
	Warranty, Limitations of Liability		
	Application Considerations		
	Disclaimers	13	
	Safety Precautions	14	
	Definition of Precautionary Information		
	Symbols		
	Warnings		
	Cautions	16	
	Precautions for Safe Use	18	
	Precautions for Correct Use	23	
	Regulations and Standards	24	
	Conformance to EU Directives		
	Conformance to UL and CSA Standards	25	
	Conformance to Shipbuilding Standards		
	Conformance to KC Certification		
	• • •		
	Unit Versions	26	
	Unit Versions		
	Unit Versions and Support Software Versions	27	
	Related Manuals	28	
	Terminology	32	
	Revision History	34	
	Sections in this Manual	35	
Section	on 1 Features and System Configuration		
	1-1 Features and Types of Digital I/O Units	1-2	
	1-1-1 Digital I/O Unit Features	1-2	
	1-1-2 Digital I/O Unit Types	1-4	
	1-2 System Configuration	1-5	
	1-2-1 System Configuration in the Case of a CPU Unit		
	1-2-2 System Configuration of Slave Terminals		
	1-2-3 System Configuration in the Case of a Communication Control Unit	1-9	

1-3	Model List	1-11
	1-3-1 Model Notation	
	1-3-2 Digital Input Units	
	1-3-3 Digital Output Units	
	1-3-4 Digital Mixed I/O Units	
1-4	List of Functions	
	1-4-1 Digital Input Units	
	1-4-2 Digital Output Units	
	1-4-3 Digital Mixed I/O Units	
1-5	Support Software	1-23
Section 2	Specifications	
2-1	General Specifications	2-2
2-2	Individual Specifications	
	marviduai Opeemisuutens	
Section 3	Part Names and Functions	
3-1	Part Names	3-2
	3-1-1 Screwless Clamping Terminal Block Type	3-2
	3-1-2 M3 Screw Terminal Block Type	
	3-1-3 Connector Types	3-8
3-2	Indicators	3-13
	3-2-1 TS Indicator	3-15
	3-2-2 IN/OUT Indicator	
	3-2-3 Appearance Change of the Indicators	3-17
Section 4	Installation and Wiring	
4-1	Installing NX Units	4-2
	4-1-1 Installing NX Units	
	4-1-2 Attaching Markers	
	4-1-3 Removing NX Units	
	4-1-4 Installation Orientation	4-7
4-2	Power Supply Types and Wiring	4-9
	4-2-1 Applications of I/O Power Supply and Supply Methods	
	4-2-2 Calculating the Total Current Consumption from I/O Power Supply	
4-3	Wiring the Terminals	4-13
	4-3-1 Wiring to the Screwless Clamping Terminal Block	4-13
	4-3-2 Wiring to M3 Screw Terminal Block	
	4-3-3 Wiring to MIL/Fujitsu Connectors	4-36
	4-3-4 Checking the Wiring	4-40
4-4	Wiring Examples	4-41
	4-4-1 Wiring the Input Units	
	4-4-2 Precautions when Wiring to the Input Units	
	4-4-3 Precautions when Wiring to the Output Units	4-55
Section 5	I/O Refreshing	
5-1	I/O Refreshing	
	5-1-1 I/O Refreshing from CPU Units to NX Units	
	5-1-2 I/O Refreshing from CPU Units or Industrial PCs to Slave Terminal	
	5-1-3 I/O Refreshing from the Communication Control Unit to NX Units	

	5-1-4 Calculating the I/O Response Times of NX Units	5-5
5-2	I/O Refreshing Methods	5-6
	5-2-1 Types of I/O Refreshing Methods	
	5-2-2 Setting the I/O Refreshing Methods	
	5-2-3 Selecting NX Units	
	5-2-4 Free-Run Refreshing	
	5-2-6 Synchronous Output Refreshing	
	5-2-7 Time Stamp Refreshing	
	5-2-8 Input Refreshing with Input Changed Time	
	5-2-9 Output Refreshing with Specified Time Stamp	
	5-2-10 An Example of Turning ON Outputs at Specific Times After the Sensor Inputs Change	5-34
Section 6	Digital Input Units	
6-1	Types of Digital Input Units	6-2
6-2	Specifications of I/O Data	6-4
	6-2-1 Allocable I/O Data	6-4
6-3	List of Settings	6-7
6-4	Function	
0-4		
	6-4-1 List of Digital Input Unit Functions	
Section 7	Digital Output Units	
7-1	Types of Digital Output Units	7-2
7-2	Specifications of I/O Data	7-5
	7-2-1 Allocable I/O Data	7-5
7-3	List of Settings	7-9
7-4	Function	7-12
	7-4-1 List of Digital Output Unit Functions	
	7-4-2 Load Rejection Output Setting	7-13
	7-4-3 Load Short-circuit Protection	7-17
7-5	Push-pull Output	7-19
7-6	Precautions when Using the Relay Output Units	7-20
Section 8	Digital Mixed I/O Units	
8-1	Types of Digital Mixed I/O Units	
8-2	Specifications of I/O Data	
	8-2-1 Allocable I/O Data	8-3
8-3	List of Settings	8-5
	8-3-1 Input Settings	
	8-3-2 Output Settings	8-6
8-4	Function	8-7
	8-4-1 Input Functions	
	8-4-2 Output Functions	8-8
Saction 0	Troublechooting	
Section 9	Troubleshooting	

9-1	How to Check for Errors	9-2				
9-2	-2 Checking for Errors with the Indicators					
9-3	Checking for Errors and Troubleshooting on the Support Software	9-5				
	9-3-1 Checking for Errors from the Sysmac Studio	9-5				
	9-3-2 Checking for Errors from Support Software Other Than the Sysmac Studio					
	9-3-3 Event Codes and Corrections for Errors					
9-4	•					
9-5	•					
3-3	9-5-1 Digital Inputs					
	9-5-2 Digital Outputs					
9-6	Troubleshooting Flowchart	9-22				
Section 1	0 Inspection and Maintenance					
10-	1 Cleaning and Inspection	10-2				
	10-1-1 Cleaning					
	10-1-2 Periodic Inspection					
10-	2 Maintenance Procedures	10-5				
Appendic	es					
A-1	Data Sheet	A-3				
	A-1-1 Model List					
	A-1-2 Digital Input Units					
	A-1-3 Digital Output Offits					
A-2	Dimensions	A-101				
	A-2-1 Screwless Clamping Terminal Block Type					
	A-2-2 M3 Screw Terminal Block Type					
	A-2-3 Connector Types					
A-3	Connecting Connector-Terminal Block Conversion Units and I/O Relay Terminal	sA-107				
	A-3-1 Patterns for Combining Connector-Terminal Block Conversion Units and I/O Relay Terminals	A-107				
	A-3-2 Combinations of Connections	A-109				
	A-3-3 Connector-Terminal Block Conversion Unit Connection Diagrams					
_	A-3-4 Connection Diagrams for I/O Relay Terminals					
	EMC Directive Measures for Relay Outputs					
A-5	List of NX Objects					
	A-5-1 Format of Object Descriptions					
	A-5-3 Digital Output Units					
	A-5-4 Digital Mixed I/O Units					
A-6	List of Screwless Clamping Terminal Block Models	A-163				
	A-6-1 Model Notation					
	A-6-2 List of Terminal Block Models					
A-7	Version Information with CPU Units					
<u> </u>	A-7-1 Relationship between Unit Versions of Units					
A-8	Version Information with Communications Coupler Units					
	A-8-1 Connection to an EtherCAT Coupler Unit					
Δ-9	Version Information with Communication Control Units					

### **CONTENTS**

	A-9-1	Relationship between Unit Versions of Units	A-170
A-10	Displa	ying the Edit Unit Operation Settings Tab Page	.A-172
	A-10-1	Connection to the CPU Unit or the Communication Control Unit	A-172
	A-10-2	Slave Terminal	A-174

## Index

# **Relevant Manuals**

The table below provides the relevant manuals for the NX-series Digital I/O Units.

Read all of the manuals that are relevant to your system configuration and application to make the most of the NX-series Digital I/O Units.

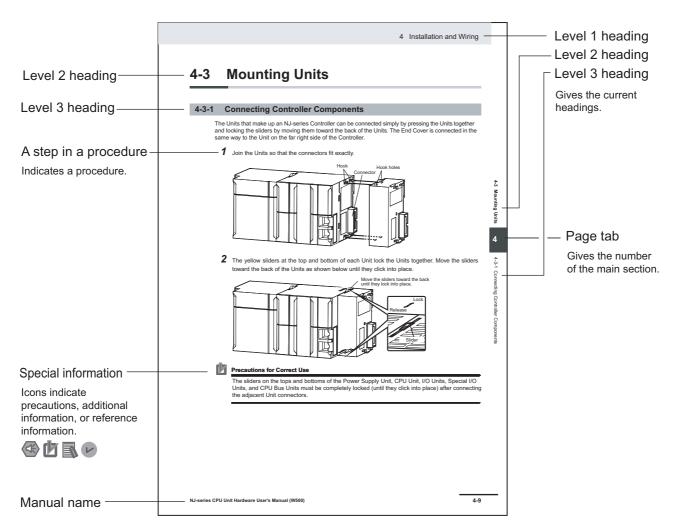
Other manuals, such as related product manuals, are necessary for specific system configurations and applications. Refer to *Related Manuals* on page 28 for the related manuals.

Manual name	Application
NX-series Digital I/O Units User's	Learning how to use NX-series Digital I/O Units
Manual	
NX-series Data Reference Man-	Referencing lists of the data that is required to configure systems with
ual	NX-series Units

## **Manual Structure**

### Page Structure and Icons

The following page structure and icons are used in this manual.



Note This illustration is provided only as a sample. It may not literally appear in this manual.

### **Special Information**

Special information in this manual is classified as follows:



#### **Precautions for Safe Use**

Precautions on what to do and what not to do to ensure safe usage of the product.



#### **Precautions for Correct Use**

Precautions on what to do and what not to do to ensure proper operation and performance.



#### **Additional Information**

Additional information to read as required.

This information is provided to increase understanding or make operation easier.



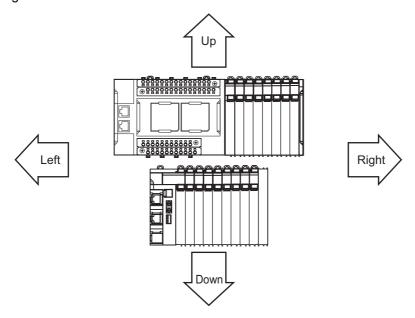
#### **Version Information**

Information on differences in specifications and functionality for CPU Units, Industrial PCs, Communications Coupler Units, and Communication Control Units with different unit versions and for different versions of the Support Software is given.

Note References are provided to more detailed or related information.

### **Precaution on Terminology**

- In this manual, "download" refers to transferring data from the Support Software to a physical device and "upload" refers to transferring data from a physical device to the Support Software.
- In this manual, the directions in relation to the Units are given in the following figure, which shows upright installation.



- This user's manual refers to the NY-series IPC Machine Controller Industrial Panel PCs and Industrial Box PCs as simply *Industrial PCs* or as *NY-series Industrial PCs*.
- This user's manual refers to the built-in EtherCAT port on an NJ/NX-series Controller or NY-series Industrial PC as simple a built-in EtherCAT port.
- This user's manual may omit manual names and manual numbers in places that refer to the user's
  manuals for CPU Units and Industrial PCs. The following table gives some examples. When necessary, refer to Related Manuals on page 28 to determine the appropriate manual based on the common text for the omitted contents.

#### Examples:

Manual name	Omitted contents	Common text
NJ/NX-series CPU Unit Software User's	Software user's manual for the con-	Software User's Manual
Manual	nected CPU Unit or Industrial PC	
NY-series		
IPC Machine Controller Industrial Panel PC		
/ Industrial Box PC		
Software User's Manual		
NJ/NX-series CPU Unit Built-in EtherCAT®	User's manual for built-in EtherCAT	Built-in EtherCAT port
Port User's Manual	port on the connected CPU Unit or	
NY-series	Industrial PC	
IPC Machine Controller Industrial Panel PC		
/ Industrial Box PC		
Built-in EtherCAT® Port		
User's Manual		

- This user's manual may omit manual names and manual numbers in places that refer to the user's manuals for Communications Coupler Units. If you use a Communications Coupler Unit, refer to Related Manuals on page 28 to identify the manual for your Unit.
- This user's manual may omit manual names and manual numbers in places that refer to the user's manuals for Communication Control Units. If you use a Communication Control Unit, refer to *Related Manuals* on page 28 to identify the manual for your Unit.

## **Terms and Conditions Agreement**

### Warranty, Limitations of Liability

### **Warranties**

### Exclusive Warranty

Omron's exclusive warranty is that the Products will be free from defects in materials and workmanship for a period of twelve months from the date of sale by Omron (or such other period expressed in writing by Omron). Omron disclaims all other warranties, express or implied.

#### Limitations

OMRON MAKES NO WARRANTY OR REPRESENTATION, EXPRESS OR IMPLIED, ABOUT NON-INFRINGEMENT, MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE OF THE PRODUCTS. BUYER ACKNOWLEDGES THAT IT ALONE HAS DETERMINED THAT THE PRODUCTS WILL SUITABLY MEET THE REQUIREMENTS OF THEIR INTENDED USE.

Omron further disclaims all warranties and responsibility of any type for claims or expenses based on infringement by the Products or otherwise of any intellectual property right.

#### Buyer Remedy

Omron's sole obligation hereunder shall be, at Omron's election, to (i) replace (in the form originally shipped with Buyer responsible for labor charges for removal or replacement thereof) the non-complying Product, (ii) repair the non-complying Product, or (iii) repay or credit Buyer an amount equal to the purchase price of the non-complying Product; provided that in no event shall Omron be responsible for warranty, repair, indemnity or any other claims or expenses regarding the Products unless Omron's analysis confirms that the Products were properly handled, stored, installed and maintained and not subject to contamination, abuse, misuse or inappropriate modification. Return of any Products by Buyer must be approved in writing by Omron before shipment. Omron Companies shall not be liable for the suitability or unsuitability or the results from the use of Products in combination with any electrical or electronic components, circuits, system assemblies or any other materials or substances or environments. Any advice, recommendations or information given orally or in writing, are not to be construed as an amendment or addition to the above warranty.

See http://www.omron.com/global/ or contact your Omron representative for published information.

## Limitation on Liability; Etc

OMRON COMPANIES SHALL NOT BE LIABLE FOR SPECIAL, INDIRECT, INCIDENTAL, OR CONSEQUENTIAL DAMAGES, LOSS OF PROFITS OR PRODUCTION OR COMMERCIAL LOSS IN ANY WAY CONNECTED WITH THE PRODUCTS, WHETHER SUCH CLAIM IS BASED IN CONTRACT, WARRANTY, NEGLIGENCE OR STRICT LIABILITY.

Further, in no event shall liability of Omron Companies exceed the individual price of the Product on which liability is asserted.

### **Application Considerations**

### **Suitability of Use**

Omron Companies shall not be responsible for conformity with any standards, codes or regulations which apply to the combination of the Product in the Buyer's application or use of the Product. At Buyer's request, Omron will provide applicable third party certification documents identifying ratings and limitations of use which apply to the Product. This information by itself is not sufficient for a complete determination of the suitability of the Product in combination with the end product, machine, system, or other application or use. Buyer shall be solely responsible for determining appropriateness of the particular Product with respect to Buyer's application, product or system. Buyer shall take application responsibility in all cases.

NEVER USE THE PRODUCT FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY OR IN LARGE QUANTITIES WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON PRODUCT(S) IS PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

### **Programmable Products**

Omron Companies shall not be responsible for the user's programming of a programmable Product, or any consequence thereof.

### **Disclaimers**

### **Performance Data**

Data presented in Omron Company websites, catalogs and other materials is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of Omron's test conditions, and the user must correlate it to actual application requirements. Actual performance is subject to the Omron's Warranty and Limitations of Liability.

## **Change in Specifications**

Product specifications and accessories may be changed at any time based on improvements and other reasons. It is our practice to change part numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the Product may be changed without any notice. When in doubt, special part numbers may be assigned to fix or establish key specifications for your application. Please consult with your Omron's representative at any time to confirm actual specifications of purchased Product.

### **Errors and Omissions**

Information presented by Omron Companies has been checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical or proofreading errors or omissions.

## **Safety Precautions**

## **Definition of Precautionary Information**

The following notation is used in this manual to provide precautions required to ensure safe usage of an NX-series Digital I/O Unit.

The safety precautions that are provided are extremely important to safety. Always read and heed the information provided in all safety precautions.

The following notation is used.



Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury. Additionally, there may be severe property damage.



Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury, or property damage.

### **Symbols**



The circle and slash symbol indicates operations that you must not do.

The specific operation is shown in the circle and explained in text.

This example indicates prohibiting disassembly.



The triangle symbol indicates precautions (including warnings).

The specific operation is shown in the triangle and explained in text.

This example indicates a precaution for electric shock.



The triangle symbol indicates precautions (including warnings).

The specific operation is shown in the triangle and explained in text.

This example indicates a general precaution.



The filled circle symbol indicates operations that you must do.

The specific operation is shown in the circle and explained in text.

This example shows a general precaution for something that you must do.

### **Warnings**

## 

### **During Power Supply**

Do not touch the terminal section while power is ON.

Electric shock may occur.



Do not attempt to take any Unit apart.

In particular, high-voltage parts are present in Units that supply power while power is supplied or immediately after power is turned OFF. Touching any of these parts may result in electric shock. There are sharp parts inside the Unit that may cause injury.



### Fail-safe Measures

Provide safety measures in external circuits to ensure safety in the system if an abnormality occurs due to malfunction of the CPU Unit, Industrial PC, other Units, or slaves or due to other external factors affecting operation.



Not doing so may result in serious accidents due to incorrect operation.

Emergency stop circuits, interlock circuits, limit circuits, and similar safety measures must be provided in external control circuits.



The CPU Unit or Industrial PC will turn OFF all outputs from Output Units in the following cases. The remote I/O slaves will operate according to the settings in the slaves.

- · If a power supply error occurs.
- If the power supply connection becomes faulty.
- If a CPU watchdog timer error or CPU reset occurs.
- If a Controller error in the major fault level occurs.



• While the CPU Unit is on standby until RUN mode is entered after the power is turned ON External safety measures must be provided to ensure safe operation of the system in such cases.

The outputs may remain ON or OFF due to deposition or burning of the output relays or destruction of the output transistors. As a countermeasure for such problems, external safety measures must be provided to ensure safe operation of the system.



If external power supplies for slaves or other devices are overloaded or short-circuited, the voltage will drop, outputs will turn OFF, and the system may be unable to read inputs. Provide external safety measures in control with monitoring of external power supply voltage as required so that the system operates safely in such a case.



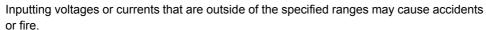
You must take fail-safe measures to ensure safety in the event of incorrect, missing, or abnormal signals caused by broken signal lines, momentary power interruptions, or other causes.



Not doing so may result in serious accidents due to incorrect operation.

### **Voltage and Current Inputs**

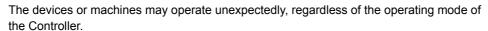
Make sure that the voltages and currents that are input to the Units and slaves are within the specified ranges.





### **Transferring**

Always confirm safety at the destination node before you transfer Unit configuration information, parameters, settings, or other data from tools such as the Sysmac Studio.





#### **Cautions**

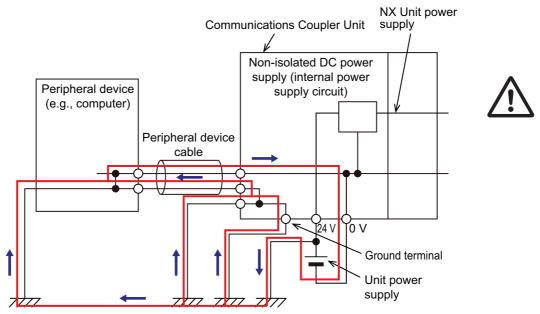
## **⚠** Caution

### Wiring

When you connect a computer or other peripheral device to a Communications Coupler Unit that has a non-isolated DC power supply, either ground the 0-V side of the external power supply (i.e. Unit power supply) or do not ground it at all.

If the peripheral devices are grounded incorrectly, the external power supply (i.e. Unit power supply) may be short-circuited.

Never ground the 24-V side of the power supply, as shown in the following figure.



Be sure that all terminal screws and cable connector screws are tightened to the torque specified in the relevant manuals. The loose screws may result in fire or malfunction.



## **Online Editing**

Execute online editing only after confirming that no adverse effects will be caused by deviations in the timing of I/O. If you perform online editing, the task execution time may exceed the task period, I/O may not be refreshed with external devices, input signals may not be read, and output timing may change.



## **Precautions for Safe Use**

### **Transporting**

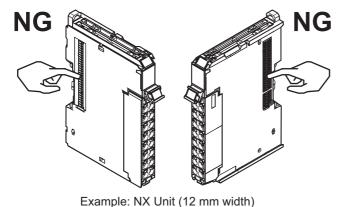
- When transporting any Unit, use the special packing box for it.
   Also, do not subject the Unit to excessive vibration or shock during transportation.
- Do not drop any Unit or subject it to abnormal vibration or shock. Doing so may result in Unit malfunction or burning.

### **Mounting**

- · Mount terminal blocks and connectors only after checking the mounting location carefully.
- Be sure that the terminal blocks, expansion cables, and other items with locking devices are properly locked into place.

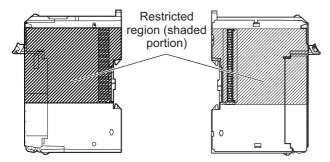
### Installation

- Always turn OFF the power supply before installing the Unit. If the power supply is not OFF, the Unit may malfunction or may be damaged.
- Always turn OFF the Unit power supply and I/O power supply before you remove the NX Unit.
- Do not apply labels or tape to the Unit. When the Unit is installed or removed, adhesive or scraps may adhere to the pins in the NX bus connector, which may result in malfunctions.
- Do not touch the pins in the NX bus connector on the Unit. Dirt may adhere to the pins in the NX bus connector, which may result in malfunctions.

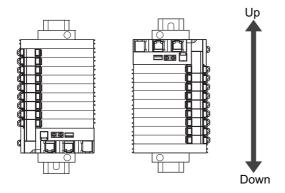


Do not write on an NX Unit with ink within the restricted region that is shown in the following figure.
Also do not get this area dirty. When the Unit is installed or removed, ink or dirt may adhere to the
pins in the NX bus connector, which may result in malfunctions in the CPU Rack or the Slave Terminal.

Refer to the user's manual for the connected CPU Unit, Communications Coupler Unit, or Communication Control Unit for details on the restricted region on the CPU Unit, Communications Coupler Unit, or Communication Control Unit.

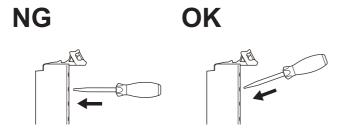


• For the installation orientations in the following figure, support the cables, e.g., with a duct, so that the End Plate on the bottom is not subjected to the weight of the cables. The weight of the cables may cause the bottom End Plate to slide downward so that the Slave Terminal is no longer secured to the DIN Track, which may result in malfunctions.

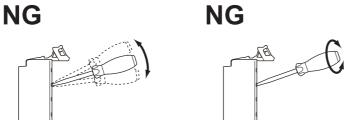


### Wiring

- Double-check all switches and other settings and double-check all wiring to make sure that they are correct before turning ON the power supply.
- · Use the correct wiring parts and tools when you wire the system.
- Do not pull on the cables or bend the cables beyond their natural limit. Also, do not place heavy objects on top of the cables or other wiring lines. Doing so may break the cable.
- · When wiring or installing the Units, do not allow metal fragments to enter the Units.
- Do not press the flat-blade screwdriver straight into the release holes on a screwless clamping terminal block. Doing so may damage the terminal block.



- When you insert a flat-blade screwdriver into a release hole on a screwless clamping terminal block, press it down with a force of 30N or less. Applying excessive force may damage the terminal block.
- Do not incline or twist the flat-blade screwdriver while it is in a release hole on a screwless clamping terminal block. Doing so may damage the terminal block.



- If you use reed switches for the input contacts for AC Input Units, use switches with an allowable current of 1 A or greater. If the capacity of the reed switches is too low, inrush current may fuse the contacts.
- Use crimp terminals for wiring the M3 screw terminal blocks. Do not connect bare stranded wires directly to the M3 screw terminal blocks.

### **Power Supply Design**

- Use all Units within the I/O power supply ranges that are given in the specifications.
- The I/O power supply current for the CPU Rack with an NX-series CPU Unit should be within the
  range specified for the CPU Unit model. For example, use the NX1P2 CPU Unit with a current of 4 A
  or less. Using the currents that are outside of the specifications may cause failure or damage. Refer
  to the user's manual for the connected CPU Unit for the I/O power supply current for the CPU Unit
  model.
- Supply sufficient power according to the contents of this manual.
- Use the power supply voltage that is specified in this manual.
- Do not apply voltages that exceed the rated value to any Input Unit.
- Do not apply voltages or connect loads to the Output Units or slaves in excess of the maximum ratings.
- Inrush current occurs when the power supply is turned ON. When selecting fuses or breakers for external circuits, consider their fusing and detection characteristics as well as the above precautions and allow sufficient margin in shut-off performance.

• Install external breakers and take other safety measures against short-circuiting and overcurrents in external wiring.

### **Turning ON the Power Supply**

· When you set the Operating Mode at Startup, confirm that no adverse effect will occur in the system.

### **Actual Operation**

- Before you start operation, always register the NX Units that are connected to the Communications Coupler Unit in the host communications master as the Unit Configuration Information.
- Check the user program, data, and parameter settings for proper execution before you use them for actual operation.
- If you change the fail-soft operation setting, the output status when the error occurs may also change. Confirm safety before you change the fail-soft operation setting.
- If you use fail-soft operation, write programming to determine whether Unit I/O data is valid. Without such programming, the user program cannot distinguish between Units for which I/O refreshing is continued and Units for which I/O refreshing is stopped.

### **Turning OFF the Power Supply**

- Do not disconnect the cable or turn OFF the power supply to the Controller or a Slave Terminal when downloading data or the user program from the Support Software.
- Always turn OFF the external power supply to the Units before attempting any of the following.

Mounting or removing an NX Unit, Communications Coupler Unit, CPU Unit, Industrial PC, or Communication Control Unit

Setting DIP switches or rotary switches

Connecting or wiring cables

Attaching or removing terminal blocks or connectors

Units that supply power continue to supply power to the Units for up to several seconds after the power supply is turned OFF. The PWR indicator remains lit as long as power is supplied. Confirm that the PWR indicator is not lit before you perform any of the above.

## **Operation**

 Confirm that the controlled system will not be adversely affected before you perform any of the following operations.

Changing the operating mode of the CPU Unit or the Industrial PC (including changing the setting of the Operating Mode at Startup)

Changing the user program or settings

Changing set values or present values

Forced refreshing

 Always sufficiently check the safety at the connected devices before you change the settings of a slave or Unit.

### **General Communications**

- Do not exceed the ranges that are given in the specifications for the communications distance and number of connected Units.
- Refer to the user's manual for the Communications Coupler Unit for precautions for the safe use of communications with the connected Communications Coupler Unit.

## **Unit Replacement**

• When you replace a Unit, start operation only after you transfer the settings and variables that are required for operation to the new Unit.

## Disposal

Dispose of the product according to local ordinances as they apply.

## **Precautions for Correct Use**

### Storage, Mounting, and Wiring

- Follow the instructions in this manual to correctly perform installation and wiring.
- Do not operate or store the Units in the following locations. Doing so may result in malfunction, in operation stopping, or in burning.

Locations subject to direct sunlight

Locations subject to temperatures or humidity outside the range specified in the specifications

Locations subject to condensation as the result of severe changes in temperature

Locations subject to corrosive or flammable gases

Locations subject to dust (especially iron dust) or salts

Locations subject to exposure to water, oil, or chemicals

Locations subject to shock or vibration

• Take appropriate and sufficient countermeasures during installation in the following locations.

Locations subject to strong, high-frequency noise

Locations subject to static electricity or other forms of noise

Locations subject to strong electromagnetic fields

Locations subject to possible exposure to radioactivity

Locations close to power lines

- Before touching a Unit, be sure to first touch a grounded metallic object in order to discharge any static build-up.
- Use the rated power supply voltage for the Units that supply power. Take appropriate measures to
  ensure that the specified power with the rated voltage and frequency is supplied in places where the
  power supply is unstable.
- Install the Units away from sources of heat and ensure proper ventilation. Not doing so may result in malfunction, in operation stopping, or in burning.
- Do not allow foreign matter to enter the openings in the Unit. Doing so may result in Unit burning, electric shock, or failure.

## **Actual Operation**

• If you change the event level of an error, the output status when the error occurs may also change. Confirm safety before you change an event level.

### **Turning OFF the Power Supply**

- Do not turn OFF the power supply while data is being transferred.
- Do not turn OFF the power supply while parameters are being written to the CPU Unit, the Communications Coupler Unit, Communication Control Unit, or NX Units.

### **General Communications**

- Refer to the user's manual for the Communications Coupler Unit for precautions for the correct use of communications with the connected Communications Coupler Unit.
- Refer to the user's manual for the Communication Control Unit for precautions for the correct use of communications with the connected Communication Control Unit.

## Regulations and Standards

#### **Conformance to EU Directives**

### **Applicable Directives**

- · EMC Directives
- · Low Voltage Directive

### Concepts

#### EMC Directives

OMRON devices that comply with EU Directives also conform to the related EMC standards so that they can be more easily built into other devices or the overall machine. The actual products have been checked for conformity to EMC standards.\*1

Whether the products conform to the standards in the system used by the customer, however, must be checked by the customer. EMC-related performance of the OMRON devices that comply with EU Directives will vary depending on the configuration, wiring, and other conditions of the equipment or control panel on which the OMRON devices are installed. The customer must, therefore, perform the final check to confirm that devices and the overall machine conform to EMC standards.

\*1. Applicable EMC (Electromagnetic Compatibility) standards are as follows: EMS (Electromagnetic Susceptibility): EN 61131-2 EMI (Electromagnetic Interference): EN 61131-2 (Radiated emission: 10-m regulations).

#### Low Voltage Directive

Always ensure that devices operating at voltages of 50 to 1,000 VAC and 75 to 1,500 VDC meet the required safety standards. The applicable directive is EN 61010-2-201.

#### Conformance to EU Directives

The NX-series Units comply with EU Directives. To ensure that the machine or device in which the NX-series Units are used complies with EU Directives, the following precautions must be observed.

- The NX-series Units must be installed within a control panel.
- You must use SELV power supply for the DC power supplies that are connected as the Unit power supplies and I/O power supplies for the NX-series Units.
  - EMC standard compliance was confirmed for the recommended Power Supplies. Refer to the user's manual for the connected CPU Unit for the recommended power supplies for the CPU Rack with an NX-series CPU Unit. Refer to the user's manual for the connected Communications Coupler Unit for the recommended power supplies for the Slave Terminal. Refer to the user's manual for the connected Communication Control Unit for the recommended power supplies for the CPU Rack with an NX-series Communication Control Unit.
- NX-series Units that comply with EU Directives also conform to the Common Emission Standard (EN 61131-2). Radiated emission characteristics (10-m regulations) may vary depending on the configuration of the control panel used, other devices connected to the control panel, wiring, and other conditions.

You must therefore confirm that the overall machine or equipment in which the NX-series Units are used complies with EU Directives.

- You must use power supplies with an output hold time of 10 ms or longer for the DC power supplies that are connected as the Unit power supplies and I/O power supplies for the NX-series Units.
- This is a Class A product (for industrial environments). In a residential environment, it may cause radio interference. If radio interference occurs, the user may be required to take appropriate measures

### Conformance to UL and CSA Standards

Some NX-series products comply with UL and CSA standards. If you use an NX-series product that complies with UL or CSA standards and the machinery or system in which you use the NX-series product must also comply with the standards, refer to the *Instruction Sheet* that is provided with the product. The *Instruction Sheet* provides the application conditions for complying with the standards.

### **Conformance to Shipbuilding Standards**

Some NX-series products comply with shipbuilding standards. If you use an NX-series product that complies with shipbuilding standards and the machinery or system in which you use the NX-series product must also comply with the standards, consult with your OMRON representative. Application conditions are defined according to the installation location. Application may not be possible for some installation locations.

For shipbuilding standard usage conditions, refer to *Conformance to Shipbuilding Standards* in the user's manual for the CPU Unit, Communications Coupler Unit, or Communication Control Unit that the NX Units are connected to.

Note that the usage conditions are provided in the relevant user's manuals for Units whose conformance to shipbuilding standards is confirmed.

#### Conformance to KC Certification

Observe the following precaution if you use NX-series Units in Korea.

A급 기기 (업무용 방송통신기자재) 이 기기는 업무용(A급) 전자파적합기기로서 판매자 또는 사용자는 이 점을 주의하시기 바라며, 가정외의 지역에서 사용하는 것을 목적으로 합니다.

Class A Device (Broadcasting Communications Device for Office Use)

This device obtained EMC registration for office use (Class A), and it is intended to be used in places other than homes.

Sellers and/or users need to take note of this.

### Software Licenses and Copyrights

This product incorporates certain third party software. The license and copyright information associated with this software is available at http://www.fa.omron.co.jp/nj\_info\_e/.

## **Unit Versions**

This section describes the notation that is used for unit versions, the confirmation method for unit versions, and the relationship between unit versions and Support Software versions.

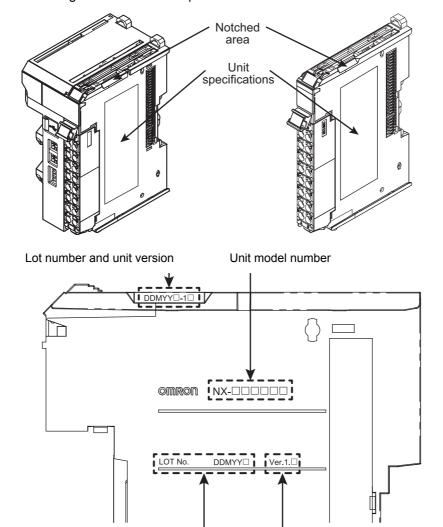
### **Unit Versions**

A "unit version" has been introduced to manage the Units in the NX Series according to differences in functionality accompanying Unit upgrades.

An example is provided below for Communications Coupler Units and NX Units. Refer to the user's manual for each Unit for details on the version notation and the method for checking version information of the CPU Units, Industrial PCs, and Communication Control Units.

### **Notation of Unit Versions on Products**

The unit version is given with the Unit specifications on the side of the Unit or in the notched area.



Lot number

Unit version

The following information is provided in the Unit specifications on the Unit.

Name	Function			
Unit model number	Gives the model of the Unit.			
Unit version	Gives the unit version of the Unit.			
Lot number	Gives the lot number of the Unit.			
	DDMYY□: Lot number, □: Used by OMRON.			
	"M" gives the month (1 to 9: January to September, X: October, Y: November, Z: December)			

The following information is provided in the notched area on the Unit.

Name	Function
Lot number and	Gives the lot number and unit version of the Unit.
unit version	• DDMYY□: Lot number, □: Used by OMRON.  "M" gives the month (1 to 9: January to September, X: October, Y: November, Z: December)
	• 1□: Unit version  The decimal portion of the unit version is omitted. (It is provided in the Unit specifications.)

### **Confirming Unit Versions with the Support Software**

If your NX Unit is connected to a CPU Unit, refer to the user's manual of the connected CPU Unit for the confirmation method for the unit version of the NX Unit.

If your NX Unit is connected to a Communications Coupler Unit, refer to the user's manual of the connected Communications Coupler Unit for the confirmation method for the unit version of the Communications Coupler Unit and NX Unit.

If your NX Unit is connected to a Communication Control Unit, refer to the user's manual of the connected Communication Control Unit for the confirmation method for the unit version of the NX Unit.

## **Unit Versions and Support Software Versions**

The functions that are supported depend on the unit version of the Unit. The version of Support Software that supports the functions that were added for an upgrade is required to use those functions.

Depending on the Unit to which the NX Unit is connected, refer to the following appendices for the functions that are supported by each unit version.

- A-7 Version Information with CPU Units on page A-164
- A-8 Version Information with Communications Coupler Units on page A-166
- A-9 Version Information with Communication Control Units on page A-170

# **Related Manuals**

The following table shows related manuals. Use these manuals for reference.

Manual name	Cat. No.	Model numbers	Application	Description
NX-series Digital I/O	W521	NX-ID	Learning how to	The hardware, setup methods, and
Units User's Manual		NX-IA□□□□	use NX-series Dig-	functions of the NX-series Digital I/O
		NX-OC □ □ □	ital I/O Units	Units are described.
		NX-OD		
		NX-MD		
NX-series Data Reference Manual	W525	NX-00000	Referencing lists of the data that is required to config- ure systems with NX-series Units	Lists of the power consumptions, weights, and other NX Unit data that is required to configure systems with NX-series Units are provided.
NX-series System Units	W523	NX-PD1□□□	Learning how to	The hardware and functions of the
User's Manual		NX-PF0□□□	use NX-series	NX-series System Units are described.
		NX-PC0□□□	System Units	
		NX-TBX01		
Sysmac Studio Version 1 Operation Manual	W504	SYSMAC- SE2□□□	Learning about the operating procedures and functions of the Sysmac Studio	Describes the operating procedures of the Sysmac Studio.
NX-IO Configurator	W585	CXONE-	Learning about the	Describes the operating procedures of
Operation Manual		AL□□D-V4	operating procedures and functions of the NX-IO Configurator.	the NX-IO Configurator.
NJ/NX-series Trouble-	W503	NX701-□□□□	Learning about the	Concepts on managing errors that may
shooting Manual		NJ501-□□□□	errors that may be	be detected in an NJ/NX-series Con-
		NJ301-□□□□	detected in an NJ/NX-series Con-	troller and information on individual
		NJ101-□□□□	troller	errors are described.
		NX102-□□□□		
		NX1P2-□□□□		
NY-series	W564	NY532-□□□□	Learning about the	Concepts on managing errors that may
Troubleshooting Manual		NY512-□□□□	errors that may be detected in an NY-series Indus- trial PC	be detected in an NY-series Controller and information on individual errors are described.
NX-series EtherCAT® Coupler Unit User's Manual	W519	NX-ECC20□	Learning how to use an NX-series EtherCAT Coupler Unit and Ether- CAT Slave Termi- nals	The following items are described: the overall system and configuration methods of an EtherCAT Slave Terminal (which consists of an NX-series EtherCAT Coupler Unit and NX Units), and information on hardware, setup, and functions to set up, control, and monitor NX Units through EtherCAT.

Manual name	Cat. No.	Model numbers	Application	Description
NX-series Ether- Net/IP <sup>TM</sup> Coupler Unit User's Manual	W536	NX-EIC202	Learning how to use an NX-series EtherNet/IP Cou- pler Unit and Eth- erNet/IP Slave Terminals	The following items are described: the overall system and configuration methods of an EtherNet/IP Slave Terminal (which consists of an NX-series EtherNet/IP Coupler Unit and NX Units), and information on hardware, setup, and functions to set up, control, and monitor NX Units.
NX-series CPU Unit Hardware User's Manual	W535	NX701-□□□□	Learning the basic specifications of the NX-series NX701 CPU Units, including introductory information, designing, installation, and maintenance.  Mainly hardware information is provided.	An introduction to the entire NX701 CPU Unit system is provided along with the following information on the CPU Unit.  • Features and system configuration  • Overview  • Part names and functions  • General specifications  • Installation and wiring  • Maintenance and Inspection
NX-series NX102 CPU Unit Hardware User's Manual	W593	NX102-□□□□	Learning the basic specifications of the NX-series NX102 CPU Units, including introductory information, designing, installation, and maintenance. Mainly hardware information is provided.	An introduction to the entire NX102 CPU Unit system is provided along with the following information on the CPU Unit.  • Features and system configuration  • Overview  • Part names and functions  • General specifications  • Installation and wiring  • Maintenance and inspection
NX-series NX1P2 CPU Unit Hardware User's Manual	W578	NX1P2-□□□	Learning the basic specifications of the NX-series NX1P2 CPU Units, including introductory information, designing, installation, and maintenance. Mainly hardware information is provided.	An introduction to the entire NX1P2 CPU Unit system is provided along with the following information on the CPU Unit.  • Features and system configuration  • Overview  • Part names and functions  • General specifications  • Installation and wiring  • Maintenance and Inspection
NJ-series CPU Unit Hardware User's Man- ual	W500	NJ501-□□□□ NJ301-□□□□ NJ101-□□□□	Learning the basic specifications of the NJ-series CPU Units, including introductory information, designing, installation, and maintenance.  Mainly hardware information is provided.	An introduction to the entire NJ-series system is provided along with the following information on the CPU Unit.  • Features and system configuration  • Overview  • Part names and functions  • General specifications  • Installation and wiring  • Maintenance and Inspection

Manual name	Cat. No.	Model numbers	Application	Description
NY-series IPC Machine Controller Industrial	W557	NY532-□□□□	Learning the basic specifications of	An introduction to the entire NY-series system is provided along with the fol-
Panel PC Hardware			the NY-series	lowing information on the Industrial
User's Manual			Industrial Panel	Panel PC.
			PCs, including	Features and system configuration
			introductory infor-	Introduction
			mation, designing, installation, and	Part names and functions
			maintenance.	General specifications
			Mainly hardware	Installation and wiring
			information is pro-	Maintenance and inspection
NN/ : 150.14 1:	14/550	10/5/0 0000	vided.	·
NY-series IPC Machine Controller Industrial Box	W556	NY512-□□□□	Learning the basic specifications of	An introduction to the entire NY-series
PC Hardware User's			the NY-series	system is provided along with the following information on the Industrial Box
Manual			Industrial Box PCs,	PC.
			including introduc-	Features and system configuration
			tory information,	• Introduction
			designing, installa-	Part names and functions
			tion, and mainte- nance. Mainly	General specifications
			hardware informa-	Installation and wiring
			tion is provided.	-
NJ/NX-series CPU Unit	W501	NX701-□□□□	Learning how to	Maintenance and inspection     The following information is provided
Software User's Manual	VV301	NJ501-□□□□	program and set	on an NJ/NX-series CPU Unit.
		NJ301-□□□□	up an	CPU Unit operation
			NJ/NX-series CPU	CPU Unit features
		NJ101-□□□□	Unit.	Initial settings
		NX102-□□□□	Mainly software	Programming based on IEC 61131-3
		NX1P2-□□□□	information is pro- vided.	language specifications
NY-series IPC Machine	W558	NY532-□□□□	Learning how to	The following information is provided
Controller Industrial		NY512-□□□□	program and set	on NY-series Machine Automation Con-
Panel PC / Industrial Box PC Software User's			up the Controller functions of an	trol Software.
Manual			NY-series Indus-	Controller operation
			trial PC	Controller features
				Controller settings
				• Programming based on IEC 61131-3 language specifications
NJ/NX-series Instruc-	W502	NX701-□□□□	Learning detailed	The instructions in the instruction set
tions Reference Manual		NJ501-□□□□	specifications on	(IEC 61131-3 specifications) are
		NJ301-□□□□	the basic instruc- tions of an	described.
		NJ101-□□□□	NJ/NX-series CPU	
		NX102-□□□□	Unit	
		NX1P2-□□□□		
NY-series Instructions	W560	NY532-□□□□	Learning detailed	The instructions in the instruction set
Reference Manual		NY512-□□□□	specifications on	(IEC 61131-3 specifications) are
			the basic instruc- tions of an	described.
			NY-series Indus-	
			trial PC	
	<u> </u>	l .		<u> </u>

Manual name	Cat. No.	Model numbers	Application	Description
NX-series Safety Control Unit / Communication Control Unit User's Manual	Z395	NX-SL5□□□  NX-SI□□□□  NX-SO□□□□  NX-CSG□□□	Learning how to use the NX-series Safety Control Units and Communication Control Units.	Describes the hardware, setup methods, and functions of the NX-series Safety Control Units and Communication Control Units.

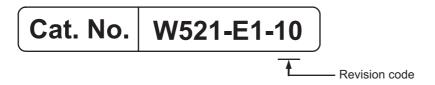
# **Terminology**

Term	Abbre- viation	Description
application layer status, AL status		Status for indicating information on errors that occur in an application on a slave.
CAN application protocol over Ether- CAT	CoE	A CAN application protocol service implemented on EtherCAT.
CAN in Automation	CiA	CiA is the international users' and manufacturers' group that develops and supports higher-layer protocols.
Communication Control Unit		An interface unit for CIP Safety communications between a Safety CPU Unit and a CIP Safety on EtherNet/IP device on a network.
Communications Coupler Units		The generic name of an interface unit for remote I/O communications on a network between NX Units and a host network master.
CPU Rack		A Rack to which a CPU Unit or Communication Control Unit is mounted. For NX-series CPU Units to which NX Units can be connected, a CPU Rack has a CPU Unit with NX Units and an End Cover mounted to it. For NX-series Communication Control Units, a CPU Rack has a Communication Control Unit with NX Units and an End Cover mounted to it.
DC time		In a CPU Rack of a NX-series CPU Unit to which NX Units can be connected, time indicated by the clock shared between the CPU Unit and the NX Units. EtherCAT slaves that support distributed clock synchronization have a clock that is shared by all slaves in the network. The time that is based on this distributed clock is called the DC time. The same clock is shared by a CPU Unit, NX Units connected to the CPU Unit, and applicable EtherCAT slaves.
device profile		A collection of device dependent information and functionality providing consistency between similar devices of the same device type.
device variable		A variable that is used to access a specific device through an I/O port by an NJ/NX-series CPU Unit or NY-series Industrial PC. Process data on an EtherCAT slave is allocated to this variable. For NX-series CPU Units to which NX Units can be connected, I/O data for the NX Units on a CPU Unit is allocated. A user application on a CPU Unit or Industrial PC accesses a device that can be connected, by directly reading and writing this device variable.
distributed clock	DC	Clock distribution mechanism used to synchronize EtherCAT slaves and the EtherCAT master.
EtherCAT slave controller	ESC	A controller for EtherCAT slave communications.
EtherCAT slave information	ESI	An XML file that contains setting information for an EtherCAT slave.
EtherCAT state machine	ESM	An EtherCAT communications state machine.
EtherCAT Technology Group	ETG	The ETG is a global organization in which OEM, end users, and technology providers join forces to support and promote the further technology development.
I/O map settings		Settings that assign variables to I/O ports. Assignment information between I/O ports and variables.
I/O port		A logical interface that is used by the NJ/NX-series CPU Unit or NY-series Industrial PC to exchange data with an external device (slave or Unit).
I/O refreshing		Cyclic data exchange with external devices that is performed with predetermined memory addresses.
index		Address of an object within an application process.
network configuration information		The EtherCAT network configuration information held by the EtherCAT master.
NX bus		The NX-series internal bus.

Object	Term	Abbre- viation	Description
Object dictionary	object		
Cation objects and application objects			-
A state in which I/O refresh communications and NX message communications are possible between the communications master and the Communications Coupler Unit or NX Units.	object dictionary	OD	The state of the s
cations are possible between the communications master and the Communications Coupler Unit or NX Units.  PDO communications			
munications Coupler Unit or NX Units.  PDO communications	Operational		
PDO communications Pre-Operational			
Pre-Operational  A state in which NX message communications are possible between the communications master and the Communications are not possible.  Primary periodic task  The task with the highest priority.  Process data  Collection of application objects designated to be downloaded cyclically or acyclically for the purpose of measurement and control.  Process data communications  Process data object  Process data object received by an EtherCAT slave.  A state in which input refresh communications and NX message communications are possible between the communications master and the Communications are possible between the communications master and the Communications are not possible.  Safety Network Controller  A building-block Safety Controller, which consists of a Communication Control Unit connected with Safety Control Units.  Solo communications  Process data object  Solo et transmit information wherever required.  Solo communications where all objects in the object dictionary can be read and written.  Slave Information Interface  Sil Slave Information that is stored in non-volatile memory in the slave.  Slave Terminal  Process data object within the object dictionary.  A building-block remote I/O terminal, which consists of a Communication Coupler Unit connected with NX Units.  Sub-address of an object within the object dictionary.  Process data object objects.  Process data object objects.  Process data object objects.  Process data object objects.  Process data object objects and the communication object objects.  Process data object objects.  Process data object objects objects objects.	PDO communications		
communications master and the Communications Coupler Unit or NX Units, but I/O refresh communications are not possible.  primary periodic task The task with the highest priority.  process data Collection of application objects designated to be downloaded cyclically or acyclically for the purpose of measurement and control.  process data communications One type of EtherCAT communications in which process data objects (PDOs) are used to exchange information cyclically and in realtime. This is also called PDO communications.  process data object PDO A structure that describes the mappings of parameters that have one or more process data objects entitles.  receive PDO RxPDO A process data object received by an EtherCAT slave.  Safe-Operational A state in which input refresh communications and NX message communications are possible between the communications master and the Communications Coupler Unit or NX Units, but output refresh communications are possible.  Safety Network Controller A building-block Safety Controller, which consists of a Communication Control Unit connected with Safety Control Units.  SDO communications One type of EtherCAT communications in which service data objects (SDOs) are used to transmit information whenever required.  service data object  SDO CoE asynchronous mailbox communications where all objects in the object dictionary can be read and written.  Slave Information Interface SII Slave information that is stored in non-volatile memory in the slave.  Slave Terminal A building-block remote I/O terminal, which consists of a Communication Coupler Unit connected with NX Units.  subindex Sub-address of an object within the object dictionary.  Sync0 A signal that gives the interrupt timing based on the distributed clock (DC) in EtherCAT communications. The slaves execute controls according to this interrupt timing.  Sync Manager  SM Collection of control elements to coordinate access to concurrently used objects.			
Units, but I/O refresh communications are not possible.	i re-operational		* · · · · · · · · · · · · · · · · · · ·
primary periodic task The task with the highest priority.  process data Collection of application objects designated to be downloaded cyclically or acyclically for the purpose of measurement and control.  Process data communications One type of EtherCAT communications in which process data objects (PDOs) are used to exchange information cyclically and in realtime. This is also called PDO communications.  PDO A structure that describes the mappings of parameters that have one or more process data entities.  PDO A process data object received by an EtherCAT slave.  Safe-Operational A state in which input refresh communications and NX message communications are possible between the communications master and the Communications Coupler Unit or NX Units, but output refresh communications are not possible.  Safety Network Controller A building-block Safety Controller, which consists of a Communication Control Unit connected with Safety Control Units.  SDO communications One type of EtherCAT communications in which service data objects (SDOs) are used to transmit information whenever required.  Service data object SDO CoE asynchronous mailbox communications where all objects in the object dictionary can be read and written.  Slave Information Interface A building-block remote I/O terminal, which consists of a Communication Coupler Unit connected with NX Units.  Slave Terminal A building-block remote I/O terminal, which consists of a Communication Coupler Unit connected with NX Units.  Sub-address of an object within the object dictionary.  Synco A signal that gives the interrupt timing based on the distributed clock (DC) in EtherCAT communications. The slaves execute controls according to this interrupt timing.  Sync Manager SM Collection of control elements to coordinate access to concurrently used objects.  The interval at which the primary periodic task or a periodic task is executed.			•
process data	primary periodic task		·
process data communications			
(PDOs) are used to exchange information cyclically and in realtime. This is also called PDO communications.  process data object  PDO  A structure that describes the mappings of parameters that have one or more process data entities.  receive PDO  RxPDO  A process data object received by an EtherCAT slave.  Safe-Operational   A state in which input refresh communications and NX message communications are possible between the communications master and the Communications Coupler Unit or NX Units, but output refresh communications are not possible.  Safety Network Controller  A building-block Safety Controller, which consists of a Communication Control Unit connected with Safety Control Units.  SDO communications   One type of EtherCAT communications in which service data objects (SDOs) are used to transmit information whenever required.  SERVICE SERVIC	•		
is also called PDO communications.  process data object  PDO  A structure that describes the mappings of parameters that have one or more process data entities.  RxPDO  A process data entities.  Safe-Operational   A state in which input refresh communications and NX message communications are possible between the communications master and the Communications are possible between the communications master and the Communications are not possible.  Safety Network Controller  A building-block Safety Controller, which consists of a Communication Control Unit connected with Safety Control Units.  SDO communications   One type of EtherCAT communications in which service data objects (SDOs) are used to transmit information whenever required.  service data object  SDO  CoE asynchronous mailbox communications where all objects in the object dictionary can be read and written.  Slave Information Interface  SII  Slave information that is stored in non-volatile memory in the slave.  A building-block remote I/O terminal, which consists of a Communication Coupler Unit connected with NX Units.  subindex   A signal that gives the interrupt timing based on the distributed clock (DC) in EtherCAT communications. The slaves execute controls according to this interrupt timing.  Sync Manager  SM  Collection of control elements to coordinate access to concurrently used objects.  The interval at which the primary periodic task or a periodic task is executed.	process data communications		One type of EtherCAT communications in which process data objects
process data object PDO RxPDO A process data entities.  receive PDO RxPDO A process data object received by an EtherCAT slave.  Safe-Operational			(PDOs) are used to exchange information cyclically and in realtime. This
more process data entities.  receive PDO RXPDO A process data object received by an EtherCAT slave.  Safe-Operational			
RxPDO	process data object	PDO	
Safe-Operational  A state in which input refresh communications and NX message communications are possible between the communications master and the Communications Coupler Unit or NX Units, but output refresh communications are not possible.  Safety Network Controller  A building-block Safety Controller, which consists of a Communication Control Unit connected with Safety Control Units.  SDO communications  One type of EtherCAT communications in which service data objects (SDOs) are used to transmit information whenever required.  service data object  SDO CoE asynchronous mailbox communications where all objects in the object dictionary can be read and written.  Slave Information Interface  SII Slave information that is stored in non-volatile memory in the slave.  Slave Terminal  A building-block remote I/O terminal, which consists of a Communication Coupler Unit connected with NX Units.  subindex  Sub-address of an object within the object dictionary.  Sync0  A signal that gives the interrupt timing based on the distributed clock (DC) in EtherCAT communications. The slaves execute controls according to this interrupt timing.  Sync Manager  SM Collection of control elements to coordinate access to concurrently used objects.  The interval at which the primary periodic task or a periodic task is executed.			
nications are possible between the communications master and the Communications Coupler Unit or NX Units, but output refresh communications are not possible.  Safety Network Controller  A building-block Safety Controller, which consists of a Communication Control Unit connected with Safety Control Units.  SDO communications   One type of EtherCAT communications in which service data objects (SDOs) are used to transmit information whenever required.  service data object  SDO  CoE asynchronous mailbox communications where all objects in the object dictionary can be read and written.  Slave Information Interface  SII  Slave information that is stored in non-volatile memory in the slave.  Slave Terminal   A building-block remote I/O terminal, which consists of a Communication Coupler Unit connected with NX Units.  subindex   Sub-address of an object within the object dictionary.  Sync0   A signal that gives the interrupt timing based on the distributed clock (DC) in EtherCAT communications. The slaves execute controls according to this interrupt timing.  Sync Manager  SM  Collection of control elements to coordinate access to concurrently used objects.  The interval at which the primary periodic task or a periodic task is executed.			
Communications Coupler Unit or NX Units, but output refresh communications are not possible.  Safety Network Controller  A building-block Safety Controller, which consists of a Communication Control Unit connected with Safety Control Units.  SDO communications   One type of EtherCAT communications in which service data objects (SDOs) are used to transmit information whenever required.  service data object  SDO  CoE asynchronous mailbox communications where all objects in the object dictionary can be read and written.  Slave Information Interface  SII  Slave information that is stored in non-volatile memory in the slave.  Slave Terminal   A building-block remote I/O terminal, which consists of a Communication Coupler Unit connected with NX Units.  subindex   Sub-address of an object within the object dictionary.  Sync0   A signal that gives the interrupt timing based on the distributed clock (DC) in EtherCAT communications. The slaves execute controls according to this interrupt timing.  Sync Manager  SM  Collection of control elements to coordinate access to concurrently used objects.  The interval at which the primary periodic task or a periodic task is executed.	Safe-Operational		,
Safety Network Controller  A building-block Safety Controller, which consists of a Communication Control Unit connected with Safety Control Units.  SDO communications  One type of EtherCAT communications in which service data objects (SDOs) are used to transmit information whenever required.  service data object  SDO CoE asynchronous mailbox communications where all objects in the object dictionary can be read and written.  Slave Information Interface  SII Slave information that is stored in non-volatile memory in the slave.  Slave Terminal  A building-block remote I/O terminal, which consists of a Communication Coupler Unit connected with NX Units.  subindex  Sub-address of an object within the object dictionary.  Sync0  A signal that gives the interrupt timing based on the distributed clock (DC) in EtherCAT communications. The slaves execute controls according to this interrupt timing.  Sync Manager  SM Collection of control elements to coordinate access to concurrently used objects.  The interval at which the primary periodic task or a periodic task is executed.			
Safety Network Controller  A building-block Safety Controller, which consists of a Communication Control Unit connected with Safety Control Units.  SDO communications  One type of EtherCAT communications in which service data objects (SDOs) are used to transmit information whenever required.  service data object  SDO CoE asynchronous mailbox communications where all objects in the object dictionary can be read and written.  Slave Information Interface  SII Slave information that is stored in non-volatile memory in the slave.  Slave Terminal  A building-block remote I/O terminal, which consists of a Communication Coupler Unit connected with NX Units.  subindex  Sub-address of an object within the object dictionary.  Sync0  A signal that gives the interrupt timing based on the distributed clock (DC) in EtherCAT communications. The slaves execute controls according to this interrupt timing.  Sync Manager  SM Collection of control elements to coordinate access to concurrently used objects.  The interval at which the primary periodic task or a periodic task is executed.			
Control Unit connected with Safety Control Units.  SDO communications  One type of EtherCAT communications in which service data objects (SDOs) are used to transmit information whenever required.  service data object  SDO CoE asynchronous mailbox communications where all objects in the object dictionary can be read and written.  Slave Information Interface  SII Slave information that is stored in non-volatile memory in the slave.  A building-block remote I/O terminal, which consists of a Communication Coupler Unit connected with NX Units.  subindex  Sub-address of an object within the object dictionary.  Sync0  A signal that gives the interrupt timing based on the distributed clock (DC) in EtherCAT communications. The slaves execute controls according to this interrupt timing.  Sync Manager  SM Collection of control elements to coordinate access to concurrently used objects.  The interval at which the primary periodic task or a periodic task is executed.	Safety Network Controller		·
SDO communications  One type of EtherCAT communications in which service data objects (SDOs) are used to transmit information whenever required.  service data object  SDO CoE asynchronous mailbox communications where all objects in the object dictionary can be read and written.  Slave Information Interface  SII Slave information that is stored in non-volatile memory in the slave.  A building-block remote I/O terminal, which consists of a Communication Coupler Unit connected with NX Units.  subindex  Sub-address of an object within the object dictionary.  Sync0  A signal that gives the interrupt timing based on the distributed clock (DC) in EtherCAT communications. The slaves execute controls according to this interrupt timing.  Sync Manager  SM Collection of control elements to coordinate access to concurrently used objects.  The interval at which the primary periodic task or a periodic task is executed.			· · · · · · · · · · · · · · · · · · ·
(SDOs) are used to transmit information whenever required.  service data object  SDO  CoE asynchronous mailbox communications where all objects in the object dictionary can be read and written.  Slave Information Interface  SII  Slave information that is stored in non-volatile memory in the slave.  Slave Terminal   A building-block remote I/O terminal, which consists of a Communication Coupler Unit connected with NX Units.  subindex   Sub-address of an object within the object dictionary.  Sync0   A signal that gives the interrupt timing based on the distributed clock (DC) in EtherCAT communications. The slaves execute controls according to this interrupt timing.  Sync Manager  SM  Collection of control elements to coordinate access to concurrently used objects.  task period   The interval at which the primary periodic task or a periodic task is executed.	SDO communications		-
object dictionary can be read and written.  Slave Information Interface  SII  Slave information that is stored in non-volatile memory in the slave.  Slave Terminal   A building-block remote I/O terminal, which consists of a Communication Coupler Unit connected with NX Units.  subindex   Sub-address of an object within the object dictionary.  Sync0   A signal that gives the interrupt timing based on the distributed clock (DC) in EtherCAT communications. The slaves execute controls according to this interrupt timing.  Sync Manager  SM  Collection of control elements to coordinate access to concurrently used objects.  task period   The interval at which the primary periodic task or a periodic task is executed.			-
Slave Information Interface  SII Slave information that is stored in non-volatile memory in the slave.  Slave Terminal A building-block remote I/O terminal, which consists of a Communication Coupler Unit connected with NX Units.  subindex Sub-address of an object within the object dictionary.  Sync0 A signal that gives the interrupt timing based on the distributed clock (DC) in EtherCAT communications. The slaves execute controls according to this interrupt timing.  Sync Manager SM Collection of control elements to coordinate access to concurrently used objects.  task period The interval at which the primary periodic task or a periodic task is executed.	service data object	SDO	CoE asynchronous mailbox communications where all objects in the
Slave Terminal  A building-block remote I/O terminal, which consists of a Communication Coupler Unit connected with NX Units.  subindex  Sub-address of an object within the object dictionary.  Sync0  A signal that gives the interrupt timing based on the distributed clock (DC) in EtherCAT communications. The slaves execute controls according to this interrupt timing.  Sync Manager  SM Collection of control elements to coordinate access to concurrently used objects.  task period  The interval at which the primary periodic task or a periodic task is executed.			object dictionary can be read and written.
Coupler Unit connected with NX Units.  Sub-address of an object within the object dictionary.  Sync0 A signal that gives the interrupt timing based on the distributed clock (DC) in EtherCAT communications. The slaves execute controls according to this interrupt timing.  Sync Manager SM Collection of control elements to coordinate access to concurrently used objects.  task period The interval at which the primary periodic task or a periodic task is executed.		SII	·
subindex        Sub-address of an object within the object dictionary.         Sync0        A signal that gives the interrupt timing based on the distributed clock (DC) in EtherCAT communications. The slaves execute controls according to this interrupt timing.         Sync Manager       SM       Collection of control elements to coordinate access to concurrently used objects.         task period        The interval at which the primary periodic task or a periodic task is executed.	Slave Terminal		T =
Sync0 A signal that gives the interrupt timing based on the distributed clock (DC) in EtherCAT communications. The slaves execute controls according to this interrupt timing.  Sync Manager SM Collection of control elements to coordinate access to concurrently used objects.  task period The interval at which the primary periodic task or a periodic task is executed.			-
(DC) in EtherCAT communications. The slaves execute controls according to this interrupt timing.  Sync Manager  SM  Collection of control elements to coordinate access to concurrently used objects.  The interval at which the primary periodic task or a periodic task is executed.			
ing to this interrupt timing.  Sync Manager  SM  Collection of control elements to coordinate access to concurrently used objects.  task period  The interval at which the primary periodic task or a periodic task is executed.	Sync0		
Sync Manager  SM  Collection of control elements to coordinate access to concurrently used objects.  The interval at which the primary periodic task or a periodic task is executed.			
task period The interval at which the primary periodic task or a periodic task is executed.	Syna Managor	CM	
task period The interval at which the primary periodic task or a periodic task is executed.	Synt Manager	SIVI	-
cuted.	task period		-
	taon polica		
	transmit PDO	TxPDO	A process data object sent from an EtherCAT slave.

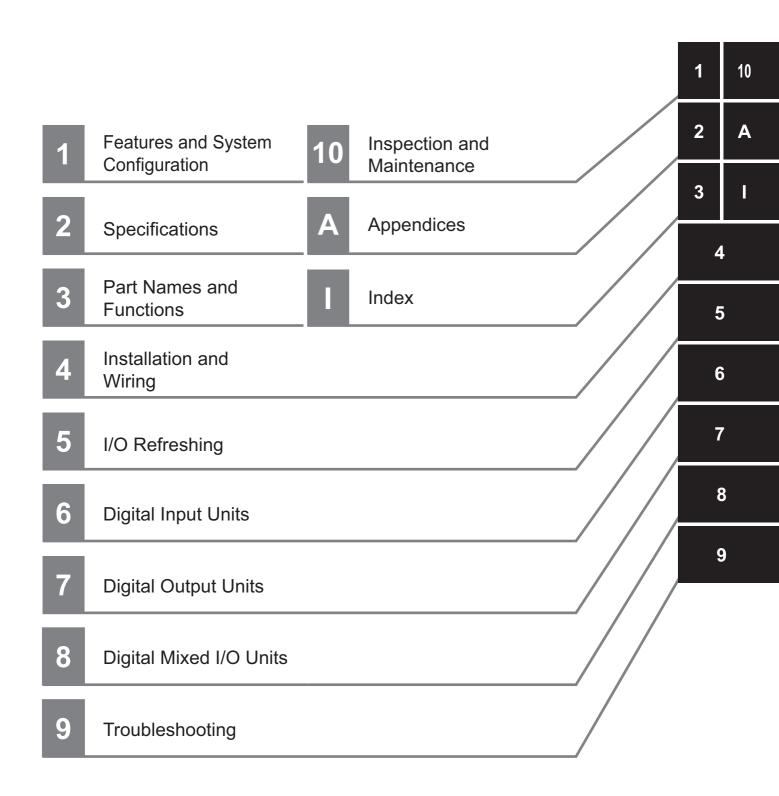
# **Revision History**

A manual revision code appears as a suffix to the catalog number on the front and back covers of the manual.



Revision code	Date	Revised content
01	April 2013	Original production
02	June 2013	Added time stamp refreshing, models on time stamp refreshing and corrected mistakes.
03	September 2013	Added information on the NX-IA3117/OC2733 and corrected mistakes.
04	July 2014	Added information on the NX-ID5142-5/ID6142-5/OD5121-5/OD5256-5/OD6121-5/OD6256-5/MD 6121-5/MD6256-5 and corrected mistakes.
05	April 2015	Added information on the     NX-ID5142-1/ID6142-6/OD3268/OD5121-1/OD5256-1/OD6121-6/MD     6121-6.
		<ul><li>Made changes accompanying the addition of the NX-series CPU Unit.</li><li>Corrected mistakes.</li></ul>
06	October 2016	Made changes accompanying the addition of NX-OC4633.
		Made changes to add NY-series IPC Machine Controller Industrial Panel PCs and Industrial Box PCs.
		Made changes accompanying the addition of the NX-series NX1P2     CPU Unit.
		Corrected mistakes.
07	June 2017	Made changes accompanying the upgrade of the NX-ECC203 unit version to version 1.5.
		Made changes accompanying the upgrade of the NX-EIC202 unit version to version 1.2.
		Corrected mistakes.
08	April 2018	Made changes accompanying the addition of the NX-series NX102 CPU Unit.
		Corrected mistakes.
09	July 2018	Made changes accompanying the addition of the NX-series Communication Control Unit.
10	October 2018	Made revisions accompanying the appearance change of the indicators.

### **Sections in this Manual**



Sections in this Manual



# Features and System Configuration

This section describes NX system configuration and the types of Digital I/O Units.

1-1	Featur	res and Types of Digital I/O Units	1-2
	1-1-1	Digital I/O Unit Features	1-2
	1-1-2	Digital I/O Unit Types	1-4
1-2	Syster	m Configuration	1-5
	1-2-1	System Configuration in the Case of a CPU Unit	1-5
	1-2-2	System Configuration of Slave Terminals	1-6
	1-2-3	System Configuration in the Case of a Communication Control Unit	1-9
1-3	Model	List 1	I-11
	1-3-1	Model Notation	1-11
	1-3-2	Digital Input Units	1-14
	1-3-3	Digital Output Units	1-16
	1-3-4	Digital Mixed I/O Units	1-19
1-4	List of	f Functions	-20
	1-4-1	Digital Input Units	1-20
	1-4-2	Digital Output Units	1-21
	1-4-3	Digital Mixed I/O Units	1-22
1-5	Suppo	ort Software	-23

# Features and Types of Digital I/O **Units**

This section describes features and types of Digital I/O Units.

#### 1-1-1 **Digital I/O Unit Features**

The Digital I/O Units are NX Units to process inputs and outputs of digital signals (ON/OFF signals). The NX-series Digital I/O Units have the following features.



#### **Additional Information**

#### **CPU Rack**

A CPU Rack is a rack to which a CPU Unit or Communication Control Unit is mounted. For NX-series CPU Units to which NX Units can be connected, a CPU Rack is configured to have a CPU Unit with NX Units and an End Cover mounted to it. For NX-series Communication Control Units, a CPU Rack has a Communication Control Unit with NX Units and an End Cover mounted to it.

#### **Slave Terminal**

Slave Terminal is a generic name for a building block-type remote I/O terminal that contains a group of NX Units connected to a Communications Coupler Unit.

#### Can Be Connected to More Than One Unit with the NX Bus

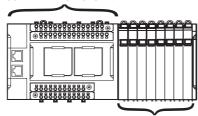
NX-series Digital I/O Units can be connected to the following Units, which each support an NX bus.\*1

- · NX-series CPU Unit
- · NX-series Communications Coupler Unit
- NX-series Communication Control Unit\*2

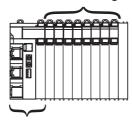
When these Units are used, you can unify the methods for installing, wiring, and setting up NX Units, and eventually reduce design costs.

#### Example:

NX-series NX1P2 CPU Unit



NX Units: e.g., NX-series Degital I/O Units



NX-series EtherCAT Coupler Unit

- \*1. For whether NX Units can be connected to the CPU Unit or Communications Coupler Unit to be used, refer to the user's manual for the CPU Unit or Communications Coupler Unit to be used.
- \*2. You cannot connect Digital I/O Units that support input refreshing with input changed time or output refreshing with specified time stamp.

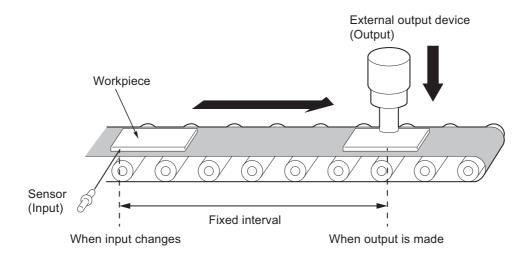
### Synchronous I/O with Refresh Cycle of the NX Bus

When the NX-series CPU Units or EtherCAT Coupler Unit is used together with NX Units that support synchronous I/O refreshing, the I/O control of multiple NX Units can be synchronized at the time to synchronize with the refresh cycle of the NX bus.

This provides an accurate I/O control because it suppresses jitter in the I/O timing of multiple NX Units.

#### **Controlling Outputs at Fixed Intervals After Inputs Change**

You can use NX-series CPU Units or EtherCAT Coupler Units with NX Units that support input refreshing with input changed time and with other NX Units that support output refreshing with specified time stamp to control the outputs at fixed intervals after the sensor inputs change.



### Simple I/O Wiring with a Screwless Clamping Terminal Block

The terminal block is a screwless clamping terminal block.

You can connect the wires simply by pushing the ferrules into the terminals. The amount of wiring work is reduced without requiring the use of screws.

#### 1-1-2 **Digital I/O Unit Types**

The types of Digital I/O Units are as follows.

Туре	Purpose
Digital Input Units	These are Units with functionality to process input of digital signals from sensors and other connected external devices.
Digital Output Units	These are Units with functionality to process output of digital signals to relays and other connected external devices.
Digital Mixed I/O Units	These are Units with functionality to process input of digital signals from connected external devices as well as functionality to process output of digital signals to connected external devices.

Refer to 1-3 Model List on page 1-11 for details on Digital I/O Unit models and 1-4 List of Functions on page 1-20 for details on their functions.

# 1-2 System Configuration

NX Unit NX-series Digital I/O Units can be connected to the following Units.

- · NX-series CPU Unit
- · NX-series Communications Coupler Unit
- · NX-series Communication Control Unit

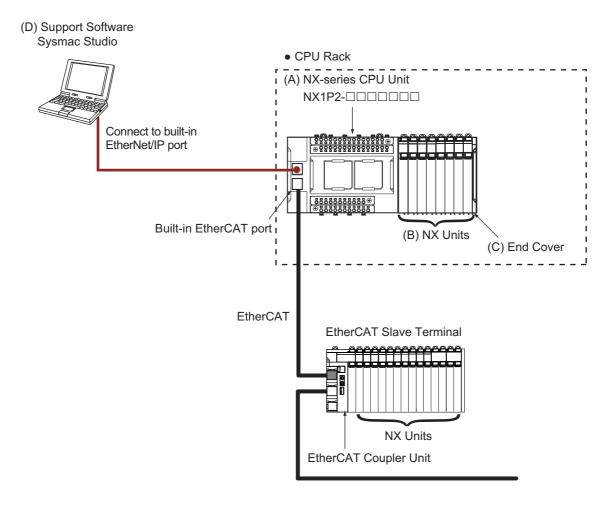
The following explains the system configuration for each NX Unit connection destination.

### 1-2-1 System Configuration in the Case of a CPU Unit

The following figure shows a system configuration when a group of NX Units is connected to an NX-series NX1P2 CPU Unit.

You can connect the EtherCAT Slave Terminal to the built-in EtherCAT port on the CPU Unit. Refer to 1-2-2 System Configuration of Slave Terminals on page 1-6 for details on the system configuration of a Slave Terminal.

Refer to the user's manual for the connected CPU Unit for details on how to configure the system if the connected CPU Unit is not an NX1P2 CPU Unit.



Sym- bol	Item	Description
(A)	NX-series CPU Unit	The Unit that serves as the center of control for a Machine Automation Controller. It executes tasks, refreshes I/O for other Units and slaves, etc. NX Units can be connected to an NX1P2 CPU Unit.
(B)	NX Units <sup>*1</sup>	The NX Units perform I/O processing with connected external devices. The NX Units exchange data with the CPU Unit through I/O refreshing. A maximum of eight NX Units can be connected to an NX1P2 CPU Unit.
(C)	End Cover	The End Cover is attached to the end of a CPU Rack.
(D)	Support Software (Sysmac Studio)	A computer software application for setting, programming, debugging, and troubleshooting NJ/NX/NY-series Controllers.
		For an NX1P2 CPU Unit, this application performs setting operation by making a connection to a built-in EtherNet/IP port.

<sup>\*1.</sup> For whether an NX Unit can be connected to the CPU Unit, refer to the version information in the user's manual for the NX Unit.

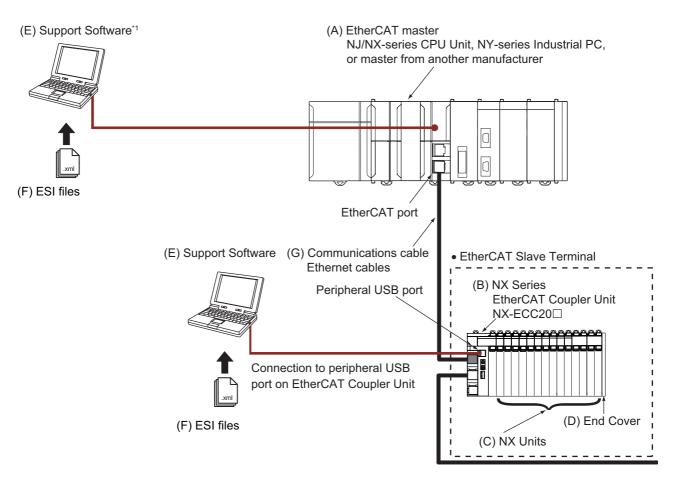
#### 1-2-2 **System Configuration of Slave Terminals**

A building-block remote I/O slave provided with a group of NX Units connected to a Communications Coupler Unit is generically called a Slave Terminal.

The NX Units can be flexibly combined with a Communications Coupler Unit to achieve the optimum remote I/O slave for the application with less wiring, less work, and less space.

The following figure shows an example of the system configuration when an EtherCAT Coupler Unit is used as a Communications Coupler Unit.

Refer to the user's manual for the connected Communications Coupler Unit for details on how to configure the system when any other type of Communications Coupler Unit is used.



\*1. The connection method for the Support Software depends on the model of the CPU Unit or Industrial PC.

Let- ter	ltem	Description
(A)	EtherCAT master *1	The EtherCAT master manages the network, monitors the status of slaves, and exchanges I/O data with slaves.
(B)	EtherCAT Coupler Unit	The EtherCAT Coupler Unit serves as an interface for process data communications on the EtherCAT network between the NX Units and the EtherCAT master.
		The I/O data for the NX Units is accumulated in the EtherCAT Coupler Unit and then all of the data is exchanged with the EtherCAT master at the same time.
		The EtherCAT Coupler Unit can also perform message communications (SDO communications) with the EtherCAT master.
(C)	NX Units*2	The NX Units perform I/O processing with connected external devices.
		The NX Units perform process data communications with the EtherCAT master through the EtherCAT Coupler Unit.
(D)	End Cover	The End Cover is attached to the end of the Slave Terminal.
(E)	Support Software*3 *4	The Support Software runs on a personal computer and it is used to configure the EtherCAT network and EtherCAT Slave Terminal, and to program, monitor, and troubleshoot the Controllers.
(F)	ESI (EtherCAT Slave Information) file	The ESI files contain information that is unique to the EtherCAT Slave Terminals in XML format. You can load an ESI file into the Support Software to easily allocate Slave Terminal process data and make other settings.
		The ESI files for OMRON EtherCAT slaves are installed in the Support Software. You can obtain the ESI files for the latest models through the Support Software's automatic update function.
(G)	Communications cable	Use a double-shielded cable with aluminum tape and braiding of Ethernet category 5 (100Base-TX) or higher, and use straight wiring.

<sup>\*1.</sup> An EtherCAT Slave Terminal cannot be connected to any of the OMRON CJ1W-NC 81/ 82 Position Control Units even though they can operate as EtherCAT masters.

<sup>\*2.</sup> For whether an NX Unit can be connected to the Communications Coupler Unit, refer to the version information in the user's manual for the NX Unit.

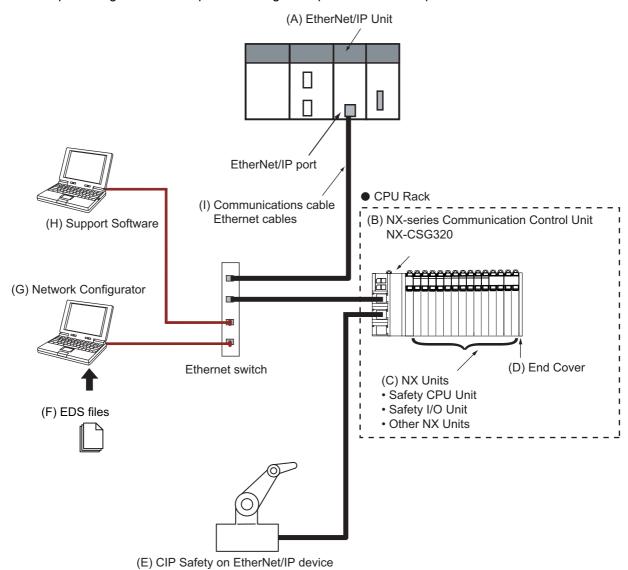
<sup>\*3.</sup> The term Support Software indicates software that is provided by OMRON. If you connect to a master from another company, use the software tool corresponding to that master.

<sup>\*4.</sup> Refer to 1-5 Support Software on page 1-23 for information on Support Software.

# 1-2-3 System Configuration in the Case of a Communication Control Unit

The following figure shows a system configuration when a group of NX Units is connected to an NX-series Communication Control Unit. To configure a Safety Network Controller, mount the Safety CPU Unit, which is one of the NX Units, to the CPU Rack of the Communication Control Unit.

You cannot connect a Communication Control Unit with Digital I/O Units that support input refreshing with input changed time or output refreshing with specified time stamp.



Let- ter	Item	Description
(A)	EtherNet/IP Unit	The EtherNet/IP Unit manages the EtherNet/IP network, monitors the status of slaves, and exchanges I/O data with the slaves.
		The types of EtherNet/IP Units are listed below.
		• CJ1W-EIP21
		Built-in EtherNet/IP port on a CPU Unit
		Refer to the user's manual for your EtherNet/IP Unit for information on the Support Software to configure the EtherNet/IP Unit.
(B)	Communication Control Unit	The Communication Control Unit has built-in EtherNet/IP ports and relays CIP Safety communications between the Safety CPU Unit and CIP Safety on EtherNet/IP devices. It also performs tag data link communications with standard controllers.
(C)	NX Units*1	Safety CPU Unit
		This Unit serves as the center of control for the Safety Network Controller. It executes safety programs and CIP Safety communications.
		Safety I/O Unit
		This Unit performs safety input or output processing.
		Other NX Units
		Digital I/O Units and other types of NX Units perform standard I/O processing.
(D)	End Cover	The End Cover is attached to the end of the CPU Rack.
(E)	CIP Safety on Ether- Net/IP device	The CIP Safety on EtherNet/IP device performs CIP Safety communications with the Safety CPU Unit.
(F)	EDS (Electronic Data	The EDS file contains information that is unique to the Communication Control
	Sheet) file	Unit. You can load EDS files into the Network Configurator or other Ether-
		Net/IP network setup software to easily allocate data and view or change settings.
(G)	Network Configurator	The software tool to configure the EtherNet/IP network.
(H)	Support Software*2	The Support Software runs on a personal computer and it is used to configure
		the CPU Rack, and to perform programming, monitoring, and troubleshooting.
(I)	Communications cable	Use an STP (shielded twisted-pair) cable of category 5 or higher. You can use
		either a straight or cross cable.

<sup>\*1.</sup> For whether an NX Unit can be connected to the Communication Control Unit, refer to the version information in the user's manual for the NX Unit.

<sup>\*2.</sup> Refer to 1-5 Support Software on page 1-23 for information on Support Software.

# 1-3 Model List

### 1-3-1 Model Notation

The Digital I/O Unit models are assigned based on the following rules.

N	IX - □□		]	
Unit type  ID: DC input IA: AC input OD: Transistor output OC: Relay output MD: DC input/Transistor output				
Number of points 2:2 points 3:4 points 4:8 points 5:16 points 6:32 points, or 16 points each for input	ts and outputs			
1/0 6 10 0				

Number	Inputs	Outputs	Mixed I/O (Input, Output)
1	For both NPN/PNP	NPN	For both NPN/PNP, NPN
2	_	PNP	For both NPN/PNP, PNP
3	NPN	_	_
4	PNP	-	_
6	_	N.O.	_
7	_	N.O. + N.C.	_

Other specifications -

Refer to Other specifications on the next page.

External connection terminals

Number	External connection terminals				
None	Screwless clamping terminal block				
-1	M3 screw terminal block				
-5	MIL connector				
-6	Fujitsu connector				

### Other Specifications

#### Digital Input Units

	Input voltage	ON/OFF response time		I/O refreshing method		
Num ber		Exceeds 1 µs	1 μs max.	Free-Run refreshing *1 only or Switching Synchronous I/O refreshing *2 and Free-Run refreshing	Input refreshing with input changed time only	
17	12 to 24 VDC or 240 VAC	Yes		Yes		
42		Yes		Yes		
43	24 VDC		Yes	Yes		
44			Yes		Yes	

<sup>\*1.</sup> Free-Run refreshing

#### Digital Output Units

		Load cur- rent	ON/OFF response time		I/O refreshing method		Other func- tions
Num ber	Rated volt- age		Exceed s 1 µs	1 μs max.	Free-Run refreshing *1 only or Switching Synchronous I/O refreshing *2 and Free-Run refreshing	Output refresh- ing with speci- fied time stamp only	Load short-circuit protection
21	12 to 24 VDC	0.5 A	Yes		Yes		
33	or 240 VAC	2 A	Yes		Yes		
53				Yes	Yes		
54				Yes		Yes	
56	24 VDC	0.5 A	Yes		Yes		Yes
57	24 100			Yes	Yes		Yes
58				Yes		Yes	Yes
68		2 A	Yes		Yes		Yes

<sup>\*1.</sup> Free-Run refreshing

<sup>\*2.</sup> Synchronous I/O refreshing

<sup>\*2.</sup> Synchronous I/O refreshing

#### Digital Mixed I/O Units

Num ber	Input section		Output section						
	Rated input voltage	Rated	Load	ON/OFF response time		I/O refreshing	Other func- tions		
		volt- age	current	Exceeds 1 µs	1 μs max.	method	Load short-circuit protection		
21	24 VDC	12 to 24 VDC	0.5 A	Yes		Switching Synchro- nous I/O refresh- ing and Free-Run	Yes		
56		24 VDC		Yes		refreshing			

Refer to Section 5 I/O Refreshing for details on the I/O refreshing method.

#### 1-3-2 **Digital Input Units**

This section shows the specifications for Digital Input Units.

Refer to A-1-2 Digital Input Units on page A-8 for details on the specifications of individual Digital Input Units.

### DC Input Units (Screwless Clamping Terminal Block, 12 mm Width)

Model	Num ber of poin ts	Internal I/O common	Rated input voltage	I/O refreshing method	ON/OFF response time	Reference
NX-ID3317			12 to 24 VDC	Switching Synchro- nous I/O refreshing	20 μs max./400 μs max.	P. A-10
NX-ID3343		NPN		and Free-Run refreshing	100 ns max./100 ns	P. A-12
NX-ID3344	4 point		24 VDC	Input refreshing with input changed time only	max.	P. A-14
NX-ID3417	S		12 to 24 VDC	Switching Synchro- nous I/O refreshing	20 μs max./400 μs max.	P. A-16
NX-ID3443		PNP		and Free-Run refreshing	100 ns max /100 ns	P. A-18
NX-ID3444				Input refreshing with input changed time only	max.	P. A-20
NX-ID4342	8	NPN	24 VDC			P. A-22
NX-ID4442	point s	PNP		Switching Synchro- nous I/O refreshing	20 μs max./400 μs	P. A-24
NX-ID5342	16	NPN	and Free-Run		max.	P. A-26
NX-ID5442	point s	PNP		refreshing		P. A-28

### DC Input Units (M3 Screw Terminal Block, 30 mm Width)

Model	Num ber of poin ts	Internal I/O common	Rated input voltage	I/O refreshing method	ON/OFF response time	Reference
NX-ID5142-1	16 point s	For both NPN/PNP	24 VDC	Switching Synchro- nous I/O refreshing and Free-Run refreshing	20 μs max./400 μs max.	P. A-30

### DC Input Units (MIL Connector, 30 mm Width)

Model	Num ber of poin ts	Internal I/O common	Rated input voltage	I/O refreshing method	ON/OFF response time	Reference
NX-ID5142-5	16 point s	For both NPN/PNP	24 VDC	Switching Synchro- nous I/O refreshing	20 µs max./400 µs	P. A-32
NX-ID6142-5	32 point s	For both NPN/PNP	24 VDC	and Free-Run refreshing	max.	P. A-34

### DC Input Units (Fujitsu Connector, 30 mm Width)

Model	Num ber of poin ts	Internal I/O common	Rated input voltage	I/O refreshing method	ON/OFF response time	Reference
NX-ID6142-6	32 point s	For both NPN/PNP	24 VDC	Switching Synchro- nous I/O refreshing and Free-Run refreshing	20 μs max./400 μs max.	P. A-37

### AC Input Units (Screwless Clamping Terminal Block, 12 mm Width)

Model	Num ber of poin ts	Rated input voltage	I/O refreshing method	ON/OFF response time	Reference
NX-IA3117	4 point s	200 to 240 VAC, 50/60 Hz (170 to 264 VAC, ±3 Hz)	Free-Run refreshing	10 ms max./40 ms max.	P. A-40

#### 1-3-3 **Digital Output Units**

This section shows the specifications for Digital Output Units.

Refer to A-1-3 Digital Output Units on page A-42 for details on the specifications of individual Digital Output Units.

### Transistor Output Units (Screwless Clamping Terminal Block, 12 mm Width)

Model	Num- ber of points	Internal I/O common	Maximum value of load cur- rent	Rated volt- age	I/O refresh- ing method	ON/OFF response time	Refer- ence
NX-OD2154		NPN			Output		P. A-45
NX-OD2258	2 points	PNP	0.5 A/point, 1 A/Unit	24 VDC	refreshing with speci- fied time stamp only	300 ns max./300 ns max.	P. A-47
NX-OD3121		NPN		12 to 24 VDC	Switching Synchro- nous I/O refreshing and	0.1 ms max./0.8 ms max.	P. A-49
NX-OD3153	4 points	IN IN	0.5 A/point,	24 VDC		300 ns max./300 ns max.	P. A-51
NX-OD3256			2 A/Unit			0.5 ms max./1.0 ms max.	P. A-53
NX-OD3257		PNP  2 A/poir A/Unit		24 VDC		300 ns max./300 ns max.	P. A-55
NX-OD3268			2 A/point, 8 A/Unit			0.5 ms max./1.0 ms max.	P. A-57
NX-OD4121	8 noints	NPN		12 to 24 VDC	Free-Run refreshing	0.1 ms max./0.8 ms max.	P. A-59
NX-OD4256	8 points	PNP	0.5 A/point,	24 VDC		0.5 ms max./1.0 ms max.	P. A-61
NX-OD5121		NPN	4 A/Unit	12 to 24 VDC		0.1 ms max./0.8 ms max.	P. A-63
NX-OD5256	points	PNP		24 VDC		0.5 ms max./1.0 ms max.	P. A-65

### Transistor Output Units (M3 Screw Terminal Block, 30 mm Width)

Model	Num- ber of points	Internal I/O common	Maximum value of load cur-rent	Rated volt- age	I/O refresh- ing method	ON/OFF response time	Refer- ence
NX-OD5121-1	- 16 points	NPN	0.5 A/point,	12 to 24 VDC	Switching Synchro- nous I/O refreshing and Free-Run refreshing	0.1 ms max./0.8 ms max.	P. A-67
NX-OD5256-1		PNP	5 A/Unit	24 VDC		0.5 ms max./1.0 ms max.	P. A-69

### Transistor Output Units (MIL Connector, 30 mm Width)

Model	Num- ber of points	Internal I/O common	Maximum value of load cur- rent	Rated volt- age	I/O refresh- ing method	ON/OFF response time	Refer- ence
NX-OD5121-5	16	NPN (	0.5 A/point,	12 to 24 VDC	Switching Synchro- nous I/O refreshing	0.1 ms max./0.8 ms max.	P. A-71
NX-OD5256-5	points	PNP	2 A/Unit	24 VDC		0.5 ms max./1.0 ms max.	P. A-73
NX-OD6121-5	32	NPN 0.5 A/point, 2 A/com-	12 to 24 VDC	and Free-Run refreshing	0.1 ms max./0.8 ms max.	P. A-75	
NX-OD6256-5	points	PNP	mon, 4 A/Unit	24 VDC	3	0.5 ms max./1.0 ms max.	P. A-77

### Transistor Output Units (Fujitsu Connector, 30 mm Width)

Model	Num- ber of points	Internal I/O common	Maximum value of load cur- rent	Rated volt- age	I/O refresh- ing method	ON/OFF response time	Refer- ence
NX-OD6121-6	32 points	NPN	0.5 A/point, 2 A/com- mon, 4 A/Unit	12 to 24 VDC	Switching Synchro- nous I/O refreshing and Free-Run refreshing	0.1 ms max./0.8 ms max.	P. A-79

### Relay Output Units (Screwless Clamping Terminal Block, 12 mm Width)

Model	Num- ber of points	Relay type	Maximum switching capacity	I/O refresh- ing method	ON/OFF response time	Refer- ence
NX-OC2633		N.O.	250 VAC/2 A (cosΦ = 1),		15 ms	P. A-81
NX-OC2733	2 points	N.O. + N.C.	250 VAC/2 A (cosΦ = 0.4), 24 VDC/2 A, 4 A/Unit	Free-Run refreshing	max./15 ms max.	P. A-83

### Relay Output Units (Screwless Clamping Terminal Block, 24 mm Width)

Model	Num- ber of points	Relay type	Maximum switching capacity	I/O refresh- ing method	ON/OFF response time	Refer- ence
NX-OC4633	8 points	N.O.	250 VAC/2A (cosΦ = 1), 250 VAC/2A (cosΦ = 0.4), 24 VDC/2A, 8 A/Unit	Free-Run refreshing	15 ms max./15 ms max.	P. A-85

### 1-3-4 Digital Mixed I/O Units

This section shows the specifications for Digital Mixed I/O Units.

Refer to A-1-4 Digital Mixed I/O Units on page A-87 for details on the specifications of individual Mixed I/O Units.

### DC Input/Transistor Output Units (MIL Connector, 30 mm Width)

Model	Num- ber of points	Internal I/O common	Maximum value of load cur- rent	Rated volt- age	I/O refreshing method	ON/OFF response time	Refer- ence
		Outputs: NPN		Outputs: 12 to 24 VDC		Outputs: 0.1 ms max./0.8 ms max.	
NX-MD6121-5	Out- puts: 16 points	both NPN/PNP  Outputs: PNP	0.5 A/point, 2 A/Unit	Inputs: 24 VDC	Switching Synchro- nous I/O	Inputs: 20 µs max./400 µs max.	P. A-89
NX-MD6256-5	Inputs: 16 points			Outputs: 24 VDC Inputs: 24 VDC	refreshing and Free-Run refreshing	Outputs: 0.5 ms max./1.0 ms max. Inputs: 20 µs max./400 µs max.	P. A-93

### DC Input/Transistor Output Units (Fujitsu Connector, 30 mm Width)

Model	Num- ber of points	Internal I/O common	Maximum value of load cur- rent	Rated volt- age	I/O refresh- ing method	ON/OFF response time	Refer- ence
NX-MD6121-6	Out- puts: 16 points Inputs: 16 points	Outputs: NPN Inputs: For both NPN/PNP	0.5 A/point, 2 A/Unit	Outputs: 12 to 24 VDC Inputs: 24 VDC	Switching Synchro- nous I/O refreshing and Free-Run refreshing	Outputs: 0.1 ms max./0.8 ms max. Inputs: 20 µs max./400 µs max.	P. A-97

# **List of Functions**

This section provides an overview of functions that the Digital I/O Units have.

Refer to the specifications of each model in A-1 Data Sheet on page A-3 for details on the functions.

#### 1-4-1 **Digital Input Units**

Function name		Description	Reference
Free-Run Refreshing		With this I/O refreshing method, the refresh cycle of the NX bus and the I/O refresh cycles of the NX Units are asynchronous.	5-2-4 Free-Run Refreshing on page 5-9
Synchronous I/O Refreshing		With this I/O refreshing method, the timing to read inputs or to refresh outputs is synchronized on a fixed interval between more than one NX Unit connected to a CPU Unit.  In addition, with this I/O refreshing method, the timing to read inputs or to refresh outputs is synchronized on a fixed interval between more than one NX Unit on more than one Slave Terminal.	5-2-5 Synchro- nous Input Refreshing on page 5-13
Time Stamp Refreshing		With this I/O refreshing method, the NX Units record the DC times when inputs change or perform outputs at specified DC times. These times are not synchronized to the NX bus refresh cycles.  Data exchange between the NX Units and the CPU Unit and data exchange between the NX Units and the EtherCAT Coupler Unit are performed cyclically on the NX bus refresh cycles.	5-2-7 Time Stamp Refreshing on page 5-20
Input refreshing with input changed time		With this I/O refreshing method, the Input Units record the DC times when inputs changed.	5-2-8 Input Refreshing with Input Changed Time on page 5-21
Input Filter		This function eliminates the chattering or the noises from input signals.	6-4-2 Input Filter on page 6-14
		It is used to prevent the error reading due to the noises. You can set the filter time constant.	

### 1-4-2 Digital Output Units

F	unction name	Description	Reference
Free-F	Run Refreshing	With this I/O refreshing method, the refresh cycle of the NX bus and the I/O refresh cycles of the NX Units are asynchronous.	5-2-4 Free-Run Refreshing on page 5-9
Synchronous I/O Refreshing		With this I/O refreshing method, the timing to read inputs or to refresh outputs is synchronized on a fixed interval between more than one NX Unit connected to a CPU Unit.  In addition, with this I/O refreshing method, the timing to read inputs or to refresh outputs is synchronized on a fixed interval between more than one NX Unit on more than one Slave Terminal.	5-2-6 Synchro- nous Output Refreshing on page 5-17
Time Stamp Refreshing		With this I/O refreshing method, the NX Units record the DC times when inputs change or perform outputs at specified DC times. These times are not synchronized to the NX bus refresh cycles.  Data exchange between the NX Units and the CPU Unit and data exchange between the NX Units and the EtherCAT Coupler Unit are performed cyclically on the NX bus refresh	5-2-7 Time Stamp Refreshing on page 5-20
		cycles.	
	Output refreshing with specified time stamp	With this I/O refreshing method, the Output Units refresh outputs at specified DC times.	5-2-9 Output Refreshing with Specified Time Stamp on page 5-28
Load I Setting	Rejection Output g	A function that performs the preset output operation when the Digital Output Unit cannot receive output data due to the following causes:	7-4-2 Load Rejection Output Setting on page 7-13
		When the Unit is connected to a CPU Unit: NX bus error, CPU Unit watchdog timer error, etc.	
		When the Unit is connected to a Communications Coupler Unit: Host error on the Communications Coupler Unit, NX bus error, etc.	
		When the Unit is connected to a Communication Control Unit: NX bus error, Communication Control Unit watchdog timer error, etc.	
Load stion	Short-circuit Protec-	A function in which the output will turn OFF to protect the output circuit when an overload or load short-circuit occurs due to a failure of the connected external devices.	7-4-3 Load Short-circuit Pro- tection on page 7-17

#### 1-4-3 **Digital Mixed I/O Units**

Function name	Description	Reference
Free-Run Refreshing	With this I/O refreshing method, the refresh cycle of the NX bus and the I/O refresh cycles of the NX Units are asynchronous.	5-2-4 Free-Run Refreshing on page 5-9
Synchronous I/O Refreshing	With this I/O refreshing method, the timing to read inputs or to refresh outputs is synchronized on a fixed interval between more than one NX Unit connected to a CPU Unit.  In addition, with this I/O refreshing method, the timing to read inputs or to refresh outputs is synchronized on a fixed interval between more than one NX Unit on more than one Slave Terminal.	5-2-5 Synchro- nous Input Refreshing on page 5-13
Input Filter	This function eliminates the chattering or the noises from input signals.  It is used to prevent the error reading due to the noises. You can set the filter time constant.	6-4-2 Input Filter on page 6-14
Load Rejection Output Setting	<ul> <li>A function that performs the preset output operation when the Digital Mixed I/O Unit cannot receive output data due to the following causes:</li> <li>When the Unit is connected to a CPU Unit: NX bus error, CPU Unit watchdog timer error, etc.</li> <li>When the Unit is connected to a Communications Coupler Unit: Host error on the Communications Coupler Unit: Host error, etc.</li> <li>When the Unit is connected to a Communication Control Unit: NX bus error, Communication Control Unit: NX bus error, Communication Control Unit watchdog timer error, etc.</li> </ul>	7-4-2 Load Rejection Output Setting on page 7-13
Load Short-circuit Protection	A function in which the output will turn OFF to protect the output circuit when an overload or load short-circuit occurs due to a failure of the connected external devices.	7-4-3 Load Short-circuit Pro- tection on page 7-17

# 1-5 Support Software

The Support Software that is used depends on the system configuration.

#### Support Software for a System Configured with a CPU Unit

If your system is configured by connecting an NX Unit to a CPU Unit, the Sysmac Studio is used as the Support Software.

#### Support Software for a System Configured with a Slave Terminal

If your system is configured by connecting an NX Unit to a Communications Coupler Unit, refer to the user's manual for the Communications Coupler Unit for information on the Support Software.

# Support Software for a System Configured with a Communication Control Unit

If your system is configured by connecting an NX Unit to a Communication Control Unit, the Sysmac Studio is used as the Support Software.

Depending on the Unit to which the NX Unit is connected, refer to the following appendices for information on the Support Software versions.

- A-7 Version Information with CPU Units on page A-164
- A-8 Version Information with Communications Coupler Units on page A-166
- A-9 Version Information with Communication Control Units on page A-170



# **Specifications**

This section describes the general specifications and individual specifications of Digital I/O Units.

2-1	General Specifications	2-2
2-2	Individual Specifications	2-3

#### **General Specifications** 2-1

General specifications of Digital I/O Units are shown below.

Item		Specification		
Enclosure		Mounted in a panel		
Grounding methods		Ground of 100 $\Omega$ or less		
	Ambient operating temperature	0 to 55°C		
	Ambient operating humidity	10 to 95% RH (with no icing or condensation)		
	Atmosphere	Must be free from corrosive gases.		
	Ambient storage temperature	-25 to 70°C (with no icing or condensation)		
	Altitude	2,000 m max.		
	Pollution degree	Pollution degree 2 or less: Conforms to JIS B 3502 and IEC 61131-2.		
Operat-	Noise immunity	Conforms to IEC 61000-4-4, 2 kV (power supply line)		
ing envi-	Overvoltage category	Category II: Conforms to JIS B 3502 and IEC 61131-2.		
ronment	EMC immunity level	Zone B		
	Vibration resistance *1	Conforms to IEC 60068-2-6. 5 to 8.4 Hz with amplitude of 3.5 mm,		
		8.4 to 150 Hz, acceleration of 9.8 m/s <sup>2</sup>		
		100 min each in X, Y, and Z directions (10 sweeps of 10 min each = 100 min total)		
	Shock resistance *1	Conforms to IEC 60068-2-27, 147 m/s <sup>2</sup> , 3 times each in X, Y, and Z directions		
	Insulation resistance	*2		
	Dielectric strength	*2		
Applicable standards <sup>*3</sup>		cULus: Listed (UL508) or Listed (UL 61010-2-201), ANSI/ISA 12.12.01, EU: EN 61131-2 or EN 61010-2-201, C-Tick, KC: KC Registration, NK, LR		

<sup>\*1.</sup> Relay Output Unit specifications depend on the model. Refer to A-1 Data Sheet on page A-3 for details.

<sup>\*2.</sup> Varies with NX Unit Models. Refer to A-1 Data Sheet on page A-3 for the specifications of individual NX Units.

<sup>\*3.</sup> Refer to the OMRON website (www.ia.omron.com) or ask your OMRON representative for the most recent applicable standards for each model.

# 2-2 Individual Specifications

Refer to A-1 Data Sheet on page A-3 for the specifications of individual Digital I/O Units.



# **Part Names and Functions**

This section describes the names and functions of the Digital I/O Unit parts.

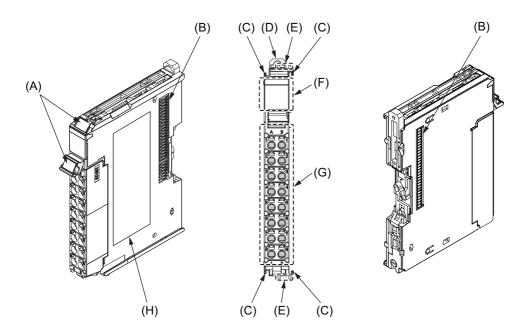
3-1	Part N	lames
	3-1-1	Screwless Clamping Terminal Block Type
	3-1-2	M3 Screw Terminal Block Type
	3-1-3	Connector Types
3-2	Indica	ators 3-13
	3-2-1	TS Indicator
	3-2-2	IN/OUT Indicator
	3-2-3	Appearance Change of the Indicators

# **Part Names**

This section describes the names and functions of the Digital I/O Unit parts.

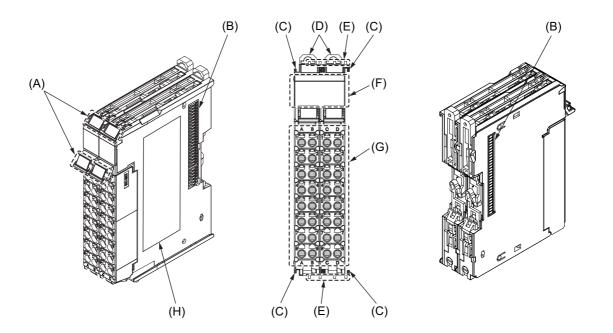
#### **Screwless Clamping Terminal Block Type** 3-1-1

### NX Units (12 mm Width)



Let- ter	Name	Function		
		The locations where markers are attached. The markers made by OMRON are installed for the factory setting. Commercially available markers can also be installed.		
		Refer to 4-1-2 Attaching Markers on page 4-4		
(B)	NX bus connector	This connector is used to connect each Unit.		
(C)	Unit hookup guides	These guides are used to connect two Units.		
(D)	DIN Track mounting hooks	These hooks are used to mount the NX Unit to a DIN Track.		
(E)	Protrusions for removing the Unit	The protrusions to hold when removing the Unit.		
(F)	Indicators	The indicators show the current operating status of the Unit.		
		Refer to 3-2 Indicators on page 3-13		
(G) Terminal block The terminal block is used to connect external dev		The terminal block is used to connect external devices.		
		The number of terminals depends on the type of Unit.		
(H)	Unit specifications	The specifications of the Unit are given.		

### NX Units (24 mm Width)

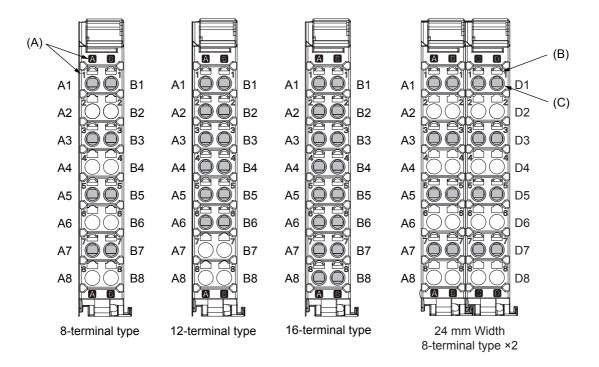


Let- ter	Name	Function		
(A)	Marker attachment locations	The locations where markers are attached. The markers made by OMRON are installed for the factory setting. Commercially available markers can also be installed.		
		Refer to 4-1-2 Attaching Markers on page 4-4		
(B)	NX bus connector	This connector is used to connect each Unit.		
(C)	Unit hookup guides	These guides are used to connect two Units.		
(D)	DIN Track mounting hooks	These hooks are used to mount the NX Unit to a DIN Track.		
(E)	Protrusions for removing the Unit	The protrusions to hold when removing the Unit.		
(F)	Indicators	The indicators show the current operating status of the Unit.		
		Refer to 3-2 Indicators on page 3-13		
(G)	Terminal block	The terminal block is used to connect external devices.		
		The number of terminals depends on the type of Unit.		
(H)	Unit specifications	The specifications of the Unit are given.		

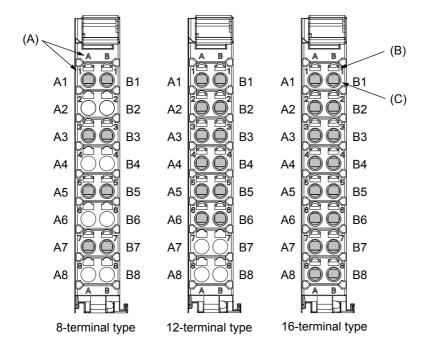
#### **Terminal Blocks**

There are two models of screwless clamping terminal blocks: NX-TB□□□2 and NX-TB□□□1. Each model has three types of terminal blocks: 8-terminal type, 12-terminal type, and 16-terminal type.

#### NX-TB□□□2



#### NX-TB□□□1



Let- ter	Name	Function
(A)	Terminal number indi- cations	Terminal numbers for which A and B indicate the column, and 1 to 8 indicate the line are displayed.
		The terminal number is a combination of column and line, i.e. A1 to A8 and B1 to B8.
		For models of 24 mm width, A1 to A8 and B1 to B8 are terminal number of the left terminal block, C1 to C8 and D1 to D8 are terminal numbers of the right terminal block.
		The terminal number indications are the same regardless of the number of terminals on the terminal block.
(B)	Release holes	Insert a flat-blade screwdriver into these holes to connect and remove the wires.
(C)	Terminal holes	The wires are inserted into these holes.

The NX-TB $\square\square\square$ 2 and N	√IX-TB□□□1 Terminal	Blocks have	different terminal	current	capacities.
The NX-TB□□□2 has 1	0 A and NX-TB□□□1	has 4 A.			

To differentiate between the two models of terminal blocks, use the terminal number column indications. The terminal block with white letters on a dark background is the NX-TB $\square\square$ 2.

You can mount either NX-TB $\square$ 1 or NX-TB $\square$ 2 Terminal Blocks to the Units that the current capacity specification of the terminals is 4 A or less.

You can only mount the NX-TB $\square\square$ 2 Terminal Block to the Units that the current capacity specification of the terminals is greater than 4 A.



#### **Additional Information**

- Each Digital I/O Unit is compatible with only one of three types of terminal blocks. You cannot use a terminal block with a number of terminals that differs from the specifications for a particular Unit.
- The 8-terminal type and 12-terminal type do not have terminal holes and release holes for following terminal numbers.

8-terminal type: A2, A4, A6, A8, B2, B4, B6, and B8

12-terminal type: A7, A8, B7, and B8

#### Applicable Terminal Blocks for Each Unit Model

The following indicates the terminal blocks that are applicable to each Unit.

	Terminal block				
Unit model number	Model	Number of terminals	Ground terminal mark	Current capacity	
NX-ID3□□□	NX-TBA121	12	Not provided	4 A	
	NX-TBA122			10 A	
NX-ID4□□□	NX-TBA161	16		4 A	
NX-ID5□□□	NX-TBA162			10 A	
NX-IA3117	NX-TBA081	8		4 A	
NX-OD2□□□	NX-TBA082			10 A	
NX-OD3268	NX-TBA162	16		10 A	
NX-OD3□□□	NX-TBA121	12		4 A	
(any model other than NX-OD3268)	NX-TBA122			10 A	
NX-OD4□□□	NX-TBA161	16		4 A	
NX-OD5□□□	NX-TBA162			10 A	
NX-OC2□□□	NX-TBA081	8		4 A	
	NX-TBA082			10 A	
NX-OC4633	NX-TBA082	8		10 A	
	NX-TBB082				



#### **Precautions for Correct Use**

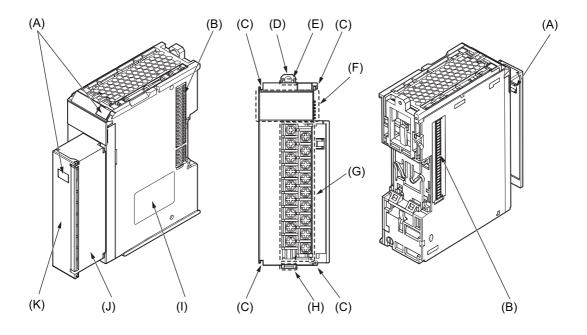
You can mount either NX-TB \underset 1 or NX-TB \underset 2 Terminal Blocks to the Units that the current capacity specification of the terminals is 4 A or less.

However, even if you mount the NX-TB□□□2 Terminal Block, the current specification does not change because the current capacity specification of the terminals on the Units is 4 A or

Refer to A-6 List of Screwless Clamping Terminal Block Models on page A-163 for information on the models of terminal blocks.

# 3-1-2 M3 Screw Terminal Block Type

# NX Units (30 mm Width)

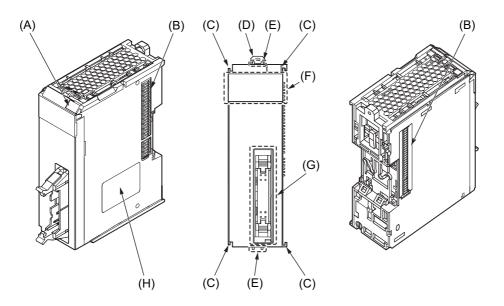


Let- ter	Name	Function	
(A)	Marker attachment locations	The locations where markers are attached. The markers made by OMRON are installed for the factory setting. Commercially available markers can also be installed.	
		Refer to 4-1-2 Attaching Markers on page 4-4	
(B)	NX bus connector	This connector is used to connect each Unit.	
(C)	Unit hookup guides	These guides are used to connect two Units.	
(D)	DIN Track mounting hooks	These hooks are used to mount the NX Unit to a DIN Track.	
(E)	Protrusions for removing the Unit	The protrusions to hold when removing the Unit.	
(F)	Indicators	The indicators show the current operating status of the Unit.	
		Refer to 3-2 Indicators on page 3-13	
(G)	Screw terminals	These screw terminals are used to connect the wires.	
(H)	Terminal block lever	llock lever This lever is used to fix the terminal block on the NX Unit.	
(I)	Unit specifications	specifications The specifications of the Unit are given.	
(J)	Terminal block	The terminal block is used to connect external devices.	
(K)	Terminal block cover	This cover is used to protect the screw terminals.	

#### **Connector Types** 3-1-3

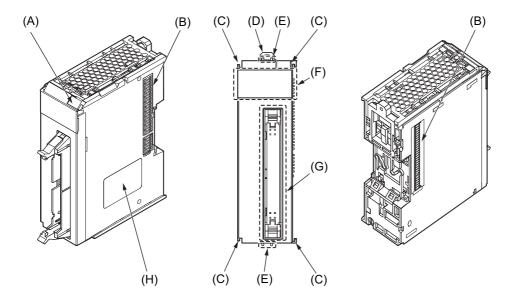
# NX Units (30 mm Width)

## • Units with MIL Connectors (1 Connector with 20 Terminals)

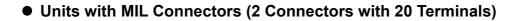


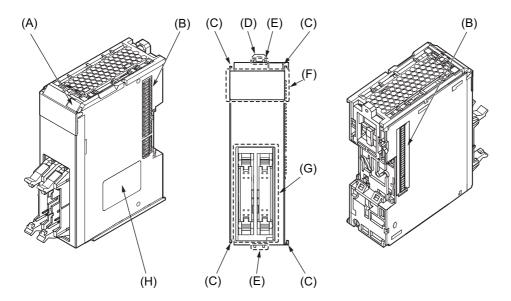
Let- ter	Name	Function	
(A)	(A) Marker attachment location where markers are attached. The markers made to are installed for the factory setting. Commercially available mark be installed.		
		Refer to 4-1-2 Attaching Markers on page 4-4.	
(B)	NX bus connector	This connector is used to connect each Unit.	
(C)	Unit hookup guides	These guides are used to connect two Units.	
(D)	DIN Track mounting hooks	g hooks These hooks are used to mount the NX Unit to a DIN Track.	
(E)	Protrusions for removing the Unit	·	
(F)	Indicators The indicators show the current operating status of the Unit.		
	Refer to 3-2 Indicators on page 3-13.		
(G)	Connectors	The connectors are used to connect to external devices.	
(H)	Unit specifications	The specifications of the Unit are given.	

## • Units with MIL Connectors (1 Connector with 40 Terminals)



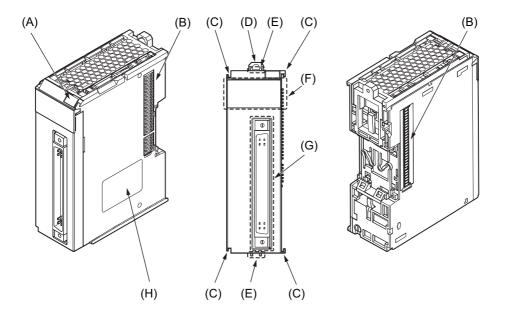
Let- ter	Name	Function	
(A)	Marker attachment location where markers are attached. The markers made are installed for the factory setting. Commercially available mar be installed.		
		Refer to 4-1-2 Attaching Markers on page 4-4.	
(B)	NX bus connector This connector is used to connect each Unit.		
(C)	Unit hookup guides	These guides are used to connect two Units.	
(D)	DIN Track mounting hooks	ting hooks These hooks are used to mount the NX Unit to a DIN Track.	
(E)	Protrusions for removing The protrusions to hold when removing the Unit. the Unit		
(F)	Indicators The indicators show the current operating status of the Unit.		
		Refer to 3-2 Indicators on page 3-13.	
(G)	Connectors	The connectors are used to connect to external devices.	
(H)	Unit specifications	The specifications of the Unit are given.	



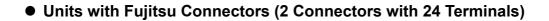


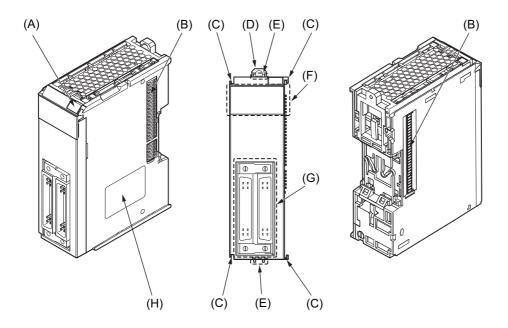
Let- ter	Name	Function	
(A)	Marker attachment location	The locations where markers are attached. The markers made by OMRON are installed for the factory setting. Commercially available markers can also be installed.	
		Refer to 4-1-2 Attaching Markers on page 4-4.	
(B)	NX bus connector	This connector is used to connect each Unit.	
(C)	Unit hookup guides	These guides are used to connect two Units.	
(D)	DIN Track mounting hooks	These hooks are used to mount the NX Unit to a DIN Track.	
(E)	Protrusions for removing the Unit	The protrusions to hold when removing the Unit.	
(F)	Indicators	The indicators show the current operating status of the Unit.	
		Refer to 3-2 Indicators on page 3-13.	
(G)	Connectors	The connectors are used to connect to external devices.	
(H)	Unit specifications	The specifications of the Unit are given.	

## • Units with Fujitsu Connectors (1 Connector with 40 Terminals)



Let- ter	Name	Function	
(A)	Marker attachment location tion  The locations where markers are attached. The markers made by O are installed for the factory setting. Commercially available markers be installed.		
		Refer to 4-1-2 Attaching Markers on page 4-4.	
(B)	NX bus connector This connector is used to connect each Unit.		
(C)	Unit hookup guides	These guides are used to connect two Units.	
(D)	DIN Track mounting hooks	s These hooks are used to mount the NX Unit to a DIN Track.	
(E)	Protrusions for removing the Unit	ng The protrusions to hold when removing the Unit.	
(F)	Indicators	The indicators show the current operating status of the Unit.	
		Refer to 3-2 Indicators on page 3-13.	
(G)	Connectors	The connectors are used to connect to external devices.	
(H)	Unit specifications	The specifications of the Unit are given.	





Let- ter	Name	Function	
(A)	Marker attachment location	The locations where markers are attached. The markers made by OMRON are installed for the factory setting. Commercially available markers can also be installed.	
		Refer to 4-1-2 Attaching Markers on page 4-4.	
(B)	NX bus connector	This connector is used to connect each Unit.	
(C)	Unit hookup guides	These guides are used to connect two Units.	
(D)	DIN Track mounting hooks	These hooks are used to mount the NX Unit to a DIN Track.	
(E)	Protrusions for removing the Unit	The protrusions to hold when removing the Unit.	
(F)	Indicators	The indicators show the current operating status of the Unit.	
		Refer to 3-2 Indicators on page 3-13.	
(G)	Connectors	The connectors are used to connect to external devices.	
(H)	Unit specifications	The specifications of the Unit are given.	

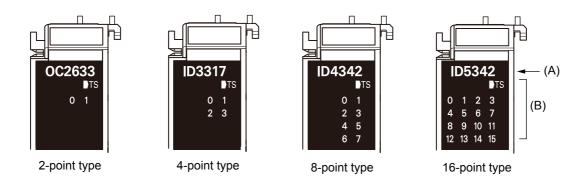
# 3-2 Indicators

There are the indicators to show the current operating status of the Unit or the signal I/O status on the Digital I/O Units.

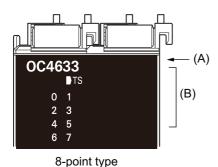
The appearance of the indicators has been changed for models released in or before September 2018 with lot numbers that represent the date of or after September 20, 2018. In this manual, those models are shown with the indicators after the change. For details on the applicable models and the changes, refer to 3-2-3 Appearance Change of the Indicators on page 3-17.

The following indicator patterns are available depending on width of the Unit and the number of I/O points.

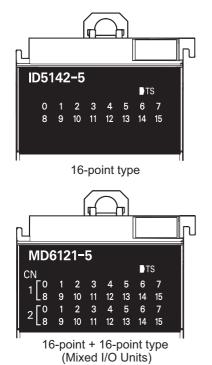
## NX Units (12 mm Width)

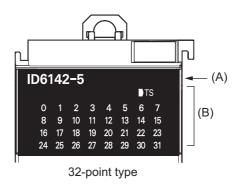


## NX Units (24 mm Width)



## • NX Units (30 mm Width)





Let- ter	Name	Function	
(A)	Model number indications	The model numbers of the NX Unit are displayed.	
		(Example) "ID3317" in the case of NX-ID3317	
		The NX Units are separated in the following color depending on the type of inputs and outputs.	
		Digital Input Unit: Orange	
		Digital Output Unit: Yellow	
		Digital Mixed I/O Unit: White	
(B)	Indicators	The indicators show the current operating status of the NX Unit or the signal	
		I/O status.	

The following section describes the specifications of each indicator.

# 3-2-1 TS Indicator

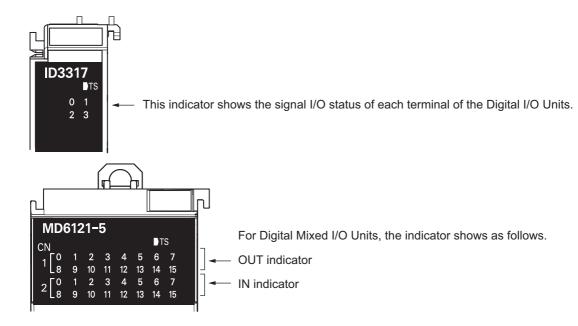


The meanings of light statuses are described as follows:

Color		Status	Description
Green	\ <u> </u>	Lit	The Unit is operating normally.
			The Unit is ready for I/O refreshing.
			I/O checking is operating.*1
		Flashing at 2-s	Initializing
		intervals.	Restarting is in progress for the Unit.
			Downloading
Red		Lit	A hardware failure, WDT error, or other fatal error that is common to all I/O Units occurred.
		Flashing at 1-s	A communications error or other NX bus-related error that is common
		intervals.	to all I/O Units occurred.
		Not lit	No Unit power supply
			Restarting is in progress for the Unit.
			Waiting for initialization to start

<sup>\*1.</sup> Refer to the manual for the Communications Coupler Unit for the status of the indicator on the Communications Coupler Units when I/O checking is in progress.

#### **IN/OUT Indicator** 3-2-2



The following shows an example of Contact 1. The number of the I/O contact is lit or not lit.

Color		Status	Description
Yellow	1	Lit	The digital I/O contact corresponding to the contact number is ON.
	1	Not lit	The digital I/O contact corresponding to the contact number is OFF.



## **Additional Information**

Product models before the appearance change have a square-shaped light-emitter on the left side of each I/O contact number code. For details on the applicable models and the changes, refer to 3-2-3 Appearance Change of the Indicators on page 3-17.

Color	Status	Description
Yellow	Lit	Digital I/O is ON
	Not lit	Digital I/O is OFF

## 3-2-3 Appearance Change of the Indicators

The appearance of the indicators has been changed for models released in or before September 2018 with lot numbers that represent the date of or after September 20, 2018. See below for details on the applicable models and the changes. Models that are not listed here have the appearance after the change.

## **Applicable Models**

NX-ID3317, NX-ID3343, NX-ID3344, NX-ID3417,

NX-ID3443, NX-ID3444, NX-ID4342, NX-ID4442,

NX-ID5142-1, NX-ID5142-5, NX-ID5342, NX-ID5442,

NX-ID6142-5, NX-ID6142-6, NX-IA3117, NX-OD2154,

NX-OD2258, NX-OD3121, NX-OD3153, NX-OD3256,

NX-OD3257, NX-OD3268, NX-OD4121, NX-OD4256,

NX-OD5121, NX-OD5121-1, NX-OD5121-5, NX-OD5256,

NX-OD5256-1, NX-OD5256-5, NX-OD6121-5, NX-OD6121-6,

NX-OD6256-5, NX-OC2633, NX-OC2733,

NX-OC4633, NX-MD6121-5, NX-MD6121-6, NX-MD6256-5

## **Change Details**

#### TS Indicator

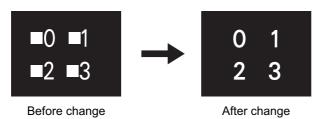
The shape of the light emitting part of each indicator has been changed from a square to a pentagon.

See below.



#### IN/OUT Indicator

The indicators before the change have a square-shaped light-emitter on the left side of each I/O contact number, and the indicators after the change have the I/O contact numbers emitting light.





# **Installation and Wiring**

This section describes how to install the NX Units, the types of power supplies provided to the NX Units and wiring methods, and how to wire the NX Units.

4-1	Installi	ing NX Units	4-2
	4-1-1	Installing NX Units	4-2
	4-1-2	Attaching Markers	4-4
	4-1-3	Removing NX Units	4-6
	4-1-4	Installation Orientation	4-7
4-2	Power	Supply Types and Wiring	4-9
	4-2-1	Applications of I/O Power Supply and Supply Methods	4-9
	4-2-2	Calculating the Total Current Consumption from I/O Power Supply 4	11
4-3	Wiring	the Terminals 4-	-13
	4-3-1	Wiring to the Screwless Clamping Terminal Block	-13
	4-3-2	Wiring to M3 Screw Terminal Block	-32
	4-3-3	Wiring to MIL/Fujitsu Connectors	-36
	4-3-4	Checking the Wiring	-40
4-4	Wiring	Examples 4-	-41
	4-4-1	Wiring the Input Units	-41
	4-4-2	Precautions when Wiring to the Input Units	-53
	4-4-3	Precautions when Wiring to the Output Units 4	-55

# **Installing NX Units**

This section describes how to install NX Units.

Refer to the user's manual for the CPU Unit, Communications Coupler Unit, or Communication Control Unit to which NX Units are connected for information on preparations of installation and installation in a control panel.

#### 4-1-1 **Installing NX Units**

This section describes how to mount two NX Units to each other.

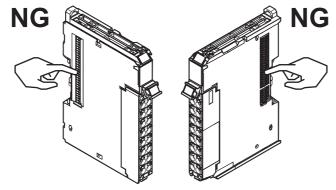
Always turn OFF the power supply before you mount NX Units.

Always mount NX Units one at a time. If you attempt to mount multiple NX Units that are already connected together, the connections between the NX Units may separate from each other and fall.



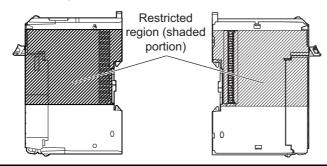
#### **Precautions for Safe Use**

- Always turn OFF the power supply before installing the Unit. If the power supply is not OFF, the Unit may malfunction or may be damaged.
- · Do not apply labels or tape on the NX Units. When the Unit is installed or removed, adhesive or scrap may adhere to the pins of the NX bus connector, which may cause malfunctions.
- Do not touch the pins in the NX bus connector on the Unit. Dirt may adhere to the pins in the NX bus connector, which may result in malfunctions.



Example: NX Unit (12 mm width)

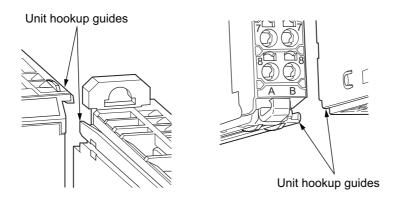
- Do not write on an NX Unit with ink within the restricted region that is shown in the following figure. Also do not get this area dirty. When the Unit is installed or removed, ink or dirt may adhere to the pins in the NX bus connector, which may result in malfunctions in the CPU Rack or the Slave Terminal.
  - Refer to the user's manual for the connected CPU Unit, Communications Coupler Unit, or Communication Control Unit for details on the restricted region on the CPU Unit, Communications Coupler Unit, or Communication Control Unit.



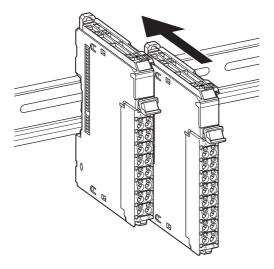


#### **Precautions for Correct Use**

- When you install an NX Unit, do not touch or bump the pins in the NX bus connector.
- When you handle an NX Unit, be careful not to apply any stress to the pins in the NX bus connector. If you install an NX Unit and turns ON the power supply when the pins in the NX bus connector are deformed, a contact defect may cause malfunctions.
- **1** From the front of the previously mounted NX Unit, engage the Unit hookup guides on a new Unit with the Unit hookup guides on the previously mounted NX Unit.



2 Slide the NX Unit in on the hookup guides.



**3** Press the NX Unit with a certain amount of force against the DIN Track until you hear the DIN Track mounting hook lock into place.

When you mount the NX Unit, it is not necessary to release the DIN track mounting hook on the NX Unit.

After you mount the NX Unit, make sure that it is locked to the DIN Track.



#### Additional Information

- Normally, it is not necessary to release the DIN track mounting hook when you mount the NX Unit. However, if you mount the NX Unit on a DIN Track that is not a recommended DIN Track, the DIN track mounting hook may not lock correctly. If that happens, first unlock the DIN track mounting hook, mount the NX Unit to the DIN Track, then lock the DIN track mounting hook.
- Refer to the user's manual for the CPU Unit to which NX Units can be connected for information on how to mount the CPU Unit, and how to mount NX Units to the CPU Unit.
- · Refer to the user's manual for the Communications Coupler Unit for information on how to mount the Communications Coupler Unit, and how to mount the NX Unit to the Communications Coupler Unit.
- Refer to the user's manual for the Communication Control Unit for information on how to mount the Communication Control Unit, and how to mount NX Units to the Communication Control Unit.

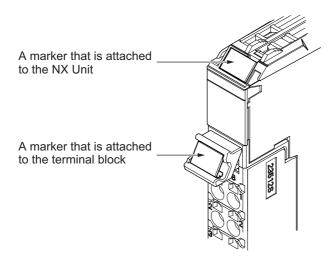
#### 4-1-2 **Attaching Markers**

You can attach markers to the NX Units to identify them.

The plastic markers made by OMRON are installed for the factory setting. The ID information can be written on them.

Commercially available markers can also be installed.

Replace the markers made by OMRON if you use commercially available markers now.

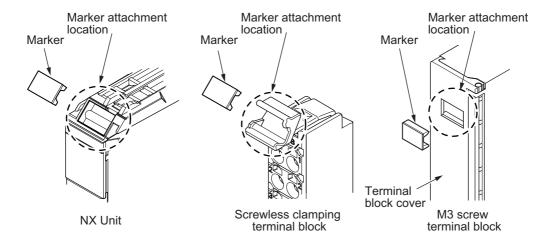


The marker attachment locations vary depending on the type of the external connection terminals on the NX Units.

External connection terminals on NX Units	Marker attachment location	
Screwless clamping terminal block	NX Unit and terminal block	
M3 screw terminal block		
MIL connector	NX Unit only	
Fujitsu connector		

#### Installation Method

Insert the protrusions on the markers into the marker attachment locations.



## Commercially Available Markers

Commercially available markers are made of plastic and can be printed on with a special printer. To use commercially available markers, purchase the following products.

Product name	Model number			
Froduct Hairie	Manufactured by Phoenix Contact	Manufactured by Weidmuller		
Markers	UC1-TMF8	DEK 5/8		
Special marker printer	UM EN BLUEMARK X1	PrintJet PRO		

The markers made by OMRON cannot be printed on with commercially available special printers.

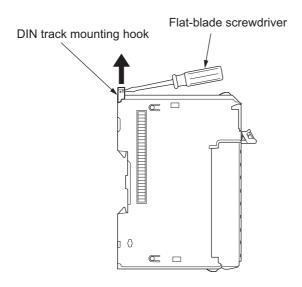
#### **Removing NX Units** 4-1-3



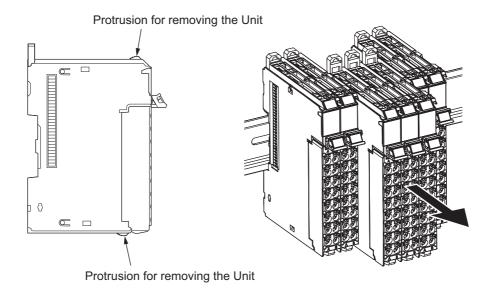
## **Precautions for Safe Use**

Always turn OFF the Unit power supply and I/O power supply before you remove the NX Unit.

Use a flat-blade screwdriver to pull up the DIN Track mounting hook on the Unit to remove.



Put your fingers on the protrusions for removing multiple NX Units including the Unit to be removed, then pull out straight forward to remove.





#### **Precautions for Correct Use**

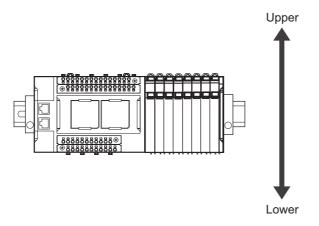
- When removing an NX Unit, remove multiple Units together which include the one you want to remove. If you attempt to remove only one Unit, it is stuck and hard to pull out.
- Do not unlock the DIN track mounting hooks on all of the NX Units at the same time. If you
  unlock the DIN Track mounting hooks on all of the NX Units at the same time, all of the Units
  may come off.

## 4-1-4 Installation Orientation

The following explains the installation orientation for each NX Unit connection destination.

# Installation Orientation in the Case of a CPU Unit or Communication Control Unit

Orientation is possible only in the upright installation orientation.



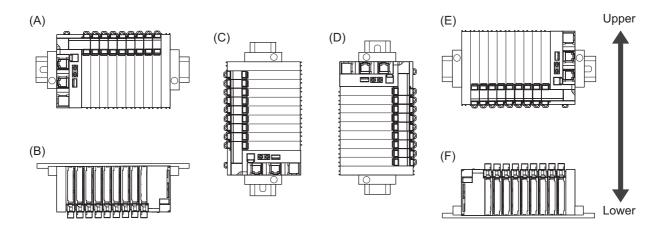
However, there are restrictions on the specifications depending on the NX Units to be used.

Refer to the user's manuals for the NX Units and System Units that you will use for details on restrictions.

## Installation Orientation in the Case of a Slave Terminal

Orientation is possible in the following six directions.

(A) is the upright orientation and (B) to (F) are other orientations.



However, there are restrictions on the installation orientation and restrictions to specifications that can result from the Communications Coupler Units and NX Units that are used.

Refer to the user's manuals for the Communications Coupler Units, NX Units and System Units that you will use for details on restrictions.



#### **Precautions for Safe Use**

For installation orientations (C) and (D) in the above figure, support the cables, e.g., with a duct, so that the End Plate on the bottom is not subjected to the weight of the cables. The weight of the cables may cause the bottom End Plate to slide downward so that the Slave Terminal is no longer secured to the DIN Track, which may cause malfunctions.

# 4-2 Power Supply Types and Wiring

There are the following two types of power supplies that supply power to the NX Units.

Power supply name	Description
NX Unit power supply	This power supply is used for operating the NX Units.
I/O power supply	This power supply is used for driving the I/O circuits of the NX Units and for the connected external devices.

The method for supplying power to the NX Units and the wiring method depend on the specifications for the CPU Unit, Slave Terminal, or Communication Control Unit to which NX Units are connected. Depending on where the NX Unit is connected, refer to *Designing the Power Supply System* or *Wiring* in the following manuals for details on the method for supplying power to the NX Units and the wiring method.

- CPU Unit Hardware User's Manual
- User's manual for the Communications Coupler Unit
- User's manual for the Communication Control Unit

The subsequent sections describe the applications of I/O power supply for the Digital I/O Units and supply methods, and how to calculate the total current consumption from the I/O power supply.

## 4-2-1 Applications of I/O Power Supply and Supply Methods

The applications of I/O power supply and supply methods for the Digital I/O Units are given as follows:

## **Applications of I/O Power Supply**

The I/O power supply is used for the following applications.

- · I/O circuits operations in the Digital I/O Units
- · Input current in a Digital Input Unit
- · Load current of the external load of a Digital Output Unit
- · Power supply for the connected external devices

## I/O Power Supply Method

This power is supplied by one of the following two methods. Refer to *A-1 Data Sheet* on page A-3 for the supply method of each NX Unit.

### Supply from the NX Bus

This power is supplied through the NX bus connectors by connecting an I/O power supply to the I/O power supply terminals on the Communications Coupler Unit or Additional I/O Power Supply Unit.

For the Units to which I/O power supply is provided by a CPU Rack with an NX-series CPU Unit, refer to *Designing the Power Supply System* or *Wiring* in the hardware user's manual for the CPU Unit to be connected.

For the Units to which I/O power supply is provided by a Slave Terminal, refer to *Designing the Power Supply System* or *Wiring* in the user's manual for the Communications Coupler Unit to be connected.

For the Units to which I/O power supply is provided by a CPU Rack with a Communication Control Unit, refer to Designing the Power Supply System or Wiring in the user's manual for the Communication Control Unit to be connected.

### Supply from External Source

This power is supplied to the Units from an external source.

I/O power is supplied by connecting an I/O power supply to the I/O power supply terminals on the Units.



#### **Additional Information**

#### Power Supply-related Units for the NX-series

The following three NX-series Units are related to power supply.

- · Additional NX Unit Power Supply Unit
- · Additional I/O Power Supply Unit
- I/O Power Supply Connection Unit

Refer to the NX-series System Unit User's Manual (Cat. No. W523) for the specifications of these Units.

For a complete list of the latest power supply Units in the NX Series, refer to the product catalog or OMRON websites, or contact your OMRON representatives.

# 4-2-2 Calculating the Total Current Consumption from I/O Power Supply

The total current consumption of I/O power supplied from the NX bus must be within the range of the maximum I/O power supply current of the Communications Coupler Unit, Communication Control Unit, or Additional I/O Power Supply Unit.

However, when an Additional I/O Power Supply Unit is connected to the CPU Rack of a CPU Unit, the maximum I/O power supply current value may be smaller than that of the Additional I/O Power Supply Unit. For example, the maximum I/O power supply current for the CPU Rack of an NX1P2 CPU Unit is 4 A.

Refer to the hardware user's manual for the CPU Unit to which NX Units are connected for information on the restrictions for the CPU Rack.

To confirm this and to calculate the I/O power supply capacity, calculate the total current consumption from I/O power supply from the NX bus.

The total current consumption from I/O power supply from the NX bus is the total sum of current consumption from I/O power supply of the NX Unit that supplies the I/O power from the NX bus, the current consumption of each applicable I/O circuit, and current consumption of any connected external devices.

Note that the current consumption from I/O power supply indicated in the data sheet for each Unit type does not include the load current of any external connection load and current consumption of any connected external devices.

The total current consumption from I/O power supply of the Digital I/O Units is calculated as follows.

### • Total Current Consumption from I/O Power Supply of the Digital Input Units

= (Current consumption from I/O power supply of the Digital Input Units) + (Input current of the Digital Input Units × Number of input points used) + (Total current consumption of connected external devices)

#### Total Current Consumption from I/O Power Supply of the Digital Output Units

= (Current consumption from I/O power supply of the Digital Output Units) + (Total load current of connection load) + (Total current consumption of connected external devices)

Refer to *A-1 Data Sheet* on page A-3 for the current consumption from I/O power supply for each Digital I/O Unit model and input current for each Digital Input Unit model.

There are no above confirmations if you use the NX Unit that supplies the I/O power from external source.

Use the total current consumption from I/O power supply from external source and the total current consumption from the I/O power supply from the above NX bus together to calculate the I/O power supply capacity.



## Precautions for Safe Use

The I/O power supply current for the CPU Rack with an NX-series CPU Unit should be within the range specified for the CPU Unit model. For example, use the NX1P2 CPU Unit with a current of 4 A or less. Using the currents that are outside of the specifications may cause failure or damage. Refer to the user's manual for the connected CPU Unit for the I/O power supply current for the CPU Unit model.

# 4-3 Wiring the Terminals

This section describes how to wire the terminals on the Digital I/O Units.

# **∕** ₩ARNING



Make sure that the voltages and currents that are input to the Units and slaves are within the specified ranges.

Inputting voltages or currents that are outside of the specified ranges may cause accidents or fire.

# **⚠** Caution



Be sure that all terminal screws and cable connector screws are tightened to the torque specified in the relevant manuals. The loose screws may result in fire or malfunction.

## 4-3-1 Wiring to the Screwless Clamping Terminal Block

This section describes how to connect wires to the screwless clamping terminal block, the installation and removing methods, and functions for preventing incorrect attachment.

You can connect ferrules that are attached to the twisted wires to the screwless clamping terminal block. You can also connect the twisted wires or the solid wires to the screwless clamping terminal block. If you connect the ferrules, all you need to do to connect the wires is to insert the ferrules into the terminal holes.

## **Wiring Terminals**

The terminals to be wired are as follows.

- · I/O power supply terminals
- I/O terminals

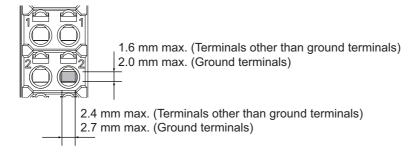
## **Applicable Wires**

The wires that you can connect to the screwless clamping terminal block are twisted wires, solid wires, and ferrules that are attached to the twisted wires. The following section describes the dimensions and processed methods for applicable wires.

## Dimensions of Wires Connected to the Terminal Block

The dimensions of wires that you can connect into the terminal holes of the screwless clamping terminal block are as in the figure below.

Process the applicable wires that are specified in the following description to apply the dimensions.



## Using Ferrules

If you use ferrules, attach the twisted wires to them.

Observe the application instructions for your ferrules for the wire stripping length when attaching ferrules.

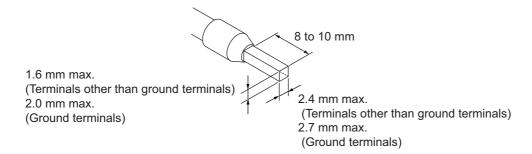
Always use plated one-pin ferrules. Do not use unplated ferrules or two-pin ferrules.

The applicable ferrules, wires, and crimping tools are listed in the following table.

Terminal types	Manufac- turer	Ferrule model	Applica- ble wire (mm <sup>2</sup> (AWG))	Crimping tool		
Terminals	Phoenix	AI0,34-8	0.34 (#22)	Phoenix Contact (The figure in parentheses is the		
other than	Contact	AI0,5-8	0.5 (#20)	applicable wire size.)		
ground ter-		AI0,5-10		CRIMPFOX 6 (0.25 to 6 mm <sup>2</sup> , AWG24 to 10)		
minals		AI0,75-8	0.75 (#18)			
		AI0,75-10				
		AI1,0-8	1.0 (#18)			
		AI1,0-10				
		AI1,5-8	1.5 (#16)			
		AI1,5-10				
Ground ter- minals		Al2,5-10	2.0 *1			
Terminals	Weidmuller	H0.14/12	0.14 (#26)	Weidmuller (The figure in parentheses is the appli-		
other than		H0.25/12	0.25 (#24)	cable wire size.)		
ground ter-		H0.34/12	0.34 (#22)	PZ6 Roto (0.14 to 6 mm <sup>2</sup> , AWG26 to 10)		
minals		H0.5/14	0.5 (#20)			
		H0.5/16				
		H0.75/14	0.75 (#18)			
		H0.75/16				
		H1.0/14	1.0 (#18)			
		H1.0/16		_		
		H1.5/14	1.5 (#16)			
		H1.5/16				

 $<sup>^{*}</sup>$ 1. Some AWG14 wires exceed 2.0 mm $^{2}$  and cannot be used in the screwless clamping terminal block.

When you use any ferrules other than those in the above table, crimp them to the twisted wires so that the following processed dimensions are achieved.



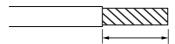
## Using Twisted Wires/Solid Wires

If you use twisted wires or solid wires, use the following table to determine the correct wire specifications.

Termi	Terminals		Wire type				Conductor
Classifica-	Current	Twisted wires		Solid wire		Wire size	length (strip-
tion	capacity	Plated	Unplated	Plated	Unplated		ping length)
All terminals	2 A max.	Possible	Possible	Possible	Possible	0.08 to 1.5	8 to 10 mm
except	Greater	]		Possible	Not possi-	mm <sup>2</sup> (AWG	
ground	than 2 A			*1	ble	28 to 16)	
terminals	and 4 A or					•	
	less						
	Greater	Possible *1	Not pos-	Not pos-			
	than 4 A		sible	sible			
Ground		Possible	Possible	Possible	Possible*2	2.0 mm <sup>2</sup>	9 to 10 mm
terminals				*2			

<sup>\*1.</sup> Secure wires to the screwless clamping terminal block. Refer to Securing Wires on page 4-21 for how to secure wires.

<sup>\*2.</sup> With the NX-TB \underset 1 Terminal Block, use twisted wires to connect the ground terminal. Do not use a solid

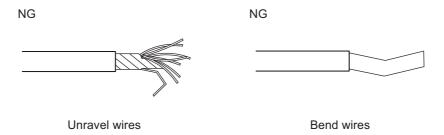


Conductor length (stripping length)



#### **Precautions for Correct Use**

- Use cables with suitable wire sizes for the carrying current. There are also restrictions on the current due to the ambient temperature. Refer to the manuals for the cables and use the cables correctly for the operating environment.
- · For twisted wires, strip the sheath and twist the conductor portion. Do not unravel or bend the conductor portion of twisted wires or solid wires.





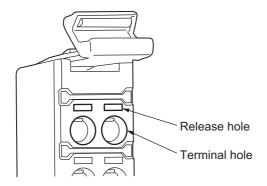
#### **Additional Information**

If more than 2 A will flow on the wires, use plated wires or use ferrules.

# Connecting/Removing Wires

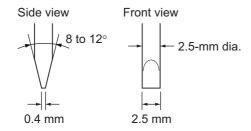
This section describes how to connect and remove wires.

## Terminal Block Parts and Names



## Required Tools

Use a flat-blade screwdriver to connect and remove wires. Use the following flat-blade screwdriver.



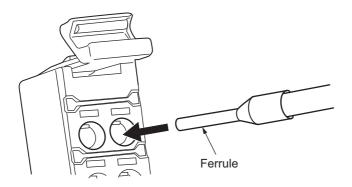
Recommended screwdriver

Model	Manufacturer			
SZF 0-0,4×2,5	Phoenix Contact			

## Connecting Ferrules

Insert the ferrule straight into the terminal hole.

It is not necessary to press a flat-blade screwdriver into the release hole.



After you make a connection, make sure that the ferrule is securely connected to the terminal block.

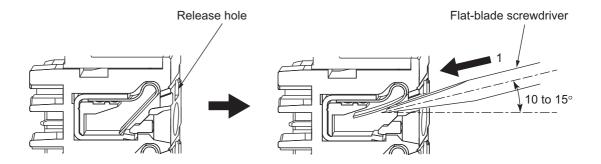
## Connecting Twisted Wires/Solid Wires

Use the following procedure to connect the twisted wires or solid wires to the terminal block.

Press a flat-blade screwdriver diagonally into the release hole.

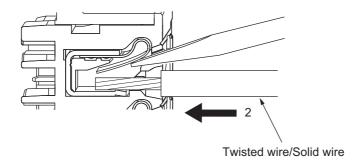
Press at an angle of 10° to 15°.

If you press in the screwdriver correctly, you will feel the spring in the release hole.

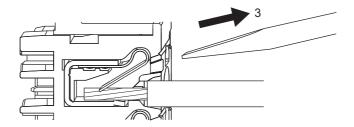


**2** Leave the flat-blade screwdriver pressed into the release hole and insert the twisted wire or the solid wire into the terminal hole.

Insert the twisted wire or the solid wire until the stripped portion is no longer visible to prevent shorting.



**3** Remove the flat-blade screwdriver from the release hole.

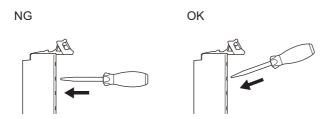


After you make a connection, make sure that the twisted wire or the solid wire is securely connected to the terminal block.

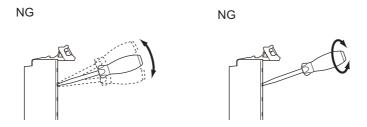


## **Precautions for Safe Use**

• Do not press the flat-blade screwdriver straight into the release hole. Doing so may break the terminal block.



- When you insert a flat-blade screwdriver into a release hole, press it down with a force of 30 N max. Applying excessive force may damage the terminal block.
- Do not tilt or twist the flat-blade screwdriver while it is pressed into the release hole. Doing so may break the terminal block.



- · Make sure that all wiring is correct.
- Do not bend the cable forcibly. Doing so may sever the cable.

## Securing Wires

It is necessary to secure wires to the screwless clamping terminal block depending on the wire types that are used or the current flows on the wires.

The following table gives the necessity for securing wires.

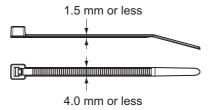
Terminals		Wire type				
			Twisted wires		Solid wire	
Classifica- tion	Current capacity	Ferrule	Plated	Unplated	Plated	Unplated
Allterminals	2 A max.	No	No	No	No	No
except	Greater than	]		Not Possible	Yes	Not Possible
ground	2 A and 4 A or					
terminals	less					
	Greater than		Yes		Not Possible	
	4 A					
Ground			No	No	No	No
terminals						

Use the following procedure to secure the wires.

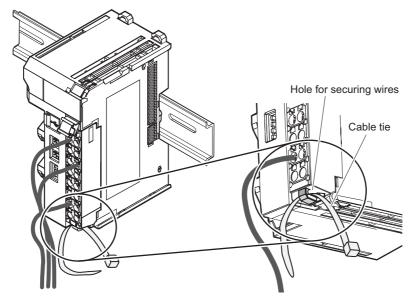
Prepare a cable tie.

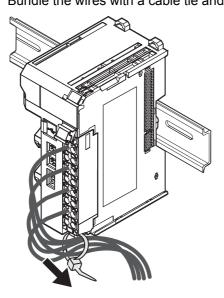
A cable tie can be used with a width of 4 mm or less and a thickness of 1.5 mm or less.

Select a cable tie correctly for the operating environment.

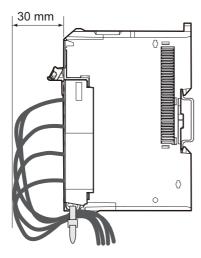


**2** Pass a cable tie through the hole for securing wires on the bottom of the screwless clamping terminal block.





Secure wires within the range of 30 mm from the screwless clamping terminal block.



## Removing Wires

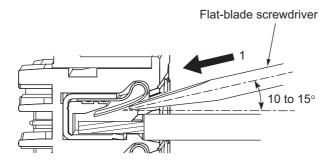
Use the following procedure to remove the wires from the terminal block.

The removal method is the same for ferrules, twisted wires, and solid wires.

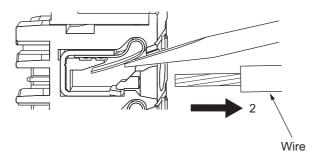
If wires are secured firmly to the terminal block, release them first.

**1** Press the flat-blade screwdriver diagonally into the release hole. Press at an angle of 10° to 15°.

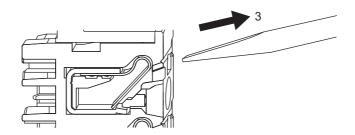
If you press in the screwdriver correctly, you will feel the spring in the release hole.



**2** Leave the flat-blade screwdriver pressed into the release hole and pull out the wire.



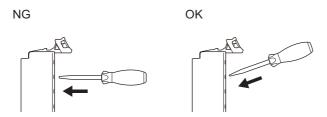
**3** Remove the flat-blade screwdriver from the release hole.



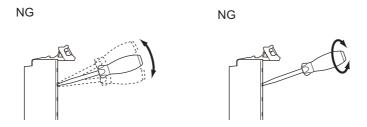


## **Precautions for Safe Use**

• Do not press the flat-blade screwdriver straight into the release hole. Doing so may break the terminal block.



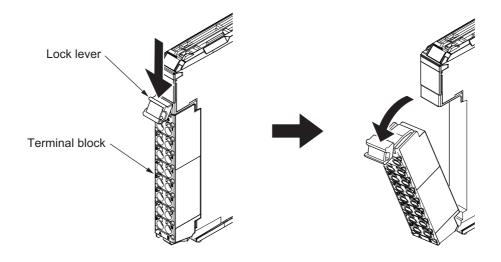
- When you insert a flat-blade screwdriver into a release hole, press it down with a force of 30 N max. Applying excessive force may damage the terminal block.
- Do not tilt or twist the flat-blade screwdriver while it is pressed into the release hole. Doing so may break the terminal block.



- · Make sure that all wiring is correct.
- Do not bend the cable forcibly. Doing so may sever the cable.

# Removing a Terminal Block

1 Press the lock lever on the terminal block and pull out the top of the terminal block to remove it.

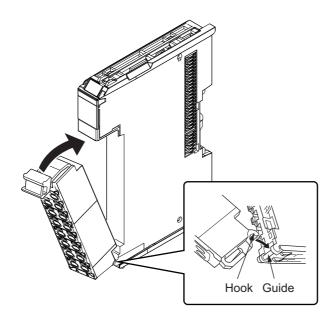


## **Attaching a Terminal Block**

Mount the terminal block hook on the guide at the bottom of the NX Unit, lift up the terminal block, and press in on the top of the terminal block until you hear it engage.

The terminal block will click into place on the Unit.

After you mount the terminal block, make sure that it is locked to the Unit.



Mount a terminal block that is applicable to each Unit model.

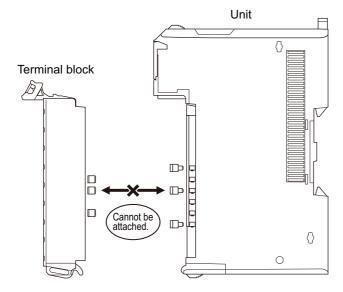
Refer to Applicable Terminal Blocks for Each Unit Model on page 3-6 for the applicable terminal blocks.

## **Preventing Incorrect Attachment of Terminal Blocks**

In order to prevent unintentionally installing the wrong terminal block, you can limit the combination of a Unit and a terminal block.

Insert three Coding Pins (NX-AUX02) into three of the six incorrect attachment prevention holes on the Unit and on the terminal block. Insert these pins into positions so that they do not interfere with each other when the Unit and terminal block are connected to each other.

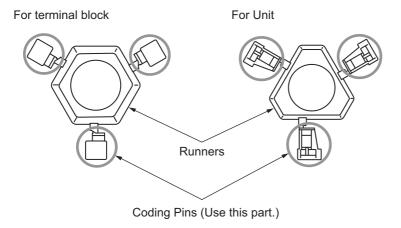
You can use these pins to create a combination in which the wrong terminal block cannot be attached because the pin patterns do not match.



## • Types of Coding Pins

There are two types of Coding Pins, both with their own unique shape: one for terminal blocks and one for Units.

Three pins come with each runner.



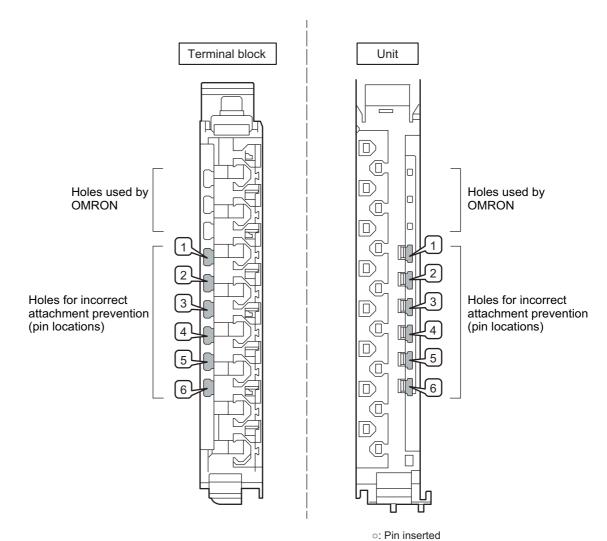
Use the following Coding Pins.

Name	Model	Specification
Coding Pin	NX-AUX02	For 10 Units
		(Terminal block: 30 pins, Unit: 30 pins)

## • Insertion Locations and Patterns of Coding Pins

Insert three Coding Pins of each on the terminal block and on the Unit at the positions designated by the numbers 1 through 6 in the figure below.

As shown in the following table, there are 20 unique pin patterns that can be used.



o. i ili moorted												
Pattern	Pin locations for terminal block				Pin locations for Unit							
	1	2	3	4	5	6	1	2	3	4	5	6
No.1	0	0	0							0	0	0
No.2	0	0		0					0		0	0
No.3	0	0			0				0	0		0
No.4	0	0				0			0	0	0	
No.5	0		0	0				0			0	0
No.6	0		0		0			0		0		0
No.7	0		0			0		0		0	0	
No.8	0			0	0			0	0			0
No.9	0			0		0		0	0		0	
No.10	0				0	0		0	0	0		
No.11		0	0	0			0				0	0
No.12		0	0		0		0			0		0
No.13		0	0			0	0			0	0	
No.14		0		0	0		0		0			0
No.15		0		0		0	0		0		0	
No.16		0			0	0	0		0	0		
No.17			0	0	0		0	0				0
No.18			0	0		0	0	0			0	
No.19			0		0	0	0	0		0		
No 20				0	0	0	0	0	0			

To make the maximum of 20 patterns, purchase two sets of NX-AUX02 Pins. (One set for 10 Units.)



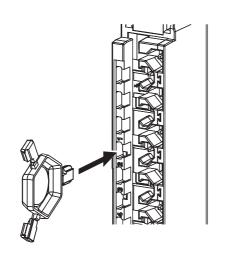
#### **Precautions for Correct Use**

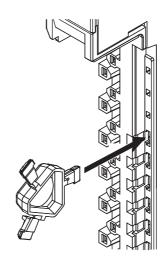
- OMRON uses the holes other than No. 1 to 6 in the figure on the previous page. If you insert a Coding Pin into one of the holes used by OMRON on the terminal block side, this makes it impossible to mount the terminal block on a Unit.
- · Do not use Coding Pins that have been attached and removed.

### Inserting the Coding Pins

Hold the pins by the runner and insert a pin into one of the incorrect attachment prevention holes on the terminal block or on the Unit.

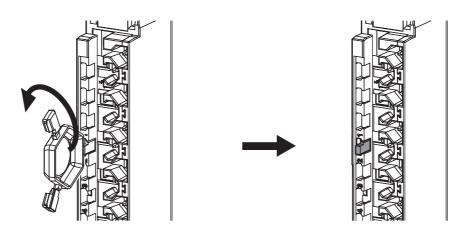
Terminal block Unit

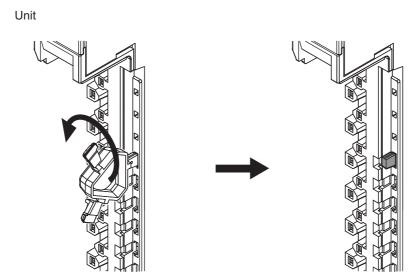




Rotate the runner to break off the Coding Pin.

Terminal block





#### Wiring to M3 Screw Terminal Block 4-3-2

This section describes how to connect wires to the M3 screw terminal block, and the installation and removing methods.

## **Wiring Terminals**

The terminals to be wired are as follows.

- · I/O power supply terminals
- I/O terminals

## **Applicable Wires**

Connect the wires that have crimp terminals to the M3 screw terminal block.

#### Electric Wires

• The following wire gauges are recommended.

Terminal Block Connector	Wire Size
18-terminal	AWG 22 to 18 (0.32 to 0.82 mm <sup>2</sup> )

· The current capacity of electric wire depends on factors such as the ambient temperature and insulation as well as the gauge of the conductor.

## Terminal Screws and Crimp Terminals

- The terminals on the I/O Unit are M3, self-raising terminals with screws.
- Use crimp terminals (M3) having the dimensions shown below.



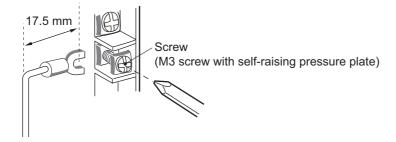


#### **Precautions for Safe Use**

Use crimp terminals for wiring the M3 screw terminal blocks. Do not connect bare stranded wires directly to the M3 screw terminal blocks.

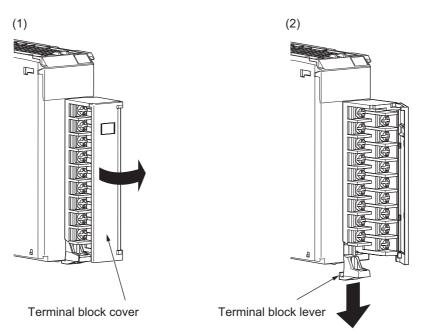
## Connecting/Removing Wires

- · Make sure that all Units are connected properly.
- Do not allow wire clippings, shavings, or other foreign material to enter any Unit during wiring.
- · Wire the Units so that they can be easily replaced.
- · Make sure that the I/O indicators are not covered by the wiring.
- Do not place the wiring for I/O Units in the same duct or raceway as power lines. Inductive noise can cause errors in operation.
- Tighten the terminal screws to the torque of 0.5 N·m.

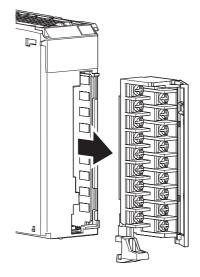


## Removing a Terminal Block

- Release the lock of the terminal block.
  - (1) Pull the terminal block cover forward to open the cover.
  - (2) Pull the terminal block lever downward. Support the NX Unit firmly while performing the operation of the terminal block lever.

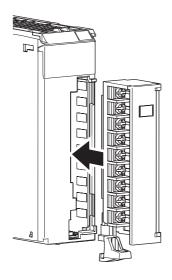


Pull out the terminal block straight forward to remove.

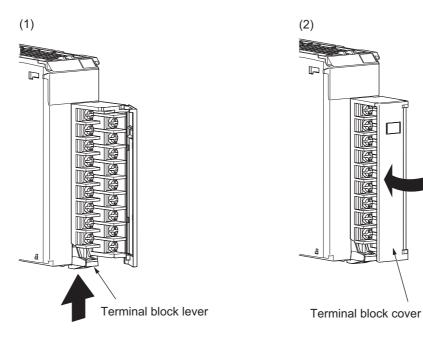


# Attaching a Terminal Block

1 Insert the terminal block straight into the NX Unit all the way.



- 2 Lock the terminal block.
  - (1) Push in the terminal block lever upward.
  - (2) Close the terminal block cover if it is still open.



#### 4-3-3 Wiring to MIL/Fujitsu Connectors

This section describes wiring for the Digital I/O Units with connectors.

Depending on the connector, the following methods are used to connect the Digital I/O Units with connectors to external I/O devices.

- Use an OMRON Connecting Cable (equipped with a special connector) to connect to a terminal block or relay terminal.
- Use a special connector and make your own cable.



#### **Precautions for Safe Use**

- · Do not apply voltages that exceed the rated value to any Input Unit.
- Do not apply voltages or connect loads to the Output Units or slaves in excess of the maximum ratings.
- · Turn ON the power after checking the connector's wiring.
- · Do not pull the cable. Doing so will damage the cable.
- · Bending the cable too sharply can damage or break wiring in the cable.
- · If the external power supply has polarity, connect it with the correct polarity. If the polarity is reversed, current may flow in the reverse direction and damage the connected devices regardless of the operation of the Unit.



#### **Additional Information**

The Digital I/O Units with 32 points and Fujitsu connectors have the same connector pin allocations as the C200H High-density I/O Units, CS-series I/O Units with connectors and CJ-series I/O Units with connectors to make them compatible.

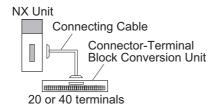
## Connecting to Connector-Terminal Block Conversion Units or I/O **Relay Terminals**

OMRON Connecting Cable can be used to connect Digital I/O Units with connectors to OMRON Connector-Terminal Block Conversion Units or to OMRON I/O Relay Terminals.

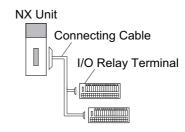
For details, refer to A-3 Connecting Connector-Terminal Block Conversion Units and I/O Relay Terminals on page A-107.

#### Connection Examples

Connector-Terminal Block Conversion Unit



I/O Relay Terminals



# Using User-made Cables with Connector

#### Available Connectors

Use the following connectors when assembling a connector and cable.

NX Units with MIL Connectors

Model	Specifications	Pins
NX-ID5142-5	DC Input Unit, 16 points	20
NX-ID6142-5	DC Input Unit, 32 points	40
NX-OD5121-5	Transistor Output Unit, 16 points	20
NX-OD5256-5		
NX-OD6121-5	Transistor Output Unit, 32 points	40
NX-OD6256-5		
NX-MD6121-5	DC Input/Transistor Output Units, 16 inputs, 16	20 (× 2)
NX-MD6256-5	outputs	

#### Applicable Cable-side Connectors

Connection	Pins	OMRON set	DDK parts
Pressure-welded	40	XG4M-4030-T	FRC5-A040-3TOS
	20	XG4M-2030-T	FRC5-A020-3TOS
Crimped	40	XG5N-401	
	20	XG5N-201	

#### NX Units with Fujitsu Connectors

Model	Specifications	Pins
NX-ID6142-6	DC Input Unit, 32 points	40
NX-OD6121-6	Transistor Output Unit, 32 points	
NX-MD6121-6	DC Input/Transistor Output Units, 16 inputs, 16 outputs	24 (× 2)

### Applicable Cable-side Connectors

Connection	Pins	OMRON set	Fujitsu parts
Solder-type	40	C500-CE404	Socket: FCN-361J040-AU
			Connector cover: FCN-360C040-J2
	24	C500-CE241	Socket: FCN-361J024-AU
			Connector cover: FCN-360C024-J2
Crimped	40	C500-CE405	Socket: FCN-363J040
			Connector cover: FCN-360C040-J2
			Contacts: FCN-363J-AU
	24	C500-CE242	Socket: FCN-363J024
			Connector cover: FCN-360C024-J2
			Contacts: FCN-363J-AU
Pressure-welded	40	C500-CE403	FCN-367J040-AU/F
	24	C500-CE243	FCN-367J024-AU/F

#### Wire Size

We recommend using cable with wire gauges of AWG 24 or AWG 28 (0.2 mm<sup>2</sup> to 0.08 mm<sup>2</sup>). Use cable with external wire diameters of 1.61 mm max.

### Wiring

NX Units with MIL Connectors

- · Make sure that all Units are connected properly.
- · After the cable side connector is connected, close the lock lever on the NX Unit side connector section to lock it. After you complete the wiring, make sure that the connector is locked.

NX Units with Fujitsu Connectors

Check that each Unit is installed securely.

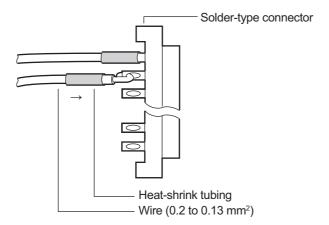


#### **Precautions for Correct Use**

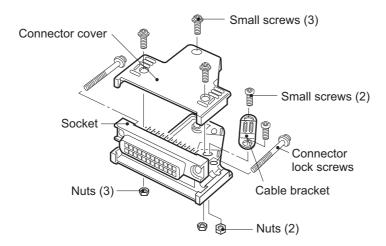
Do not force the cables.

When solder-type connectors are being used, be sure not to accidentally short adjacent termi-

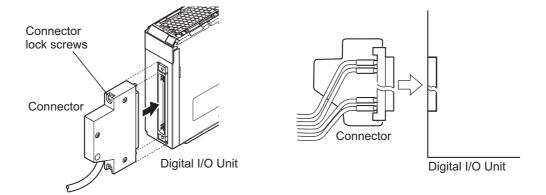
Cover the solder joint with heat-shrink tubing.



**3** Assemble the connector (purchased separately).



**4** Mount the connector on the Digital I/O Unit and fix it in place with lock screws. Tighten the connector lock screws to a torque of 0.2•m.



#### 4-3-4 **Checking the Wiring**

Check the wiring by reading input data or writing output data from Slave Terminals using the Watch Tab Page of the Support Software.

For Input Units, you can turn ON/OFF the inputs from external devices that are connected to the target Units and monitor the results.

For Output Units, you can execute the I/O outputs of the target Units and check the operation of the connected external devices.

For details on monitoring and I/O output operations using the Support Software, refer to the operation manual for the Support Software that you are using.



#### **Additional Information**

- If you check the wiring for the Output Units that support output refreshing with specified time stamp, set the value of the Output Bit  $\Box\Box$  Time Stamp parameter to 0. At this time, the Output Units refresh outputs immediately and outputs are refreshed according to the output set values.
- In the Sysmac Studio, you can check the wiring from the I/O Map or Watch Tab Page. If you use the I/O Map, you can also monitor and perform forced refreshing even if the variables are not defined or the algorithms are not created. Therefore, you can easily check the wiring. Refer to the Sysmac Studio Version 1 Operation Manual (Cat. No. W504) for details on monitoring and forced refreshing operations.
- Some Communications Coupler Units support I/O checking that allows you to check wiring with only the Slave Terminal. Refer to the user's manual of the Communications Coupler Unit for detailed information on the support and functionality of I/O checking for your Communications Coupler Unit.

# 4-4 Wiring Examples

This section gives some wiring examples for the Digital I/O Units and precautions for wiring.

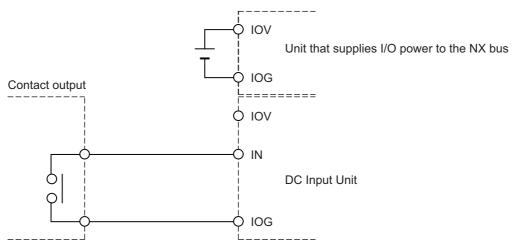
For the terminal array for each model, refer to the terminal connection diagram for each model in *A-1 Data Sheet* on page A-3.

## 4-4-1 Wiring the Input Units

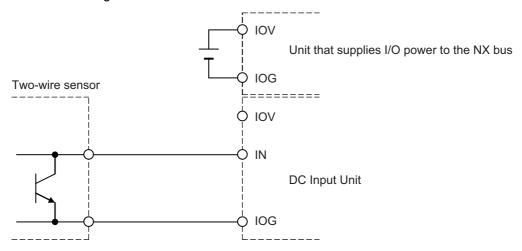
# Wiring to the DC Input Units (When I/O Power Is Supplied from the NX Bus)

## NPN Type Input Units

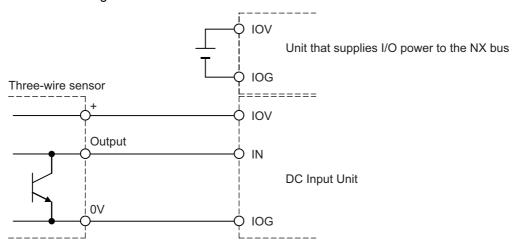
This is the wiring for contact output type external devices.



This is the wiring for two-wire sensors.

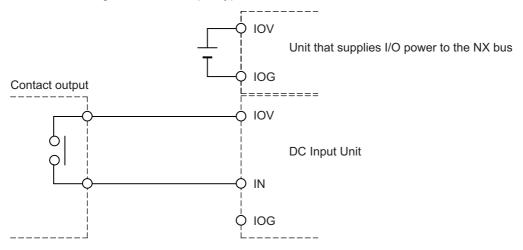


This is the wiring for three-wire sensors.

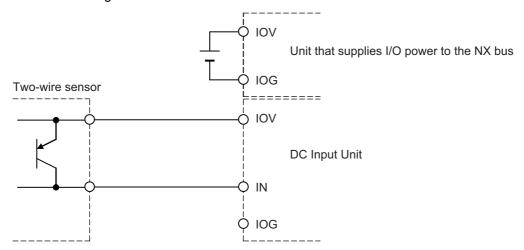


## PNP Type Input Units

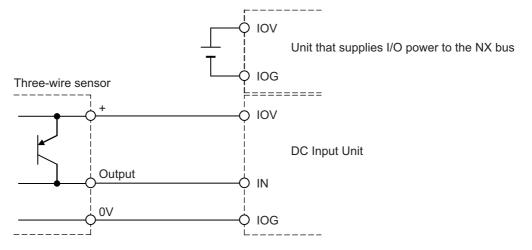
This is the wiring for contact output type external devices.



This is the wiring for two-wire sensors.



This is the wiring for three-wire sensors.



## Precautions when Connecting a Two-wire DC Sensor

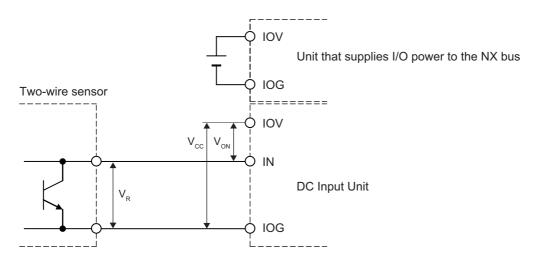
When a two-wire sensor is used with a DC Input Unit, check that the following conditions are met. Failure to meet these conditions may result in operating errors.

(a) Relation between ON voltage of the DC Input Unit and sensor residual voltage

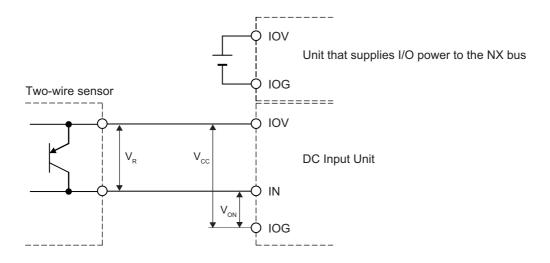
The DC Input Unit cannot detect sensor output ON unless the following conditions are satisfied:

$$V_{ON} \le V_{CC} - V_{R}$$

The voltages related to the conditions for NPN type sensors are shown in the figure below.



The voltages related to the conditions for PNP type sensors are shown in the figure below.



V<sub>CC</sub>: Power supply voltage

V<sub>R</sub>: Sensor's output residual voltage

V<sub>ON</sub>: ON voltage of DC Input Unit

(b) Relation between input current to the DC Input Unit and sensor control output (load current)

The DC Input Unit cannot detect sensor output ON unless the following conditions are satisfied:

$$I_{OUT}$$
 (min)  $\leq I_{in} \leq I_{OUT}$  (max)

 $I_{OLIT}$  (min): Minimum value of load current

I<sub>OUT</sub> (max): Maximum value of load current

Use the following equation to calculate the input current of the resistance input.

$$I_{in} = (V_{CC} - V_{R} - 1.5 \text{ [internal residual voltage of DC Input Unit]}) / R_{IN}$$

Use the following equation to calculate the input current of the constant current input.

$$I_{in} = I_{ON}$$

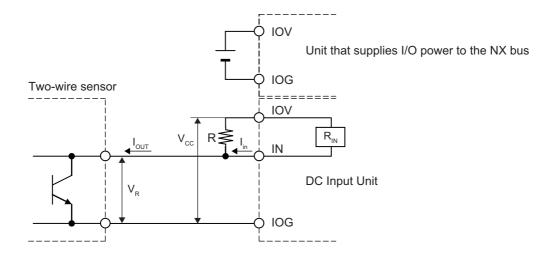
Note For constant current input type Input Units, the input current does not increase linearly for the input voltage. If you gradually raise the input voltage and once the input current reaches I<sub>ON</sub>, the input current does not increase and remains roughly constant even when the input voltage is raised.

When  $I_{in}$  is smaller than  $I_{OUT}$  (min), connect a bleeder resistor R. The bleeder resistor constant can be calculated as follows: Select an appropriate bleeder resistor R so that both equations can be satisfied.

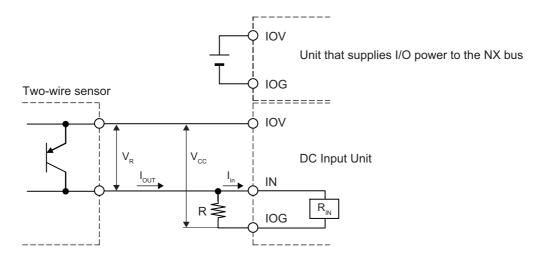
$$R \le (V_{CC} - V_R) / (I_{OUT} (min) - I_{ON})$$

Rated power W of bleeder resistor  $\geq (V_{CC} - V_{R})^{2} / R \times 4$  [allowable margin]

The voltages and currents related to the conditions for NPN type sensors are shown in the figure below.



The voltages and currents related to the conditions for PNP type sensors are shown in the figure below.



V<sub>CC</sub>: Power supply voltage

 $V_R$ : Sensor's output residual voltage

I<sub>OUT</sub>: Sensor control output (load current)

 $I_{ON}$ : Input current of DC Input Unit (Input current when the rated voltage is applied)

R: Bleeder resistor

R<sub>IN</sub>: Input resistor of DC Input Unit

(c) Relation between OFF current of the DC Input Unit and sensor leakage current

The DC Input Unit cannot detect sensor output OFF unless the following conditions are satisfied:

When  $I_{leak}$  is greater than  $I_{OFF}$ , connect a bleeder resistor R.

Use the following equation to calculate the bleeder resistance constant of the resistance input.

$$R \le R_{IN} \times V_{OFF} / (I_{leak} \times R_{IN} - V_{OFF})$$

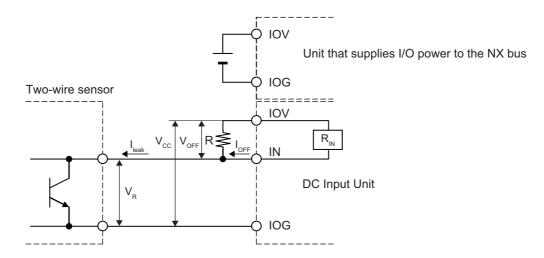
Use the following equation to calculate the bleeder resistance constant of the constant current input.

$$R \le (V_{OFF} / I_{OFF}) \times V_{OFF} / (I_{leak} \times (V_{OFF} / I_{OFF}) - V_{OFF})$$

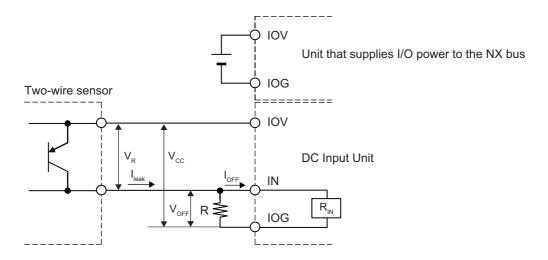
For both the resistance input and constant current input, use the following equation to calculate the rated power of bleeder resistor.

Rated power W of bleeder resistor  $\geq (V_{CC} - V_{R})^2 / R \times 4$  [allowable margin]

The voltages and currents related to the conditions for NPN type sensors are shown in the figure below.



The voltages and currents related to the conditions for PNP type sensors are shown in the figure below.



 $V_{CC}$ : Power supply voltage

V<sub>P</sub>: Sensor's output residual voltage

V<sub>OFF</sub>: OFF voltage of DC Input Unit

I<sub>leak</sub>: Sensor leakage current

R: Bleeder resistor

I<sub>OFF</sub>: OFF current of DC Input Unit

R<sub>IN</sub>: Input resistor of DC Input Unit

#### (d) Precautions on sensor inrush current

An incorrect input may occur due to sensor inrush current if a sensor is turned ON after the DC Input Unit has started up to the point where inputs are possible.

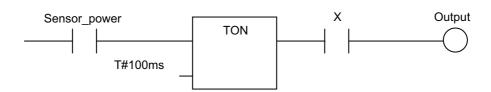
Determine the time required for sensor operation to stabilize after the sensor is turned ON and take appropriate measures, such as inserting an ON delay into the user program after turning ON the sensor.

A programming example is shown below.

The sensor's power supply voltage is used as the input bit to Sensor\_power.

A 100-ms timer delay (the time required for an OMRON Proximity Sensor to stabilize) is created in the user program.

After the timer changes to TRUE, input bit X causes the output Output to change to TRUE after the input of the sensor changes to TRUE.

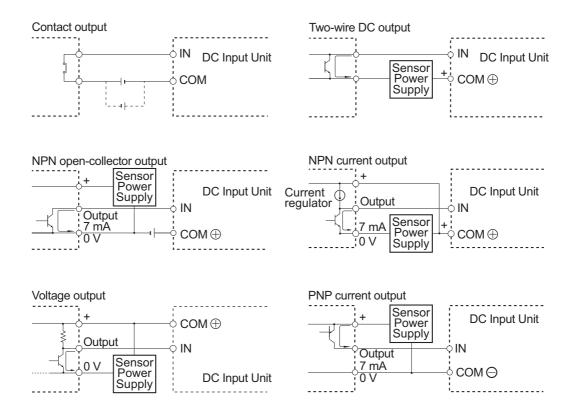


# Wiring to the DC Input Units (When I/O Power Is Supplied from an External Source)

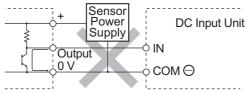
Use the following information for reference when selecting or connecting input devices.

## DC Input Units

The following types of DC input devices can be connected.



• The circuit below should NOT be used for I/O devices having a voltage output.



### Precautions when Connecting a Two-wire DC Sensor

When a two-wire sensor is used with a DC Input Unit, check that the following conditions are met. Failure to meet these conditions may result in operating errors.

(a) Relation between ON voltage of the DC Input Unit and sensor residual voltage

$$V_{ON} \le V_{CC} - V_{R}$$

(b) Relation between input current to the DC Input Unit and sensor control output (load current)

$$I_{OUT}$$
 (min)  $\leq I_{ON} \leq I_{OUT}$  (max)

$$I_{ON} = (V_{CC} - V_{R} - 1.5 \text{ [internal residual voltage of DC Input Unit]}) / R_{IN}$$

When  $I_{ON}$  is smaller than  $I_{OUT}$  (min), connect a bleeder resistor R. The bleeder resistor constant can be calculated as follows:

$$R \le (V_{CC} - V_R) / (I_{OUT}(min) - I_{ON})$$

Power W of bleeder resistor ≥  $(V_{CC} - V_R)^2 / R \times 4$  [allowable margin]

V<sub>CC</sub>: Input voltage of DC Input Unit

V<sub>R</sub>: Sensor's output residual voltage

I<sub>ON</sub>: Input current of DC Input Unit

I<sub>OUT</sub>: Sensor control output (load current)

R<sub>IN</sub>: Input resistor of DC Input Unit

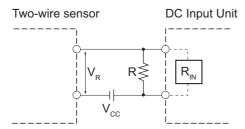
(c) Relation between OFF current of the DC Input Unit and sensor leakage current

When  $I_{leak}$  is greater than  $I_{OFF}$ , connect a bleeder resistor R.

Use the following equation to calculate the bleeder resistance constant.

$$R \le R_{IN} \times V_{OFF} / (I_{leak} \times R_{IN} - V_{OFF})$$

Power W of bleeder resistor  $\geq (V_{CC} - V_R)^2 / R \times 4$  [allowable margin]



V<sub>CC</sub>: Power supply voltage

 $V_{ON}$ : ON voltage of DC Input Unit

 $V_{\mathsf{OFF}}$ : OFF voltage of DC Input Unit

I<sub>ON</sub>: ON current of DC Input Unit

 $I_{\mathrm{OFF}}$ : OFF current of DC Input Unit

R<sub>IN</sub>: Input resistor of DC Input Unit

V<sub>R</sub>: Sensor's output residual voltage

I<sub>OUT</sub>: Sensor control output (load current)

I<sub>leak</sub>: Sensor leakage current

R: Bleeder resistor

#### (d) Precautions on sensor inrush current

An incorrect input may occur due to sensor inrush current if a sensor is turned ON after the DC Input Unit has started up to the point where inputs are possible.

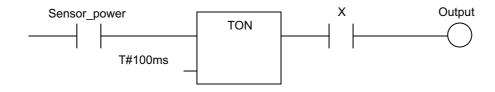
Determine the time required for sensor operation to stabilize after the sensor is turned ON and take appropriate measures, such as inserting an ON delay into the user program after turning ON the sensor.

A programming example is shown below.

The sensor's power supply voltage is used as the input bit to Sensor\_power.

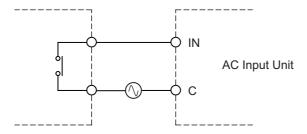
A 100-ms timer delay (the time required for an OMRON Proximity Sensor to stabilize) is created in the user program.

After the timer changes to TRUE, input bit *X* causes the output *Output* to change to TRUE after the input of the sensor changes to TRUE.

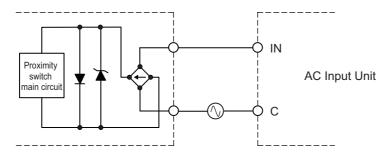


## Wiring to the AC Input Units

## Contact Output



## AC Switching





#### **Precautions for Safe Use**

If you use reed switches for the input contacts for AC Input Units, use switches with an allowable current of 1 A or greater. If the capacity of the reed switches is too low, inrush current may fuse the contacts.

## 4-4-2 Precautions when Wiring to the Input Units

## **Countermeasures to Reduce the Effects of Noise**

If you use an Input Unit without the input filter, or an Input Unit with an input filter value smaller than the default, an incorrect input is likely to occur due to the effects of external noise. In such cases, use a shield wire between the external device and the Input Unit, and then ground the end of the shield on the Input Unit side to improve noise immunity.

Use the following shield wire depending on the specifications of the external device:

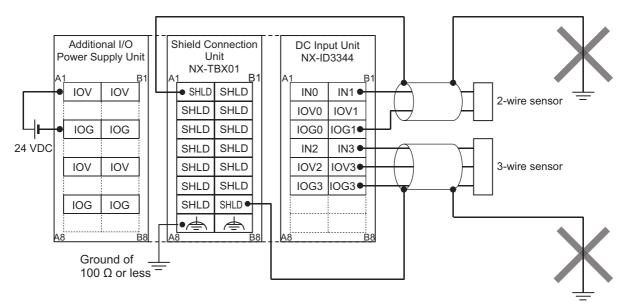
- Connection to a two-wire sensor: Shield wire (2 conductors, twisted wire)
- Connection to a three-wire sensor: Shield wire (3 conductors)

However, do not connect the end of the shield anywhere on the external device. If you ground the shield on both the Input Unit side and the external device side, the Unit becomes susceptible to noise induced due to ground loops.

You can use the NX-TBX01 Shield Connection Unit to ground more than one shield.

The following is a wiring example where an NX-ID3344 is used.

Do not ground the shield on the sensor side.

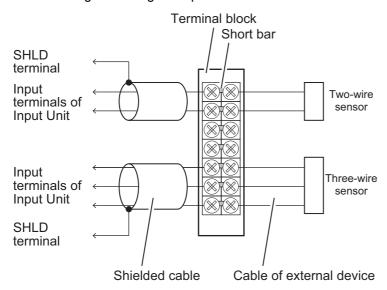


Connect the shield of the cable to the SHLD terminal on the Shield Connection Unit.

And ground the functional ground terminal of the Shield Connection Unit to 100  $\Omega$  or less.

If the cable for the external device to use is not shielded, use a commercially available terminal block or the like to connect the external cable and the shielded cable.

The following is a wiring example.





#### **Precautions for Correct Use**

To ensure this NX Unit is kept in the best operating condition, observe the following points when wiring to avoid the effects of the noise.

- Wire the input connection lines and power lines (e.g., AC power supply lines or power lines) separately. Do not place such lines in the same duct.
- Insert a noise filter into the power supply input section if noise comes from power supply lines when using the same power supply to power an electrical welder or an electric discharge machine, or there is a high-frequency source nearby.

## 4-4-3 Precautions when Wiring to the Output Units

## **Output Short-circuit Protection**

If a load connected to the output terminals is short-circuited, output components and printed circuit boards may be damaged. To guard against this, use the NX Units with load short-circuit protection.

When using the NX Units without load short-circuit protection, incorporate a protective fuse in the external circuit. Use a fuse with a capacity of around twice the rated output.

## **Inrush Current**

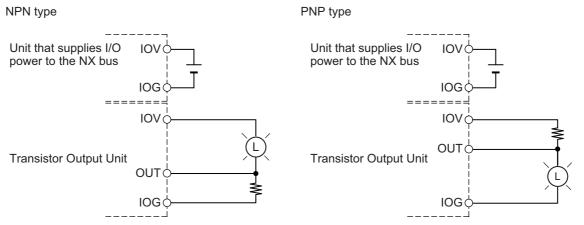
When connecting a transistor to an output device with a high inrush current (such as an incandescent lamp), steps must be taken to avoid damage to the output transistor.

Use either of the following methods to reduce the inrush current.

#### Countermeasure 1

Draw about 1/3 of the current consumed by the load.

When I/O power is supplied from the NX bus, the method is as shown in the following figure.

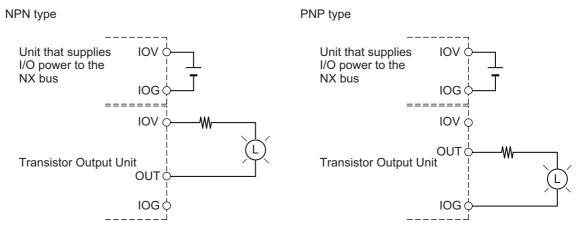


When I/O power is supplied from an external source, the method is as shown in the following figure.

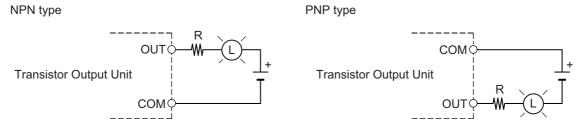
#### Countermeasure 2

Mount a limiting resistor.

When I/O power is supplied from the NX bus, the method is as shown in the following figure.



When I/O power is supplied from an external source, the method is as shown in the following figure.



In countermeasure 1, the current consumption from I/O power supply is increased although the voltage supplied to the load L is not decreased.

In countermeasure 2, the voltage supplied to the load L is decreased although the current consumption from I/O power supply is not increased.

Select the appropriate countermeasures according to the operating conditions.

# I/O Refreshing

This section describes the types and functions of I/O refreshing for the NX Units.

5-1	I/O Ref	freshing	5-2
	5-1-1	I/O Refreshing from CPU Units to NX Units	5-2
	5-1-2	I/O Refreshing from CPU Units or Industrial PCs to Slave Terminal	5-3
	5-1-3	I/O Refreshing from the Communication Control Unit to NX Units	5-5
	5-1-4	Calculating the I/O Response Times of NX Units	5-5
5-2	I/O Ref	freshing Methods	5-6
	5-2-1	Types of I/O Refreshing Methods	5-6
	5-2-2	Setting the I/O Refreshing Methods	5-8
	5-2-3	Selecting NX Units	5-9
	5-2-4	Free-Run Refreshing	5-9
	5-2-5	Synchronous Input Refreshing	5-13
	5-2-6	Synchronous Output Refreshing	5-17
	5-2-7	Time Stamp Refreshing	5-20
	5-2-8	Input Refreshing with Input Changed Time	5-21
	5-2-9	Output Refreshing with Specified Time Stamp	5-28
	5-2-10	An Example of Turning ON Outputs at Specific Times After the Sensor Inputs Change	5-34

# I/O Refreshing

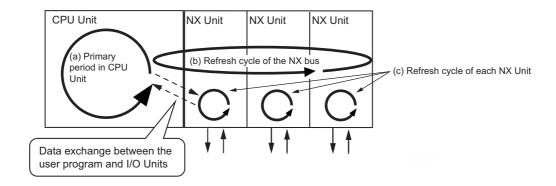
This section describes I/O refreshing for NX Unit.

#### 5-1-1 I/O Refreshing from CPU Units to NX Units

An NX-series CPU Unit cyclically performs I/O refreshing with the NX Units.

The following period and two cycles affect operation of the I/O refreshing between the CPU Unit and the NX Units.

- (a) Primary period in CPU Unit
- (b) Refresh cycle of the NX bus
- (c) Refresh cycle of each NX Unit



The following operation occurs.

- · The refresh cycle of the NX bus in item (b) is automatically synchronized with the primary period of the CPU Unit in item (a).
- The refresh cycle of each NX Unit in item (c) depends on the I/O refreshing method which is given below.

Refer to the NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501) for detailed information on I/O refreshing between the CPU Unit and the NX Units.

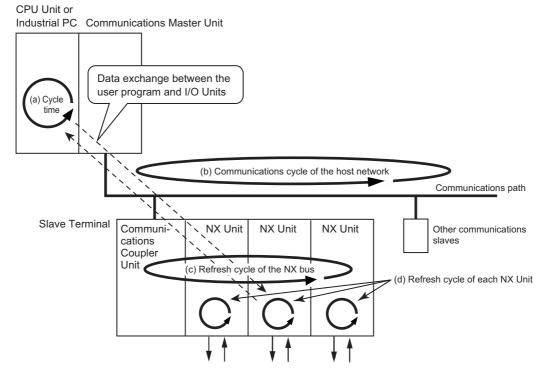
Refer to 5-1-4 Calculating the I/O Response Times of NX Units on page 5-5 for the I/O response times of NX Units in the CPU Rack of the CPU Unit.

# 5-1-2 I/O Refreshing from CPU Units or Industrial PCs to Slave Terminal

The CPU Unit or Industrial PC cyclically performs I/O refreshing with the Slave Terminal through the Communications Master and Communications Coupler Units.

The following four cycles affect operation of the I/O refreshing between the NX Unit on a Slave Terminal and the CPU Unit or Industrial PC.

- (a) Cycle time of the CPU Unit or Industrial PC
- (b) Communications cycle of the host network
- (c) Refresh cycle of the NX bus
- (d) Refresh cycle of each NX Unit



The cycle time of the CPU Unit or Industrial PC and communications cycle of the host network and the I/O refresh cycle of the NX bus are determined by the CPU Unit or Industrial PC types and the communications types.

The following explains operations when the built-in EtherCAT port on the NJ/NX-series CPU Unit or NY-series Industrial PC is used for communications with an EtherCAT Slave Terminal, with symbols in the figure.

Refer to the user's manual for the connected Communications Coupler Unit for details on the operation of I/O refreshing on Slave Terminals other than EtherCAT Slave Terminals.

## Operation of I/O Refreshing with NX-series CPU Units

The following shows the operation of I/O refreshing when the built-in EtherCAT port on the NX-series CPU Unit is used for communications with an EtherCAT Slave Terminal.

- The process data communications cycle in item (b) and the refresh cycle of the NX bus in item (c) are automatically synchronized with the primary period or the task period of the priority-5 periodic task of the CPU Unit in item (a).\*1
- The refresh cycle of each NX Unit in item (d) depends on the I/O refreshing method which is given below.
- \*1. This applies when the distributed clock is enabled in the EtherCAT Coupler Unit.

The priority-5 periodic task must be supported by the connected CPU Unit model. Refer to the NJ/NX-series CPU Unit Software User's Manual (Cat. No. W501) for information on the periodic tasks supported by each NX-series CPU Unit model.

## Operation of I/O Refreshing with NJ-series CPU Units or NY-series **Industrial PCs**

The following shows the operation of I/O refreshing when the built-in EtherCAT port on the NJ-series CPU Unit or NY-series Industrial PC is used for communications with an EtherCAT Slave Terminal.

- The process data communications cycle in item (b) and the refresh cycle of the NX bus in item (c)<sup>\*1</sup> are automatically synchronized with the primary period of the CPU Unit or Industrial PC in item (a).
- The refresh cycle of each NX Unit in item (d) depends on the I/O refreshing method which is given below.
- \*1. This applies when the distributed clock is enabled in the EtherCAT Coupler Unit.

Refer to the NX-series EtherCAT Coupler Unit User's Manual (Cat. No. W519) for detailed information on I/O refreshing between the built-in EtherCAT port and EtherCAT Slave Terminals.

Refer to 5-1-4 Calculating the I/O Response Times of NX Units on page 5-5 for the I/O response times of NX Units on Slave Terminals.

## 5-1-3 I/O Refreshing from the Communication Control Unit to NX Units

Refer to the user's manual for the Communication Control Unit for details on I/O refreshing from the Communication Control Unit to NX Units.

# 5-1-4 Calculating the I/O Response Times of NX Units

Depending on where the NX Unit is connected, refer to the following manuals to calculate the I/O response times of an NX unit.

# Connected to a CPU Unit

Manual to reference	Description
Software user's manual for the con-	The method for calculating the I/O response times of NX Units in the
nected CPU Unit	CPU Rack with a CPU Unit is described.
NX-series Data Reference Manual	The NX Unit parameter values used for calculating the I/O response times of NX Units are described.

# **Connected to a Communications Coupler Unit**

Manual to reference	Description
User's manual for the connected Com- The method for calculating the I/O response times of NX	
munications Coupler Unit	Slave Terminals is described.
NX-series Data Reference Manual	
	times of NX Units are described.

# **Connected to a Communication Control Unit**

Manual to reference	Description
User's manual for the connected Com-	The method for calculating the I/O response times of NX Units in the
munication Control Unit	CPU Rack with a Communication Control Unit is described.
NX-series Data Reference Manual	The NX Unit parameter values used for calculating the I/O response
	times of NX Units are described.

### **5-2** I/O Refreshing Methods

This section describes I/O refreshing methods for the NX Units.

#### Types of I/O Refreshing Methods 5-2-1

# Methods of I/O Refreshing between the CPU Unit and NX Units

The I/O refreshing methods that you can use between the CPU Unit and the NX Units depend on the connected CPU Unit.

Refer to the software user's manual for the connected CPU Unit for information on the I/O refreshing methods that you can use between the CPU Unit and the NX Units.

As an example, the I/O refreshing methods that you can use between the NX-series NX1P2 CPU Unit and the NX Units are shown below.

I/O refreshing method name*1	Outline of operation		
Free-Run refreshing	With this I/O refreshing method, the refresh cycle of the NX bus and I/O		
	refresh cycles of the NX Units are asynchronous.		
Synchronous I/O refreshing	With this I/O refreshing method, the timing to read inputs or to refresh out-		
	puts is synchronized on a fixed interval between more than one NX Unit con-		
	nected to a CPU Unit.		
Time stamp refreshing	With this I/O refreshing method, the NX Units record the DC times when		
	inputs change or perform outputs at specified DC times. These times are		
	asynchronous to the NX bus refresh cycles. Data exchange between the NX		
	Units and CPU Unit are performed cyclically on the NX bus refresh cycles.		
Input refreshing with input	With this I/O refreshing method, the Input Units record the DC times when		
changed time	inputs changed.		
Output refreshing with	With this I/O refreshing method, the Output Units refresh outputs at specified		
specified time stamp	DC times.		

<sup>\*1.</sup> Task period prioritized refreshing cannot be used for the NX1P2 CPU Unit.

Since the NX1P2 CPU Unit can execute all I/O refreshing methods at the same time, you can use NX Units with different I/O refreshing methods together.

# Methods of I/O Refreshing between the Communications Coupler Unit and NX Units

The I/O refreshing methods that you can use between the Communications Coupler Unit and the NX Units depend on the Communications Coupler Unit that is used.

Refer to the user's manual for the connected Communications Coupler Unit for information on the I/O refreshing methods that you can use between the Communications Coupler Unit and the NX Units.

As an example, when an EtherCAT Coupler Unit is connected to the built-in EtherCAT port on an NJ/NX-series CPU Unit or NY-series Industrial PC, the I/O refreshing methods that you can use between the EtherCAT Coupler Unit and the NX Units are shown below.

I/O refreshing method name	Outline of operation
Free-Run refreshing	With this I/O refreshing method, the refresh cycle of the NX bus and the I/O
	refresh cycles of the NX Units are asynchronous.
Synchronous I/O refreshing	With this I/O refreshing method, the timing to read inputs or to refresh out-
	puts is synchronized on a fixed interval between more than one NX Unit on
	more than one Slave Terminal.
Time stamp refreshing	With this I/O refreshing method, the NX Units record the DC times when
	inputs change or perform outputs at specified DC times. These times are
	asynchronous to the NX bus refresh cycles.
	Data exchange between the NX Units and EtherCAT Coupler Unit are per-
	formed cyclically on the NX bus refresh cycles.
Input refreshing with input	With this I/O refreshing method, the Input Units record the DC times when
changed time	inputs changed.
Output refreshing with	With this I/O refreshing method, the Output Units refresh outputs at specified
specified time stamp	DC times.
Task period prioritized refresh-	With this I/O refreshing method, shortening the task period is given priority
ing <sup>*1</sup>	over synchronizing the I/O timing with other NX Units. With this I/O refreshing
-	method, the timing of I/O is not consistent with the timing of I/O for NX Units
	that use synchronous I/O refreshing.

<sup>\*1.</sup> Necessary to use an EtherCAT Coupler Unit NX-ECC203. Task period prioritized refreshing is not supported by Digital I/O Units.

Since the EtherCAT Coupler Unit can execute all I/O refreshing methods at the same time, you can use NX Units with different I/O refreshing methods together in the EtherCAT Slave Terminal.

# Methods of I/O Refreshing between the Communication Control Unit and NX Units

Refer to the user's manual for the connected Communication Control Unit for information on the I/O refreshing methods that you can use between the Communication Control Unit and the NX Units.

#### 5-2-2 Setting the I/O Refreshing Methods

## Setting Methods between the CPU Unit and the NX Units

How to set an I/O refreshing method between the CPU Unit and the NX Units is determined by the connected CPU Unit.

Refer to the software user's manual for the connected CPU Unit for information on how to set an I/O refreshing method between the CPU Unit and the NX Units.

An example of the setting operation for the NX-series NX1P2 CPU Unit is shown below. For the NX1P2 CPU Unit, no setting operation is required, and the method is determined according to the following table.

NX Units that support only Free-Run refreshing	NX Units that support both Free-Run refreshing and synchronous I/O refreshing	NX Units that support Free-Run refreshing, synchronous I/O refreshing, and task period prioritized refreshing	NX Units that support only time stamp refreshing <sup>*1</sup>
Free-Run refreshing	Synchronous I/O refreshing		Time stamp refreshing

<sup>\*1.</sup> Two types of time stamp refreshing are available: one is input refreshing with input changed time and the other is output refreshing with specified time stamp.

### Setting Methods between the Communications Coupler Unit and the **NX Units**

How to set an I/O refreshing method between the Communications Coupler Unit and the NX Units is determined by the connected Communications Coupler Unit.

Refer to the user's manual for the connected Communications Coupler Unit for information on how to set an I/O refreshing method between the Communications Coupler and the NX Units.

An example when the EtherCAT Coupler Unit is connected to the built-in EtherCAT port on an NJ/NX-series CPU or NY-series Industrial PC is shown below.

The I/O refreshing method between the EtherCAT Coupler Unit and each NX Unit depends on whether the DC is enabled in the EtherCAT Coupler Unit.

DC enable setting in the EtherCAT Coupler Unit	NX Units that support only Free-Run refreshing	NX Units that support both Free-Run refreshing and synchronous I/O refreshing	NX Units that support Free-Run refreshing, synchronous I/O refreshing, and task period prioritized refreshing	NX Units that support only time stamp refreshing*1
Enabled (DC for	Free-Run refreshing	Synchronous I/O	Synchronous I/O	Time stamp refresh-
synchronization)*2		refreshing	refreshing	ing
Enabled (DC with			Task period priori-	
priority in cycle			tized refreshing	
time) <sup>*2</sup>				
Disabled		Free-Run refreshing	Free-Run refreshing	Operation with time
(FreeRun)*3				stamp refreshing is
-				not possible.*4

- \*1. Two types of time stamp refreshing are available: one is input refreshing with input changed time and the other is output refreshing with specified time stamp.
- \*2. The EtherCAT Slave Terminal operates in DC Mode.
- \*3. The EtherCAT Slave Terminal operates in Free-Run Mode.
- \*4. Refer to P. 5-27 and P. 5-33 for information on the operation when the DC is set to Disabled (FreeRun).

# Setting Methods between the Communication Control Unit and the NX Units

Refer to the user's manual for the connected Communication Control Unit for information on how to set an I/O refreshing method between the Communication Control Unit and the NX Units.

# 5-2-3 Selecting NX Units

The I/O refreshing methods that you can use depend on the model of the NX Unit. After you decide on which I/O refreshing method to use, select the NX Units.

### 5-2-4 Free-Run Refreshing

With this I/O refreshing method, the refresh cycle of the NX bus and I/O refresh cycles of the NX Units are asynchronous.

Digital I/O Units read inputs or refresh outputs at the time of I/O refreshing.

This method is used when it is not necessary to be aware of factors such as the I/O timing jitter and the concurrency of the timing to read inputs and refresh outputs between the NX Units.

This section explains operations when NX Units are connected to a CPU Unit or Communications Coupler Unit.

Refer to the user's manual for the Communication Control Unit for operations when NX Units are connected to a Communication Control Unit.

# **Description of Operation**

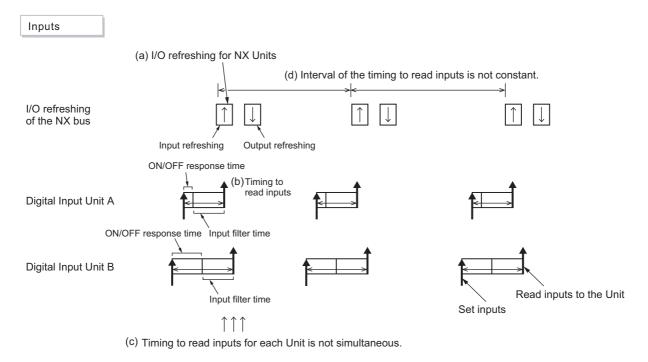
### CPU Unit Operation

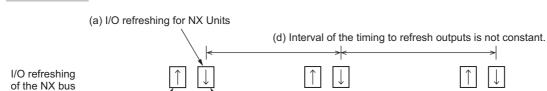
The following describes the operation of Free-Run refreshing between an NX-series CPU Unit and the NX Units.

- The CPU Unit performs I/O refreshing for NX Units. (Refer to (a) in the figure below.)
- The NX Units read inputs or refresh outputs at the time of I/O refreshing. (Refer to (b) in the figure below.)
- The CPU Unit can read the most recent input value at the time of I/O refreshing and the NX Units
  can control the most recent output value at the time of I/O refreshing. However, timing to read
  inputs or to refresh outputs for each NX Unit does not occur at the same time. (Refer to (c) in the
  figure below.)
- The interval of I/O refreshing varies with the processing conditions of the CPU Unit. Therefore, the
  interval of the timing to read inputs or to refresh outputs for NX Unit is not always the same. (Refer
  to (d) in the figure below.)
- In order to read input values correctly, you must set the inputs before the total of the ON/OFF response time and the input filter time from the timing to read inputs for each NX Unit.

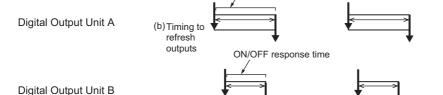
Outputs

• The ON/OFF response time is needed from the timing to refresh outputs until setting the output status of external terminals on the NX Units.

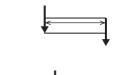








 $\downarrow\downarrow\downarrow\downarrow$ 



Set outputs

Refresh outputs

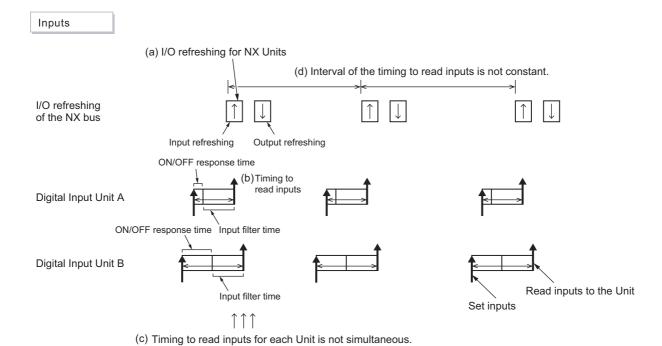
(c) Timing to refresh outputs for each Unit is not simultaneous.

ON/OFF response time

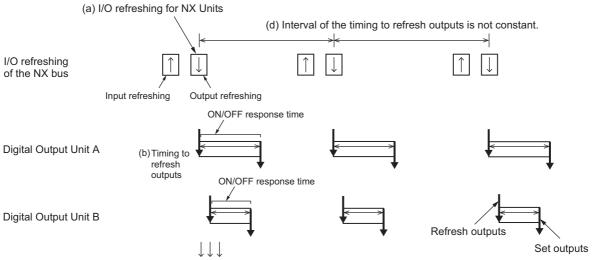
### Slave Terminal Operation

The following describes the operation of Free-Run refreshing for Slave Terminals.

- The Communications Coupler Unit performs I/O refreshing for NX Units. (Refer to (a) in the figure below.)
- The NX Units read inputs or refresh outputs at the time of I/O refreshing. (Refer to (b) in the figure below.)
- The Communications Coupler Unit can read the most recent input value at the time of I/O refreshing and the NX Units can control the most recent output value at the time of I/O refreshing. However, the timing to read inputs or to refresh outputs for each NX Unit in the Slave Terminal does not occur at the same time. (Refer to (c) in the figure below.)
- The interval of I/O refreshing varies with the processing conditions of the Communications Coupler Unit or the host communications master. Therefore, the interval of the timing to read inputs or to refresh outputs for NX Unit is not always the same. (Refer to (d) in the figure below.)
- In order to read input values correctly, you must set the inputs before the total of the ON/OFF response time and the input filter time from the timing to read inputs for each NX Unit.
- The ON/OFF response time is required from when outputs are updated until the output status is set on the external terminals of the NX Units.



Outputs



### **Settings**

Add NX Units that support Free-Run refreshing to the CPU Unit configuration or Slave Terminal configuration.

After you add the NX Units, set an I/O refreshing method depending on the connected CPU Unit or Communications Coupler Unit so that these NX Units operate with Free-Run refreshing.

Refer to 5-2-2 Setting the I/O Refreshing Methods on page 5-8 for information on how to set an I/O refreshing method.

### 5-2-5 Synchronous Input Refreshing

The I/O refreshing method described below. Among Slave Terminals, this refreshing method is supported only by EtherCAT Slave Terminals.

- The timing to read inputs is synchronized on a fixed interval between more than one NX Unit connected to a CPU Unit.
- The timing to read inputs is synchronized on a fixed interval between more than one NX Unit on more than one Slave Terminal.

This method is used when the problem such as input timing jitter or offset of timing to read inputs between more than one NX Unit happens.

This section explains operations when NX Units are connected to a CPU Unit or Communications Coupler Unit.

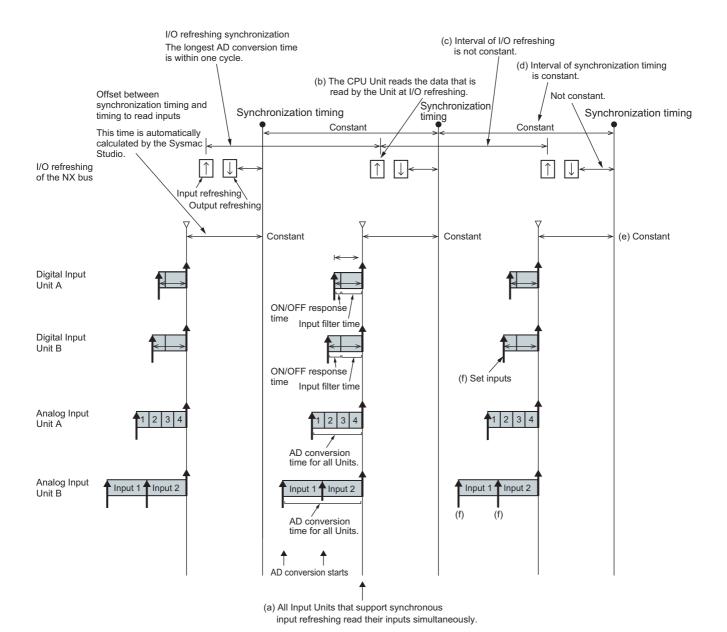
Refer to the user's manual for the Communication Control Unit for operations when NX Units are connected to a Communication Control Unit.

# **Description of Operation**

#### CPU Unit Operation

The following describes the operation of synchronous input refreshing between an NX-series CPU Unit and the NX Units.

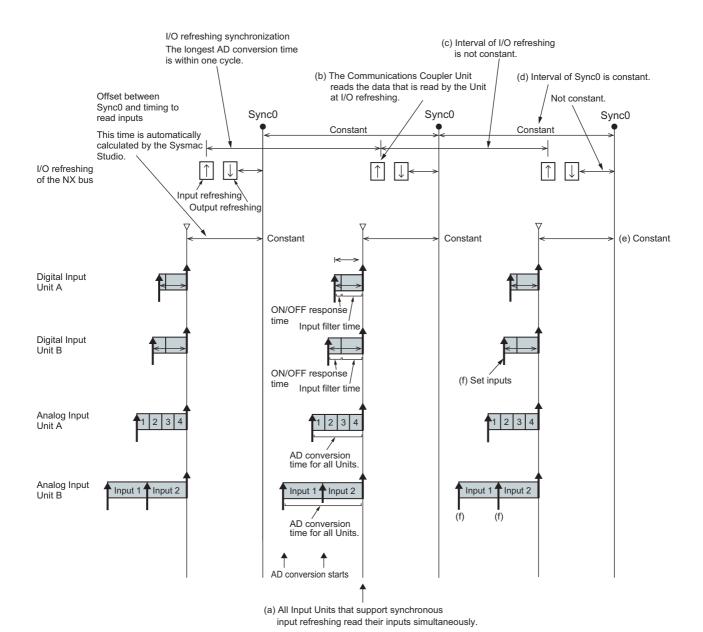
- All Digital Input Units and Analog Input Units that are connected to the CPU Units and operate
  with synchronous input refreshing read their inputs at the same time at a fixed interval based on
  the synchronization timing. (Refer to (a) in the figure below.)
- The CPU Unit reads the input values, which are read by the Unit at the timing of reading inputs, at immediate I/O refreshing. (Refer to (b) in the figure below.)
- The interval of I/O refreshing varies with the processing conditions of the CPU Unit. (Refer to (c) in the figure below.) The timing to read inputs will be at a fixed interval. (Refer to (d) and (e) in the figure below.)
- The timing of reading inputs, the synchronization timing, and the maximum NX bus I/O refresh
  cycle are automatically calculated by the Sysmac Studio according to the input refresh cycles of
  the NX Units on the CPU Unit when a Unit configuration in the CPU Unit is created and set up.
- In order to read input values correctly, you must determine the inputs before the total of the ON/OFF response time and input filter time from the timing to read inputs for each NX Unit. (Refer to (f) in the figure below.)



### Slave Terminal Operation

The following describes the operation of synchronous input refreshing of an EtherCAT Slave Terminal connected to the built-in EtherCAT port.

- All Digital Input Units and Analog Input Units that operate with synchronous input refreshing in the Slave Terminal read their inputs at the same time at a fixed interval bases on Sync0. (Refer to (a) in the figure below.)\*1
- The Communications Coupler Unit reads the input values, which are read by the Unit at the timing of reading inputs, at immediate I/O refreshing. (Refer to (b) in the figure below.)
- The interval of I/O refreshing varies with the processing conditions of the Communications Coupler Unit or the host communications master. (Refer to (c) in the figure below.) The timing to read inputs will be at a fixed interval. (Refer to (d) and (e) in the figure below.)
- The Sync0, the timing to read inputs and the maximum NX bus I/O refresh cycle of the Slave Terminals are automatically calculated by the Sysmac Studio according to the input refresh cycle of the NX Units in the Slave Terminals when the Slave Terminals are configured and set up.
- In order to read input values correctly, you must determine the inputs before the total of the ON/OFF response time and the input filter time from the timing to read inputs for each NX Unit. (Refer to (f) in the figure below.)
- \*1.If multiple Slave Terminals are present on the same EtherCAT network, refer to the *NX-series EtherCAT Coupler Unit User's Manual* (Cat. No. W519) for the range of available Slave Terminals that operate at the same timing.



### **Settings**

Add NX Units that support synchronous I/O refreshing to the CPU Unit configuration or Slave Terminal configuration.

After you add the NX Units, set an I/O refreshing method depending on the connected CPU Unit or Communications Coupler Unit so that these NX Units operate with synchronous I/O refreshing.

Refer to 5-2-2 Setting the I/O Refreshing Methods on page 5-8 for information on how to set an I/O refreshing method.

### 5-2-6 Synchronous Output Refreshing

The I/O refreshing method described below. Among Slave Terminals, this refreshing method is supported only by EtherCAT Slave Terminals.

- The timing to refresh outputs is synchronized on a fixed interval between more than one NX Unit connected to a CPU Unit.
- The timing to reresh outputs is synchronized on a fixed interval between more than one NX Unit on more than one Slave Terminal.

This method is used when the problem such as input timing jitter or offset of timing to refresh outputs between more than one NX Unit happens.

This section explains operations when NX Units are connected to a CPU Unit or Communications Coupler Unit.

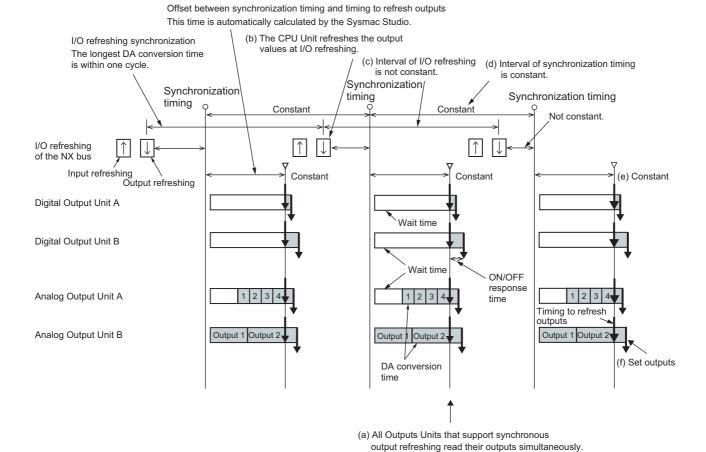
Refer to the user's manual for the Communication Control Unit for operations when NX Units are connected to a Communication Control Unit.

# **Description of Operation**

### CPU Unit Operation

The following describes the operation of synchronous output refreshing between an NX-series CPU Unit and the NX Units.

- All Digital Output Units and Analog Output Units that are connected to the CPU Units and operate
  with synchronous output refreshing refresh their outputs at the same time at a fixed interval based
  on the synchronization timing. (Refer to (a) in the figure below.)
- The CPU Unit refreshes the output values at I/O refreshing. (Refer to (b) in the figure below.)
- The interval of I/O refreshing varies with the processing conditions of the CPU Unit. (Refer to (c) in the figure below.) The timing to refresh outputs will be at a fixed interval. (Refer to (d) and (e) in the figure below.)
- The timing of refreshing outputs, the synchronization timing, and the maximum NX bus I/O refresh
  cycle are automatically calculated by the Sysmac Studio according to the output refresh cycles of
  the NX Units on the CPU Unit when a Unit Configuration in the CPU Unit is created and set up.
- The ON/OFF response time is needed from the timing to refresh outputs until setting the output status of external terminals on the NX Units. (Refer to (f) in the figure below.)



### Slave Terminal Operation

The following describes the operation of synchronous output refreshing of an EtherCAT Slave Terminal connected to the built-in EtherCAT port.

- · All Digital Output Units and Analog Output Units that operate with synchronous output refreshing in the Slave Terminal refresh their outputs at the same time at a fixed interval based on Sync0. (Refer to (a) in the figure below.)\*1
- The Communication Coupler Unit refreshes the output values at I/O refreshing. Refer to (b) in the figure below.)
- The interval of I/O refreshing varies with the processing conditions of the Communications Coupler Unit or the host communications master. (Refer to (c) in the figure below.) The timing to refresh outputs will be at a fixed interval. (Refer to (d) and (e) in the figure below.)
- The Sync0, the timing to refresh outputs and the maximum NX bus I/O refresh cycle of the Slave Terminals are automatically calculated by the Sysmac Studio according to the output refresh cycle of the NX Units in the Slave Terminals when the Slave Terminals are configured and set up.
- The ON/OFF response time is needed from the timing to refresh outputs until setting the output status of external terminals on the NX Units. (Refer to (f) in the figure below.)
- \*1. If multiple Slave Terminals are present on the same EtherCAT network, refer to the NX-series EtherCAT Coupler Unit User's Manual (Cat. No. W519) for the range of available Slave Terminals that operate at the same timing.

This time is automatically calculated by the Sysmac Studio. (b) The Communication Coupler Unit refreshes I/O refreshing synchronization the output values at I/O refreshing. The longest DA conversion time is within one cycle. (c) Interval of I/O refreshing (d) Interval of Sync0 is constant. Sync0 Sync0 Sync0 Constant Constan Not constant. I/O refreshing of the NX bus Input refreshing (e) Constant Constant Constant Output refreshing Digital Output Unit A Wait time Digital Output Unit B Wait time ON/OFF response Analog Output Unit A 1 2 3 4 time Timing to refresh outputs Analog Output Unit B Output 1 Output 2 Output 1 Output 2 Output 1 Output 2 (f) Set outputs

Offset between Sync0 and timing to refresh outputs

(a) All Outputs Units that support synchronous output refreshing read their outputs simultaneously.

DA conversion

time

# **Settings**

Same as the settings for synchronous input refreshing. Refer to Settings in 5-2-5 Synchronous Input Refreshing on page 5-13 for details.

#### 5-2-7 **Time Stamp Refreshing**

With this I/O refreshing method, the NX Units record the DC times when inputs change or perform outputs at specified DC times. These times are not synchronized to the NX bus refresh cycles. Among Slave Terminals, only EtherCAT Slave Terminals support this refreshing method.

Data exchange between the NX Units and CPU Unit or EtherCAT Coupler Unit are performed cyclically on the NX bus refresh cycles.

There are the following two I/O refreshing methods.

- · Input refreshing with input changed time
- · Output refreshing with specified time stamp

Each of these I/O refreshing methods is described below.

### 5-2-8 Input Refreshing with Input Changed Time

With this I/O refreshing method, the Input Units record the DC times when the inputs changed. The DC times are not synchronized to the NX bus refresh cycles. Among Slave Terminals, only EtherCAT Slave Terminals support this refreshing method.

The CPU Unit or EtherCAT Coupler Unit cyclically reads both the input values and the DC times when the inputs changed on the NX bus refresh cycles.

In the descriptions below, the DC time when the input changed is called the input changed time.

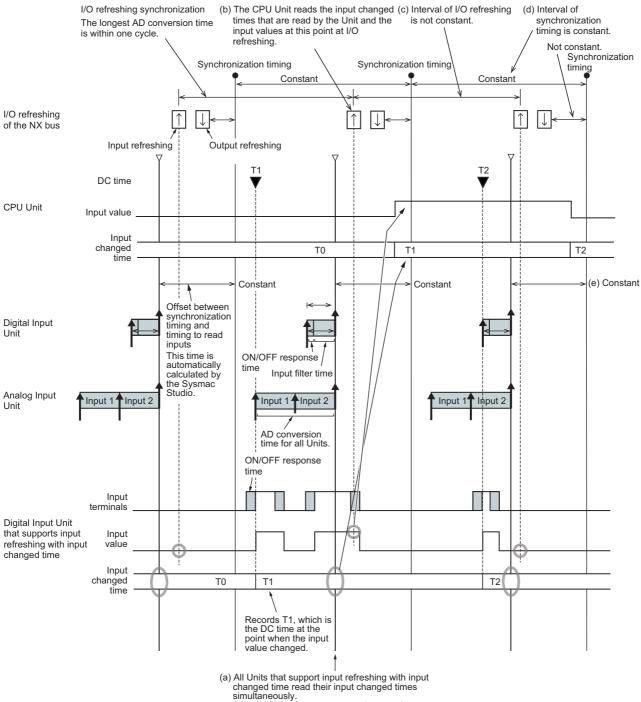
You can use the Input Units that support input refreshing with input changed time with the Output Units that support output refreshing with specified time stamp to control an output at a fixed interval after a sensor input changes.

# **Description of Operation**

### CPU Unit operation

The following describes the operation of input refreshing with input changed time between an NX-series CPU Unit and the NX Units.

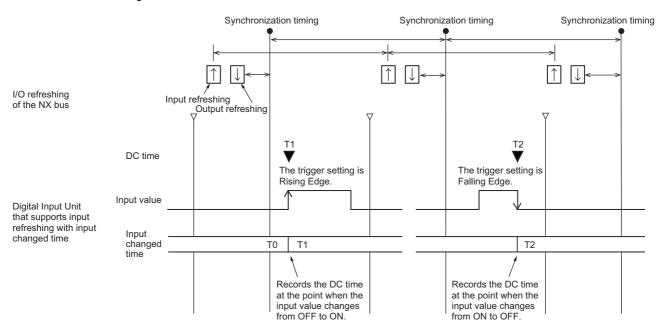
- The NX Units that support input refreshing with input changed time record the DC times when an
  input changes for each input bit. The DC times that the Units record are the DC times for which
  the status changes of the input terminals passed the ON/OFF response time and reached the
  internal circuits.
- The CPU Unit reads the input values and the input changed times from the NX Units at I/O
  refreshing. The input values that the CPU Unit reads are not the input values at the point when the
  input change times were recorded, but the input values at I/O refreshing.
- All Digital Input Units that operate with input refreshing with input changed times and are connected to the CPU Unit read the input changed times at the same time at a fixed interval based on synchronization timing. (Refer to (a) in the figure below.)
- The timing of reading input changed times is the same as the timing at which all Digital Input Units and Analog Input Units that operate with synchronous input refreshing and are connected to the CPU Unit read their inputs.
- The timing of reading input values is at I/O refreshing, which is different from the timing of reading input changed times.
- The CPU Unit reads the input changed times and input values at immediate I/O refreshing after the input changed times are read. (Refer to (b) in the figure below.)
- The interval of I/O refreshing varies with the processing conditions of the CPU Unit. (Refer to (c) in the figure below.) The timing to read input changed times will be at a fixed interval. (Refer to (d) and (e) in the figure below.)
- The timing of reading input changed times, the synchronization timing, and the maximum NX bus I/O refresh cycle are automatically calculated by the Sysmac Studio according to the input refresh cycles of the NX Units on the CPU Unit when a Unit Configuration in the CPU Unit is created and set up.



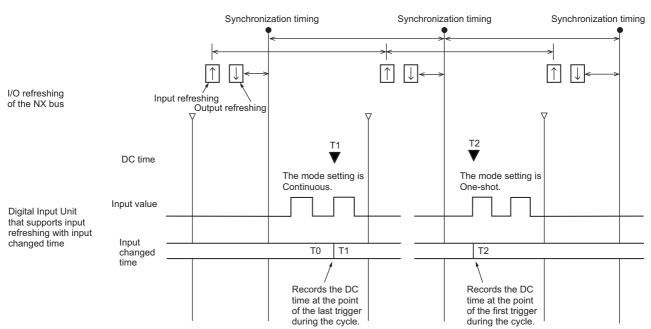
(a) All Units that support input refreshing with input changed time read their input changed times simultaneously.

All Input Units that support synchronous input refreshing read their inputs simultaneously.

 You can select to either detect changes at the input rising edge, or at the input falling edge. Make the setting in advance.



- NX Units that support input refreshing with input changed time do not have an input filter function.
- You can select at which point the input changed times are recorded when the inputs change more than one time during the NX bus I/O refresh cycle. Make the setting in advance.

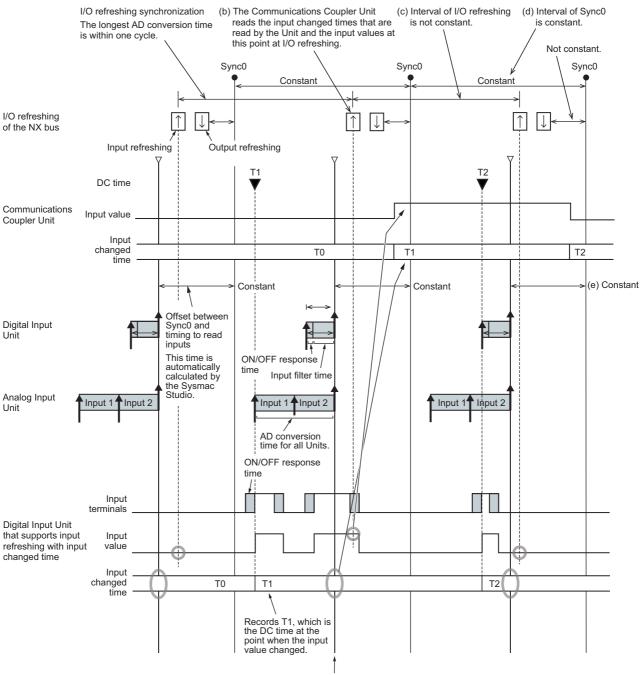


· The input changed times are retained if the inputs do not change.

### Slave Terminal Operation

The following describes the operation of input refreshing with input changed time of an EtherCAT Slave Terminal connected to the built-in EtherCAT port.

- The NX Units that support input refreshing with input changed time record the DC times when an input changes for each input bit. The DC times that the Units record are the DC times for which the status changes of the input terminals passed the ON/OFF response time and reached the internal circuits.
- The EtherCAT Coupler Unit reads the input values and the input changed times from the NX Units at I/O refreshing. The input values that the EtherCAT Coupler Unit read are not the values at the point when the input change times were recorded, but the values at I/O refreshing.
- · All Digital Input Units that operate with input refreshing with input changed times in the Slave Terminal read the input changed times at the same time at a fixed interval based on Sync0. (Refer to (a) in the figure below.)\*1
- The timing of reading input changed times is the same as the timing at which all Digital Input Units and Analog Input Units that operate with synchronous input refreshing in the Slave Terminal read their inputs.
- The timing of reading input values is at I/O refreshing, which is different from the timing of reading input changed times.
- The EtherCAT Coupler Unit reads the input changed times and input values at immediate I/O refreshing after the input changed times are read. (Refer to (b) in the figure below.)
- The interval of I/O refreshing varies with the processing conditions of the EtherCAT Coupler Unit or the EtherCAT master. (Refer to (c) in the figure below.) The timing of reading input changed times will be at a fixed interval. (Refer to (d) and (e) in the figure below.)
- Sync0, the timing of reading input changed times, and the maximum NX bus I/O refresh cycle for multiple Slave Terminals are automatically calculated by the Sysmac Studio according to the input refresh cycles of the NX Units in the Slave Terminals when the Slave Terminals are configured and set up.
- \*1. If multiple Slave Terminals are present on the same EtherCAT network, refer to the NX-series EtherCAT Coupler Unit User's Manual (Cat. No. W519) for the range of available Slave Terminals that operate at the same timing.

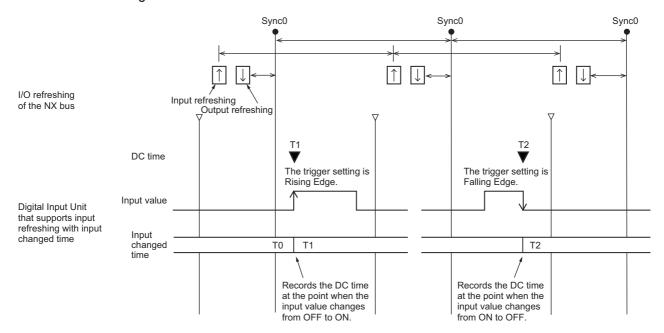


(a) All Units that support input refreshing with input changed time read their input changed times simultaneously.

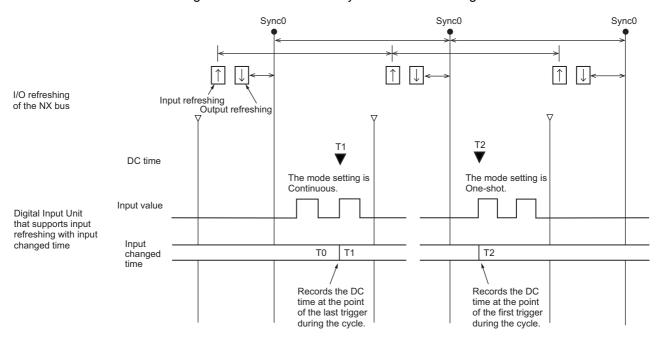
All Input Units that support synchronous input refreshing read their inputs simultaneously.

NX-series Digital I/O Unit User's Manual (W521)

· You can select to either detect changes at the input rising edge, or at the input falling edge. Make the setting in advance.



- NX Units that support input refreshing with input changed time do not have an input filter function.
- · You can select at which point the input changed times are recorded when the inputs change more than one time during the NX bus I/O refresh cycle. Make the setting in advance.



· The input changed times are retained if the inputs do not change.

## **Settings**

Add NX Units that support input refreshing with input changed time to the CPU Unit configuration or Slave Terminal configuration.

After you add the NX Units, set an I/O refreshing method depending on the connected CPU Unit or Communications Coupler Unit so that these NX Units operate with input refreshing with input changed time.

Refer to 5-2-2 Setting the I/O Refreshing Methods on page 5-8 for information on how to set an I/O refreshing method.

Also, using the NX Unit operation settings, set the edge to read the input changed time or operation mode.

Refer to NX Units in Input Refreshing with Input Changed Time on page 6-12 in 6-3 List of Settings on page 6-7 for details on the settings.



### **Additional Information**

Do not set the DC enable setting to *Disabled (FreeRun)*. If it is set to *Disabled*, the input refreshing with input changed time will not operate correctly. However, an error does not occur even if it is disabled.

If the DC enable setting is set to *Disabled (FreeRun)*, the input values reflect the actual input status, but the input changed times retain the default values and do not change.

#### **Output Refreshing with Specified Time Stamp** 5-2-9

With this I/O refreshing method, the Output Units refresh outputs at the DC times specified by the user program. The specified DC times are not synchronized to the NX bus refresh cycles. Among Slave Terminals, only EtherCAT Slave Terminals support this refreshing method.

The CPU Unit or EtherCAT Coupler Unit cyclically sets the output set values and the DC times to refresh outputs to the Output Units on the NX bus refresh cycles.

In the descriptions below, the DC time to refresh the output is called the specified time.

You can use the Input Units that support input refreshing with input changed time with the Output Units that support output refreshing with specified time stamp to control outputs at fixed intervals after the sensor inputs change.

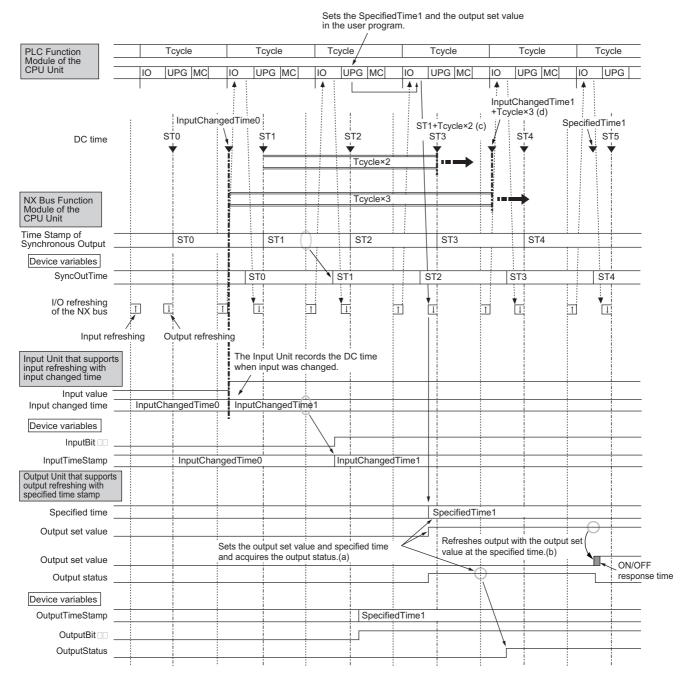
### **Description of Operation**

### CPU Unit Operation

The following describes the operation of output refreshing with specified time stamp between an NX-series CPU Unit and the NX Units.

- You can specify the specified time and the output set value for each output bit. You can also set the same specified time for multiple output bits.
- The NX Bus Function Module of the CPU Unit sets the output set values and the specified times to the NX Units and acquires the output status at I/O refreshing. (Refer to (a) in the figure below.)
- The output status is used when you determine that the output was refreshed normally at the specified time. Refer to 5-2-10 An Example of Turning ON Outputs at Specific Times After the Sensor Inputs Change on page 5-34 for an example of determining that the output was refreshed.
- The NX Units turn ON the output status when the specified times are set.
- The NX Units refresh outputs and turn OFF the output status at the specified times. The values of outputs that the NX Units refresh are the output set values at the specified times. (Refer to (b) in the figure below.)
- The ON/OFF response time is needed from the specified time until setting the output status of external terminals on the NX Units.
- If the next specified time is set before the current specified time is reached, the NX Units overwrite
  the current specified time to the next specified time. The current specified time is ignored.
- If the value of the specified time is 0, the output is refreshed immediately. At this time, the Output Units refresh outputs according to the output set values.
- When the specified time is set to the NX Units, if the specified time is a previous DC time, a Previous Time Specified event (event code: 7001000 hex) occurs.
- To make the specified time as a future DC time when it is set to the NX Units, set the specified time to satisfy both the following conditions.
- a) A future DC time at least twice the task period from the previous value of the Time Stamp of Synchronous Output (Refer to (c) in the figure below.)
- b) A future DC time at least three times the task period from the input changed time read from the Input Units that support input refreshing with input changed time (Refer to (d) in the figure below.)
- The Time Stamp of Synchronous Output is one of I/O data in the NX Bus Function Module of the CPU Unit, and contains the DC time of synchronous outputs from the NX Unit. The I/O port name for this I/O data is "□ Time Stamp of Synchronous Output"\*1. This I/O data is allocated per NX Unit to a CPU Unit.

<sup>\*1. &</sup>quot;□" is a device name.



Tcycle: Task period IO: I/O refreshing

UPG: User program execution

MC: Motion control



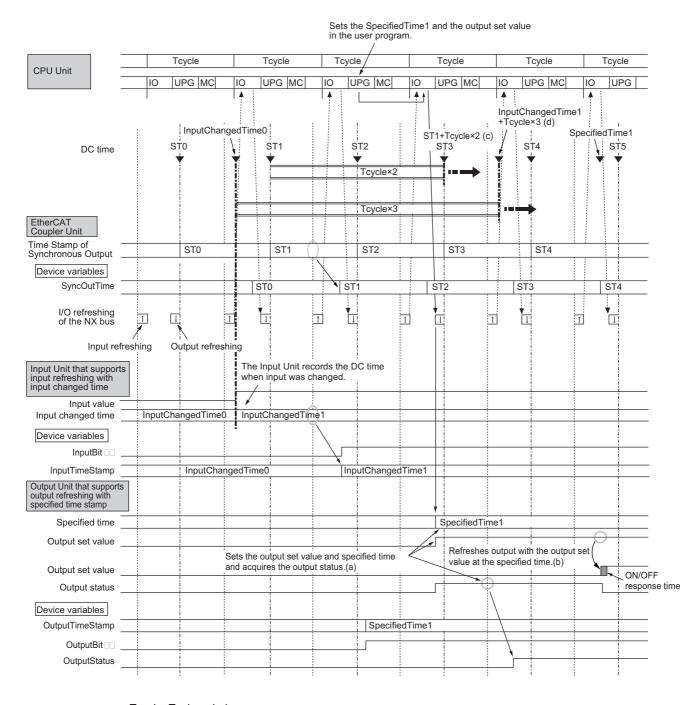
### **Additional Information**

With the NX DOutTimeStamp instruction, if you set a previous DC time unintentionally, a Previous Time Specified event will not occur and you can refresh the output immediately. Refer to the NJ/NX-series Instructions Reference Manual (Cat. No. W502) for details on the NX DOutTimeStamp instruction.

### Slave Terminal Operation

The following describes the operation of output refreshing with specified time stamp of an EtherCAT Slave Terminal connected to the built-in EtherCAT port.

- You can specify the specified time and the output set value for each output bit. You can also set the same specified time for multiple output bits.
- The EtherCAT Coupler Unit sets the output set values and the specified times to the NX Units and acquires the output status at I/O refreshing. (Refer to (a) in the figure below.)
- The output status is used when you determine that the output was refreshed normally at the specified time. Refer to 5-2-10 An Example of Turning ON Outputs at Specific Times After the Sensor Inputs Change on page 5-34 for an example of determining that the output was refreshed.
- The NX Units turn ON the output status when the specified times are set.
- The NX Units refresh outputs and turn OFF the output status at the specified times. The values of outputs that the NX Units refresh are the output set values at the specified times. (Refer to (b) in the figure below.)
- The ON/OFF response time is needed from the specified time until setting the output status of external terminals on the NX Units.
- If the next specified time is set before the current specified time is reached, the NX Units overwrite the current specified time to the next specified time. The current specified time is ignored.
- If the value of the specified time is 0, the output is refreshed immediately. At this time, the Output Units refresh outputs according to the output set values.
- When the specified time is set to the NX Units, if the specified time is a previous DC time, a Previous Time Specified event (event code: 70010000 hex) occurs.
- To make the specified time as a future DC time when it is set to the NX Units, set the specified time to satisfy both the following conditions.
- a) A future DC time at least twice the task period from the previous value of the Time Stamp of Synchronous Output (Refer to (c) in the figure below.)
- b) A future DC time at least three times the task period from the input changed time read from the Input Units that support input refreshing with input changed time (Refer to (d) in the figure below.)
- The Time Stamp of Synchronous Output is one of I/O data in the EtherCAT Coupler Unit, and contains the DC time of synchronous outputs from the NX Unit. By default, it is not assigned to the I/O entry mapping, so edit the settings and assign it to the I/O entry mapping. The added I/O data is 0x200A: 02 (Time Stamp of Synchronous Output).



Tcycle: Task period IO: I/O refreshing

UPG: User program execution

MC: Motion control



#### **Additional Information**

With the NX\_DOutTimeStamp instruction, if you set a previous DC time unintentionally, a Previous Time Specified event will not occur and you can refresh the output immediately. Refer to the instructions reference manual for the connected CPU Unit or Industrial PC for details on the NX DOutTimeStamp instruction.

# **Settings**

Add NX Units that support output refreshing with specified time stamp to the CPU Unit configuration or Slave Terminal configuration.

After you add the NX Units, set an I/O refreshing method depending on the connected CPU Unit or Communications Coupler Unit so that these NX Units operate with output refreshing with specified time stamp.

Refer to 5-2-2 Setting the I/O Refreshing Methods on page 5-8 for information on how to set an I/O refreshing method.



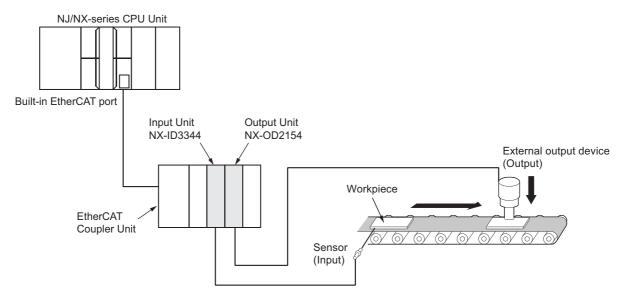
#### **Additional Information**

Do not set the DC enable setting to *Disabled (FreeRun)*. If it is set to *Disabled*, the output refreshing with specified time stamp will not operate correctly. However, an error does not occur even if it is disabled.

If the DC enable setting is set to *Disabled (FreeRun)*, outputs are not refreshed regardless of the output set values and values of the specified time.

# 5-2-10 An Example of Turning ON Outputs at Specific Times After the **Sensor Inputs Change**

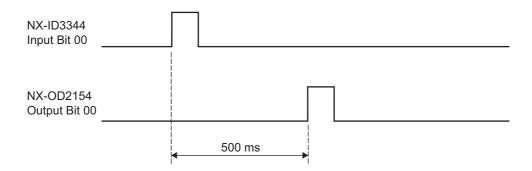
The following shows an example that uses an Input Unit NX-ID3344 that supports input refreshing with input changed time and an Output Unit NX-OD2154 that supports output refreshing with specified time stamp to turn ON the output to the external output device at a specific time after the input changed time from the sensor. It is an example when using an EtherCAT Slave Terminal.



For cases in which NX-ID3344 and NX-OD2154 are used for NX-series NX1P2 CPU Units, this section explains only the points different from the case of using an EtherCAT Slave Terminal. Refer to When Used by Connecting to the CPU Unit on page 5-41 for details.

# **Specifications of Sample Programming**

 In this example, 500 ms after the sensor input that is connected to input bit 00 of an Input Unit NX-ID3344 changes to ON, output bit 00 of an Output Unit NX-OD2154 changes to ON.



- The following determinations are performed to normally operate the programming.
  - a) When the specified time is set to an Output Unit NX-OD2154, the validity of the specified time is determined to make sure that the specified time is not a previous DC time.
  - b) With an Output Unit NX-OD2154, the output was normally refreshed at the specified time is determined.

# **Network Configuration**

The network configuration is as follows.

A Slave Terminal with the following configuration is connected at EtherCAT node address 1. The device names that are given in the following table are used.

Unit number	Model	Unit	Device name
0	NX-ECC201	EtherCAT Coupler Unit	E001
1	NX-ID3344	Digital Input Unit that supports input refreshing with input changed time	N1
2	NX-OD2154	Digital Output Unit that supports output refreshing with specified time stamp	N2

# **Task Settings**

The task period of the primary periodic task is 1 ms.

# **Unit Operation Settings**

The Unit operation settings of the Input Unit NX-ID3344 are as follows.

Meaning
Trigger to read the input changed time: Rising Edge
Operation mode to read the input changed time: Continuous (Last changed time)
Ор

# I/O Map

The following I/O map settings are used.

However, add 0x200A: 02 (Time Stamp of Synchronous Output) to an I/O entry mapping of the Ether-CAT Coupler Unit.

Position	Port	Description	R/W	Data type	Variable	Variable type
Node1	Time Stamp of	Contains the time stamp	R	ULINT	E001_Time_Stamp_	Global
	Synchronous	for the timing of			of_Synchronous_Ou	variable
	Output	synchronous outputs from			tput	
		the connected NX Unit.				
		(Unit: ns)				
Unit1	Input Bit 00	Input changed time for	R	ULINT	N1_Input_Bit_00_Ti	Global
	Time Stamp	input bit 00			me_Stamp	variable
Unit2	Output Bit 00	Specified time for output bit	W	ULINT	N2_Output_Bit_00_	Global
	Time Stamp	00			Time_Stamp	variable
Unit2	Output Bit 00	Output bit 00	W	BOOL	N2_Output_Bit_00	Global
						variable
Unit2	Output Bit 00	Output status 00	R	BOOL	N2_Output_Bit_00_	Global
	Output Status				Output_Status	variable

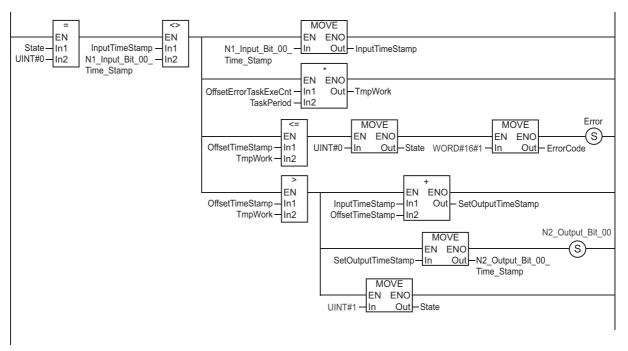
# LD

Internal Variables	Name	Data type	Default value	Comment
	State	UINT	0	Internal status of program
	Error	BOOL	FALSE	Error flag
	ErrorCode	WORD	16#0000	Error code
	InputTimeStamp	ULINT	0	Recorded input changed time
	SetOutputTimeStamp	ULINT	0	DC time set for the specified time
	OffsetTimeStamp	ULINT	ULINT#500000000	Time from the input changed time until the specified time (ms)
	OffsetErrorTaskExeCnt	ULINT	ULINT#3	Error criteria for specified time
	TaskPeriod	ULINT	ULINT#1000000	Task period (ms)
	TmpWork	ULINT		Workpiece for determining specified time error

External Variables	Name	Data type	Comment
	E001_Time_Stamp_of_Synchronous_Output	ULINT	DC time for the timing of synchronous
			outputs from the NX Unit
	N1_Input_Bit_00_Time_Stamp	ULINT	Input changed time for input bit 00
	N2_Output_Bit_00	BOOL	Output bit 00
	N2_Output_Bit_00_Time_Stamp	ULINT	Specified time for output bit 00
	N2_Output_Bit_00_Output_Status	BOOL	Output status for output bit 00

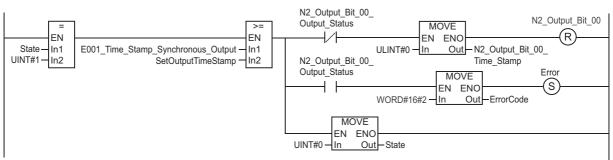
0 State0: Wait for input bit 00 to change.

If the specified time is 3 task periods or less, error end. Transit to set the specified time and to check the output.



#### 1 State1: Check the output.

Check the output status after the specified time has passed. Output error or output completion (Turn OFF the output.).



# ST

Internal Variables	Name	Data type	Default value	Comment
	State	UINT	0	Internal status of program
	Error	BOOL	FALSE	Error flag
	ErrorCode	WORD	16#0000	Error code
	InputTimeStamp	ULINT	0	Recorded input changed time
	SetOutputTimeStamp	ULINT	0	DC time set for the specified time
	OffsetTimeStamp	ULINT	ULINT#500000000	Time from the input changed time until the specified time (ms)
	OffsetErrorTaskExeCnt	ULINT	ULINT#3	Error criteria for specified time
	TaskPeriod	ULINT	ULINT#1000000	Task period (ms)

External Variables	Name	Data type	Comment
	E001_Time_Stamp_of_Synchronous_Output	ULINT	DC time for the timing of synchronous outputs from the NX Unit
	N1_Input_Bit_00_Time_Stamp N2_Output_Bit_00		Input changed time for input bit 00
			Output bit 00
	N2_Output_Bit_00_Time_Stamp	ULINT	Specified time for output bit 00
	N2_Output_Bit_00_Output_Status		Output status for output bit 00

CASE State OF

```
0:
            //Wait for input bit 00 to change.
         IF( InputTimeStamp <> N1 Input Bit 00 Time Stamp )THEN
           InputTimeStamp:=N1_Input_Bit_00_Time_Stamp;
                                                                //Save the input changed time for input bit 00.
           IF( OffsetTimeStamp <= (OffsetErrorTaskExeCnt * TaskPeriod) )THEN
              //If the specified time is 3 task periods or less, error end.
              State:=0:
                                          //Transit to waiting for input bit 00 to change.
              Error:=TRUE;
                                          //Error registration
              ErrorCode:=WORD#16#0001;
           ELSE
              //Set the specified time.
              SetOutputTimeStamp:=InputTimeStamp+OffsetTimeStamp;
              N2_Output_Bit_00_Time_Stamp:=SetOutputTimeStamp;
              N2_Output_Bit_00:=TRUE;
              State:=1;
                                                //Transit to output check.
           END IF;
        END IF;
    1:
            //Check the output.
         IF( E001_Time_Stamp_of_Synchronous_Output < SetOutputTimeStamp )THEN
                    //Continue output check because the specified time has not been reached.
         ELSE
           //Check the output status because the specified time has passed.
           IF( N2_Output_Bit_00_Output_Status=FALSE )THEN
              //Output completion
              N2_Output_Bit_00_Time_Stamp:=0;
              N2 Output Bit 00:=FALSE;
                                                //Turn OFF the output.
              State:=0;
                                                //Transit to waiting for input bit 00 to change.
           ELSE
              //Output error
              Error:=TRUE;
                                                //Error registration
              ErrorCode:=WORD#16#0002;
              State:=0;
                                                //Transit to waiting for input bit 00 to change.
           END IF;
        END_IF;
ELSE
END CASE;
```

#### When Used by Connecting to the CPU Unit

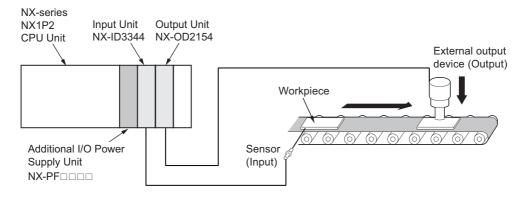
For cases in which NX-ID3344 and NX-OD2154 are used for NX-series NX1P2 CPU Units, this section explains only the points different from the case of using an EtherCAT Slave Terminal.

The points of difference are shown below. To use by connecting to the CPU Unit, read a given example with the points of difference in mind.

#### Unit Configuration

The Unit configuration is given in the following figure.

To use an NX1P2 CPU Unit, you need to add an Additional I/O Power Supply Unit to the right of the CPU Unit in order to supply I/O power to NX-ID3344 and NX-OD2154.



By adding an Additional I/O Power Supply Unit, 1 is added to the unit number of the NX-ID3344 and NX-OD2154 as well as the number in its device name, as shown below.

Unit number	Model	Unit	Device name
1	NX-PF	Additional I/O Power Supply Unit	N1
2	NX-ID3344	Digital Input Unit that supports input refreshing with input changed time	N2
3	NX-OD2154	Digital Output Unit that supports output refreshing with specified time stamp	N3

#### • I/O Map

Because we added an Additional I/O Power Supply Unit, add 1 to the corresponding numbers that represent the position and variable of the NX-ID3344 and NX-OD2154 in the example for an Ether-CAT Slave Terminal, as shown below.

Posi- tion	Port	Variable
Unit2	Input Bit 00 Time Stamp	N2_Input_Bit_00_Time_Stamp
Unit3	Output Bit 00 Time Stamp	N3_Output_Bit_00_Time_Stamp
Unit3	Output Bit 00	N3_Output_Bit_00
Unit3	Output Bit 00 Output Status	N3_Output_Bit_00_Output_Status

When Units are connected to the CPU Unit, the Time Stamp of Synchronous Output uses the following data. It is I/O data for the NX Bus Function Module, which is allocated to the CPU Unit for each NX Unit.

Posi- tion	Port	Description	R/W	Data type	Variable	Variable type
NXBus-	N3 Time Stamp	Contains the time stamp for	R	ULINT	NXBus_N3_Time_	Global
Master	of Synchro- nous Output	the timing of synchronous outputs from the connected NX Unit with the device name "N3." (Unit: ns)			Stamp_of_Synchro- nous_Output	variable

Use the above variable for the sample programming in the example for an EtherCAT Slave Terminal.

#### Task Period of the Primary Periodic Task

The minimum value for the task period of the primary periodic task in the NX1P2 CPU Unit is 2ms. 1ms in the EtherCAT Slave Terminal example cannot be set.

# **Digital Input Units**

This section describes the types and functions of Digital Input Units.

<b>3-1</b>	Types	of Digital Input Units	6-2
<b>3-2</b>	Specif	ications of I/O Data	6-4
	6-2-1	Allocable I/O Data	6-4
6-3	List of	Settings	6-7
6-4	Functi	on	-13
	6-4-1	List of Digital Input Unit Functions	3-13
	6-4-2	Input Filter	3-14

#### **Types of Digital Input Units** 6-1

Digital Input Units are parts of NX Units, and process inputs of digital signals (ON/OFF signals). The Digital Input Unit types are described below.

### DC Input Units (Screwless Clamping Terminal Block, 12 mm Width)

Model	Num ber of poin ts	Internal I/O common	Rated input voltage	I/O refreshing method	ON/OFF response time	Reference
NX-ID3317			12 to 24 VDC		20 μs max./400 μs max.	P. A-10
NX-ID3343		NPN	and Free-Run refreshing  24 VDC  Input refreshing with input changed time only	100 ns max /100 ns	P. A-12	
NX-ID3344	4 point			input changed time	max.	P. A-14
NX-ID3417	S		12 to 24 VDC	Switching Synchro- nous I/O refreshing and Free-Run refreshing	20 μs max./400 μs max.	P. A-16
NX-ID3443		PNP			100 ns max /100 ns	P. A-18
NX-ID3444				Input refreshing with input changed time only	max.	P. A-20
NX-ID4342	8	NPN	24 VDC			P. A-22
NX-ID4442	point s	PNP		Switching Synchro- nous I/O refreshing	20 μs max./400 μs	P. A-24
NX-ID5342	16	NPN		and Free-Run	max.	P. A-26
NX-ID5442	point s	PNP		refreshing		P. A-28

#### DC Input Units (M3 Screw Terminal Block, 30 mm Width)

Model	Num ber of poin ts	Internal I/O common	Rated input voltage	I/O refreshing method	ON/OFF response time	Reference
NX-ID5142-1	16 point s	For both NPN/PNP	24 VDC	Switching Synchro- nous I/O refreshing and Free-Run refreshing	20 μs max./400 μs max.	P. A-30

# DC Input Units (MIL Connector, 30 mm Width)

Model	Num ber of poin ts	Internal I/O common	Rated input voltage	I/O refreshing method	ON/OFF response time	Reference
NX-ID5142-5	16 point s	For both NPN/PNP	24 VDC	Switching Synchro- nous I/O refreshing	20 µs max./400 µs	P. A-32
NX-ID6142-5	32 point s	For both NPN/PNP	24 VDC	and Free-Run refreshing	max.	P. A-34

# DC Input Units (Fujitsu Connector, 30 mm Width)

Model	Num ber of poin ts	Internal I/O common	Rated input voltage	I/O refreshing method	ON/OFF response time	Reference
NX-ID6142-6	32 point s	For both NPN/PNP	24 VDC	Switching Synchro- nous I/O refreshing and Free-Run refreshing	20 μs max./400 μs max.	P. A-37

# AC Input Units (Screwless Clamping Terminal Block, 12 mm Width)

Model	Num ber of poin ts	Rated input voltage	I/O refreshing method	ON/OFF response time	Reference
NX-IA3117	4 point s	200 to 240 VAC, 50/60 Hz (170 to 264 VAC, ±3 Hz)	Free-Run refreshing	10 ms max./40 ms max.	P. A-40

#### 6-2 **Specifications of I/O Data**

This section describes I/O data for the Digital Input Units.

#### Allocable I/O Data 6-2-1

This section describes the allocable I/O data in the Digital Input Unit.

An I/O entry mapping is assigned to the I/O allocation settings for the Digital Input Unit.

A specific I/O entry is assigned to the I/O entry mapping for each NX Unit model. These allocations are fixed, so you cannot add others or change them.

An I/O entry means the I/O data described in this section. An I/O entry mapping means a collection of I/O entries.

To assign the I/O allocation information of the NX Unit or Slave Terminal to an NJ/NX-series CPU Unit or NY-series Industrial PC, use the I/O ports for the allocated I/O data.

However, for Slave Terminals, I/O ports may not be used depending on the type of communications master or Communications Coupler Unit.

Refer to the user's manual for the connected Communications Coupler Unit for details on how to use I/O data for Slave Terminals.

Refer to the user's manual for the Communication Control Unit for details on how to use I/O data for Communication Control Units.

### NX Units in Free-Run Refreshing or Synchronous I/O Refreshing

#### • Four-point Input Units

Data name	Description	Data type	Default value	I/O port name	Index	Subin- dex
Input Bit 00	The input value for input bit 00.	BOOL	FALSE	Input Bit 00	6000 hex	01 hex
Input Bit 01	The input value for input bit 01.	BOOL	FALSE	Input Bit 01		02 hex
Input Bit 02	The input value for input bit 02.	BOOL	FALSE	Input Bit 02		03 hex
Input Bit 03	The input value for input bit 03.	BOOL	FALSE	Input Bit 03		04 hex

#### • Eight-point Input Units

Data name	Description	Data type	Default value	I/O port name	Index	Subin- dex
Input Bit 8 bits	The input values for 8 bits.	BYTE	00 hex	Input Bit 8 bits	6001 hex	01 hex
	The following 8 BOOL data are included.					
Input Bit 00	The input value for input bit 00.	BOOL	FALSE	Input Bit 00		
Input Bit 01	The input value for input bit 01.	BOOL	FALSE	Input Bit 01		
Input Bit 02	The input value for input bit 02.	BOOL	FALSE	Input Bit 02		
Input Bit 03	The input value for input bit 03.	BOOL	FALSE	Input Bit 03		
Input Bit 04	The input value for input bit 04.	BOOL	FALSE	Input Bit 04		
Input Bit 05	The input value for input bit 05.	BOOL	FALSE	Input Bit 05		
Input Bit 06	The input value for input bit 06.	BOOL	FALSE	Input Bit 06		
Input Bit 07	The input value for input bit 07.	BOOL	FALSE	Input Bit 07		

# • Sixteen-point Input Units

Data name	Description	Data type	Default value	I/O port name	Index	Subin- dex
Input Bit 16 bits	The input values for 16	WORD	0000 hex	Input Bit 16	6002 hex	01 hex
	bits.			bits		
	The following 16 BOOL					
	data are included.					
Input Bit 00	The input value for input	BOOL	FALSE	Input Bit 00		
	bit 00.					
Input Bit 01	The input value for input	BOOL	FALSE	Input Bit 01		
	bit 01.					
•						
•						
•						
Input Bit 15	The input value for input	BOOL	FALSE	Input Bit 15		
	bit 15.					

#### • Thirty-two-point Input Units

Data name	Description	Data type	Default value	I/O port name	Index	Subin- dex
Input Bit 32 bits	The input values for 32	DWORD	00000000	Input Bit 32	6003 hex	01 hex
	bits.		hex	bits		
	The following 32 BOOL data are included.					
Input Bit 00	The input value for input bit 00.	BOOL	FALSE	Input Bit 00		
Input Bit 01	The input value for input bit 01.	BOOL	FALSE	Input Bit 01		
•						
•						
•						
Input Bit 31	The input value for input bit 31.	BOOL	FALSE	Input Bit 31		

# NX Units in Input Refreshing with Input Changed Time

# • Four-point Input Units

Data name	Description	Data type	Default value	I/O port name	Index	Subin- dex	Unit	
Input Bit 00	The input value for input bit 00.	BOOL	FALSE	Input Bit 00	6000 hex	01 hex		
Input Bit 01	The input value for input bit 01.	BOOL	FALSE	Input Bit 01			02 hex	
Input Bit 02	The input value for input bit 02.	BOOL	FALSE	Input Bit 02		03 hex		
Input Bit 03	The input value for input bit 03.	BOOL	FALSE	Input Bit 03		04 hex		
Input Bit 00 Time Stamp	The input changed time for input bit 00.	ULINT	0	Input Bit 00 Time Stamp	6010 hex	01 hex	ns	
Input Bit 01 Time Stamp	The input changed time for input bit 01.	ULINT	0	Input Bit 01 Time Stamp		02 hex	ns	
Input Bit 02 Time Stamp	The input changed time for input bit 02.	ULINT	0	Input Bit 02 Time Stamp		03 hex	ns	
Input Bit 03 Time Stamp	The input changed time for input bit 03.	ULINT	0	Input Bit 03 Time Stamp		04 hex	ns	

# 6-3 List of Settings

The followings are the setting descriptions, setting ranges, and default values of the functions that can be used in the Digital Input Units.

The settings are reflected after the Unit is restarted.



#### **Precautions for Safe Use**

The Unit is required to restart after the transfer of Unit operation settings on the Support Software is completed. Always sufficiently check the safety at the connected devices before you transfer the Unit operation settings.

# NX Units in Free-Run Refreshing or Synchronous I/O Refreshing

#### • Four-point Input Units

#### NX-ID3317/ID3417/IA3117

Setting name	Description	Default value	Setting range	Unit	Index	Subin- dex	Refer- ence
Input Filter Value Setting	Set the filter time of input	*1	*1		5000	01 hex	P. 6-14
	signal. *1				hex		
Input Filter Mode Setting	Set the operating mode	*2	*2			02 hex	
	for the filter *2						İ

<sup>\*1.</sup> The descriptions of Input Filter Value Setting are as follows.

Set value	Setting description	Default value	Setting range
0	No Filter	3	0 to 11
1	0.25 ms		
2	0.5 ms		
3	1 ms		
4	2 ms		
5	4 ms		
6	8 ms		
7	16 ms		
8	32 ms		
9	64 ms	1	
10	128 ms	1	
11	256 ms	1	

\*2. The descriptions of Input Filter Mode Setting are as follows.

Set value	Setting description	Default value	Setting range
0	Enable ON Filter and OFF Filter	0	0/1
1	Enable Only OFF Filter		

#### NX-ID3343/ID3443

Setting name	Description	Default value	Setting range	Unit	Index	Subin- dex	Refer- ence
Input Filter Value Setting	Set the filter time of input signal. *1	*1	*1		5001 hex	01 hex	P. 6-14
Input Filter Mode Setting	Set the operating mode for the filter. *2	*2	*2			02 hex	

<sup>\*1.</sup> The descriptions of Input Filter Value Setting are as follows.

Set value	Setting description	Default value	Setting range
0	No Filter	4	0 to 9
1	1 μs		
2	2 μs		
3	4 μs		
4	8 µs		
5	16 μs		
6	32 µs		
7	64 μs		
8	128 µs		
9	256 μs		

Set value	Setting description	Default value	Setting range
0	Enable ON Filter and OFF Filter	0	0/1
1	Enable Only OFF Filter		

#### • Eight-point Input Units

Setting name	Description	Default value	Setting range	Unit	Index	Subin- dex	Refer- ence
Input Filter Value Setting	Set the filter time of input signal. *1	*1	*1		5000 hex	01 hex	P. 6-14
Input Filter Mode Setting	Set the operating mode for the filter. *2	*2	*2			02 hex	

<sup>\*1.</sup> The descriptions of Input Filter Value Setting are as follows.

Set value	Setting description	Default value	Setting range
0	No Filter	3	0 to 11
1	0.25 ms		
2	0.5 ms		
3	1 ms		
4	2 ms		
5	4 ms		
6	8 ms		
7	16 ms		
8	32 ms		
9	64 ms		
10	128 ms		
11	256 ms		

Set value	Setting description	Default value	Setting range
0	Enable ON Filter and OFF Filter	0	0/1
1	Enable Only OFF Filter		

#### • Sixteen-point Input Units

Setting name	Description	Default value	Setting range	Unit	Index	Subin- dex	Refer- ence
Input Filter Value Setting	Set the filter time of input signal. *1	*1	*1		5000 hex	01 hex	P. 6-14
Input Filter Mode Setting	Set the operating mode for the filter. *2	*2	*2			02 hex	P. 6-14

<sup>\*1.</sup> The descriptions of Input Filter Value Setting are as follows.

Set value	Setting description	Default value	Setting range
0	No Filter	3	0 to 11
1	0.25 ms		
2	0.5 ms		
3	1 ms		
4	2 ms		
5	4 ms		
6	8 ms		
7	16 ms		
8	32 ms		
9	64 ms		
10	128 ms		
11	256 ms		

Set value	Setting description	Default value	Setting range
0	Enable ON Filter and OFF Filter	0	0/1
1	Enable Only OFF Filter		

#### • Thirty-two-point Input Units

Setting name	Description	Default value	Setting range	Unit	Index	Subin- dex	Refer- ence
Input Filter Value Setting	Set the filter time of input	*1	*1		5000	01 hex	P. 6-14
	signal. *1				hex		
Input Filter Mode Setting	Set the operating mode	*2	*2			02 hex	P. 6-14
	for the filter. *2						

<sup>\*1.</sup> The descriptions of Input Filter Value Setting are as follows.

Set value	Setting description	Default value	Setting range
0	No Filter	3	0 to 11
1	0.25 ms		
2	0.5 ms		
3	1 ms		
4	2 ms		
5	4 ms		
6	8 ms		
7	16 ms		
8	32 ms		
9	64 ms		
10	128 ms		
11	256 ms		

Set value	Setting description	Default value	Setting range
0	Enable ON Filter and OFF Filter	0	0/1
1	Enable Only OFF Filter		

# NX Units in Input Refreshing with Input Changed Time

# • Four-point Input Units

Setting name	Description	Default value	Setting range	Unit	Index	Subin- dex	Refer- ence
Input Bit 00 Trigger Set-	Set the trigger to read the	FALSE	TRUE or		5005	01 hex	P. 5-23
ting	input changed time.		FALSE		hex		
Input Bit 01 Trigger Set-	FALSE: Rising Edge					02 hex	
ting	TRUE: Falling Edge						
Input Bit 02 Trigger Set-	Trioning Lago					03 hex	
ting							
Input Bit 03 Trigger Set-						04 hex	
ting							
Input Bit 00 Mode Set-	Set the operation mode to	FALSE	TRUE or		5006	01 hex	P. 5-23
ting	read the input changed		FALSE		hex		
Input Bit 01 Mode Set-	time.					02 hex	
ting	FALSE: Continuous (Last						
Input Bit 02 Mode Set-	changed time)					03 hex	
ting	TRUE: One-shot (First						
Input Bit 03 Mode Set-	changed time)					04 hex	
ting	,						

# 6-4 Function

This section describes the Digital Input Unit functions.

Refer to the specifications of each model in *A-1 Data Sheet* on page A-3 for details on the functions.

# 6-4-1 List of Digital Input Unit Functions

Function name	Description	Reference
Free-Run Refreshing	With this I/O refreshing method, the refresh cycle of the NX bus and the I/O refresh cycles of the NX Units are asynchronous.	5-2-4 Free-Run Refreshing on page 5-9
Synchronous I/O Refreshing	With this I/O refreshing method, the timing to read inputs or to refresh outputs is synchronized on a fixed interval between more than one NX Unit connected to a CPU Unit.  In addition, with this I/O refreshing method, the timing to read inputs or to refresh outputs is synchronized on a fixed interval between more than one NX Unit on more than one Slave Terminal.	5-2-5 Synchro- nous Input Refreshing on page 5-13
Time Stamp Refreshing	With this I/O refreshing method, the NX Units record the DC times when inputs change or perform outputs at specified DC times. These times are not synchronized to the NX bus refresh cycles.  Data exchange between the NX Units and the CPU Unit and data exchange between the NX Units and the EtherCAT Coupler Unit are performed cyclically on the NX bus refresh cycles.	5-2-7 Time Stamp Refreshing on page 5-20
Input refreshing with input changed time	With this I/O refreshing method, the Input Units record the DC times when inputs changed.	5-2-8 Input Refreshing with Input Changed Time on page 5-21
Input Filter	This function eliminates the chattering or the noises from input signals. It is used to prevent the error reading due to the noises. You can set the filter time constant.	6-4-2 Input Filter on page 6-14

#### **Input Filter** 6-4-2

#### **Purpose**

This function prevents data changes and unstable data caused by changes of input data and unstable status of input bits due to chattering and noise.

You can also use this function to make the settings to easily read the pulses that ON time is short.

#### **Details on the Function**

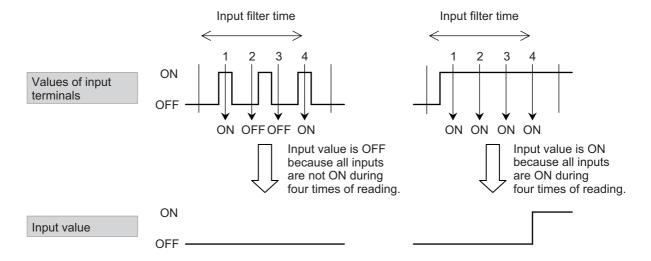
#### If Input Filter Mode Setting is Enable ON Filter and OFF Filter

Read the inputs at a 1/4 interval of the input filter time. When all inputs are ON or OFF, the input values turn ON or OFF.

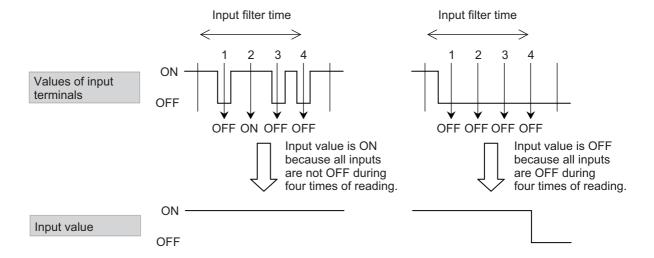
This prevents data changes and unstable data.

This function works for all inputs of the NX Units at the same time.

Operation when the input turns from OFF to ON (ON filter)



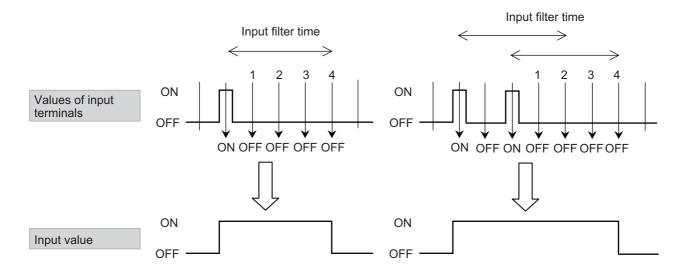
#### Operation when the input turns from ON to OFF (OFF filter)



#### • If Input Filter Mode Setting is Enable Only OFF Filter

ON filter is disabled and OFF filter is enabled.

This makes easily to read the pulses that ON time is short.



When input is ON (ON filter disabled)
If the status of input terminals turns ON,
the input value will turn ON immediately.

When input is OFF (OFF filter enabled)
If the status of input terminals does not turn ON again during the input filter time, the input value will turn OFF after the input filter time has passed.

When input is ON (ON filter disabled)
If the status of input terminals turns ON,
the input value will turn ON immediately.

When input is OFF (OFF filter enabled)
If the status of input terminals turns ON
again during the input filter time, the
input value stays ON from that time
during the input filter time.

You can use this function to set the following parameters.

- · Input Filter Value Setting
- · Input Filter Mode Setting

The values you can set for the Input Filter Value Setting depend on the model of Digital Input Units.

Townet Units	Cotting name	Description	Default	Unit
Target Units	Setting name	Description	value *1	Unit
Input Units and	Input Filter Value	Set the filter time for input signals.	3	
Mixed I/O Units in	Setting	0: No Filter		
which input		1: 0.25 ms		
ON/OFF response		2: 0.5 ms		
time exceeds 1 µs.		3: 1 ms		
		4: 2 ms		
		5: 4 ms		
		6: 8 ms		
		7: 16 ms		
		8: 32 ms		
		9: 64 ms		
		10: 128 ms		
		11: 256 ms		
Input Units and		Set the filter time for input signals.	4	
Mixed I/O Units in		0: No Filter		
which input		1: 1 µs		
ON/OFF response		2: 2 µs		
time is 1 µs maxi-		3: 4 µs		
mum.		4: 8 μs		
		5: 16 μs		
		6: 32 μs		
		7: 64 µs		
		8: 128 µs		
		9: 256 µs		
All Units	Input Filter Mode	Set the operating mode for the filter.	0	
	Setting	0: Enable ON Filter and OFF Filter		
		1: Enable Only OFF Filter		

<sup>\*1.</sup> If a value is set for the input filter time that is smaller than the default value, incorrect input caused by external noises occurs more easily. If an incorrect input occurs, either change the setting to make a long input filter time or take countermeasures, such as separate the Unit or signal lines and noise source, or protect the Unit or signal lines. Refer to Countermeasures to Reduce the Effects of Noise on page 4-53 for information on the countermeasures.

#### **Target NX Units**

The Digital Input Units that support switching Free-Run refreshing and Synchronous I/O refreshing.

You cannot use this function for the NX Units that support input refreshing with input changed time.

#### **Setting Method**

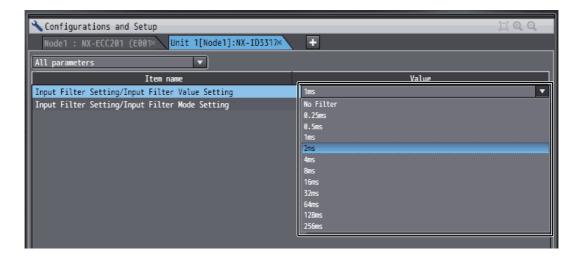
This section describes how to configure settings with the Sysmac Studio.

When you are using Support Software other than the Sysmac Studio, in the Edit Unit Operation Settings Tab Page, set the parameters described in the procedure and transfer the settings to the target NX Unit.

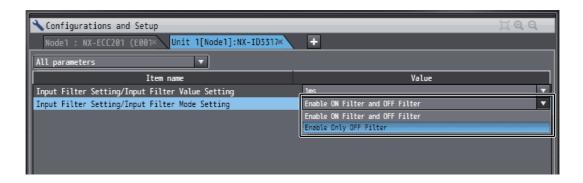
For details on how to display the Edit Unit Operation Settings Tab Page and to transfer settings to an NX Unit with Support Software other than the Sysmac Studio, refer to the operation manual for the Support Software that you are using.

- Display the Edit Unit Operation Settings Tab Page.

  For the display methods, refer to A-10 Displaying the Edit Unit Operation Settings Tab Page on page A-172.
- **2** Select the filter time you want to set from the upper list of Input Filter Setting.



3 Select the input filter mode you want to set from the lower list of Input Filter Setting.





#### **Additional Information**

- · If you set a value different from the default value, the Value on the Sysmac Studio is displayed in a different color.
- You can click the Return to Default Value Button to return all set values on the Sysmac Studio to the default values.
- · Help for the settings is displayed at the bottom of the Edit Unit Operation Settings Tab Page.



Click the Transfer to Unit Button.

The settings are transferred from the Sysmac Studio to the NX Unit.



The settings are reflected after the Unit is restarted.



#### **Precautions for Safe Use**

The Unit is required to restart after the transfer of Unit operation settings on the Support Software is completed. Always sufficiently check the safety at the connected devices before you transfer the Unit operation settings.

# **Precautions**

Note that when you use this function, the time for which the input value actually turns ON or turns OFF is delayed from the initial input to the input terminals until ON delay time or OFF delay time in the following table.

Delay time	Description
ON delay time	ON response time + input filter time
OFF delay time	OFF response time + input filter time



# **Digital Output Units**

This section describes the types and functions of Digital Output Units and points to consider when these Units are used.

7-1	Types	of Digital Output Units
	Specif	ications of I/O Data         7-5           Allocable I/O Data         7-5
7-3	List of	Settings
7-4	Functi	on
	7-4-1	List of Digital Output Unit Functions
	7-4-2	Load Rejection Output Setting
	7-4-3	Load Short-circuit Protection
7-5	Push-	pull Output
7-6	Precau	utions when Using the Relay Output Units

#### 7-1 **Types of Digital Output Units**

Digital Input Units are parts of NX Units, and process outputs of digital signals (ON/OFF signals). The Digital Output Unit types are described below.

#### Transistor Output Units (Screwless Clamping Terminal Block, 12 mm Width)

Model	Num ber of poin ts	Internal I/O common	Maximum value of load cur- rent	Rated volt- age	I/O refreshing method	ON/OFF response time	Reference								
NX-OD2154	_	NPN			Output		P. A-45								
NX-OD2258	point s	PNP	0.5 A/point, 1 A/Unit	24 VDC	refreshing with speci- fied time stamp only	300 ns max./300 ns max.	P. A-47								
NX-OD3121		NPN		12 to 24 VDC		0.1 ms max./0.8 ms max.	P. A-49								
NX-OD3153			0.5 A/point,	24 VDC		300 ns max./300 ns max.	P. A-51								
NX-OD3256	4 point s		2 A/Unit			0.5 ms max./1.0 ms max.	P. A-53								
NX-OD3257										PNP			Switching Synchro-	300 ns max./300 ns max.	P. A-55
NX-OD3268			2 A/point, 8 A/Unit		nous I/O refreshing and	0.5 ms max./1.0 ms max.	P. A-57								
NX-OD4121	8 point	NPN		12 to 24 VDC	Free-Run refreshing	0.1 ms max./0.8 ms max.	P. A-59								
NX-OD4256	S	PNP	0.5 A/point,	24 VDC		0.5 ms max./1.0 ms max.	P. A-61								
NX-OD5121	16 point	NPN	4 A/Unit	12 to 24 VDC		0.1 ms max./0.8 ms max.	P. A-63								
NX-OD5256	S	PNP		24 VDC		0.5 ms max./1.0 ms max.	P. A-65								

# Transistor Output Units (M3 Screw Terminal Block, 30 mm Width)

Model	Num- ber of points	Internal I/O common	Maximum value of load cur- rent	Rated volt- age	I/O refresh- ing method	ON/OFF response time	Refer- ence
NX-OD5121-1	16 points	NPN	0.5 A/point,	12 to 24 VDC	Synchro- nous I/O refreshing and Free-Run	0.1 ms max./0.8 ms max.	P. A-67
NX-OD5256-1		PNP	5 A/Unit	24 VDC		0.5 ms max./1.0 ms max.	P. A-69

# Transistor Output Units (MIL Connector, 30 mm Width)

Model	Num- ber of points	Internal I/O common	Maximum value of load cur- rent	Rated volt- age	I/O refresh- ing method	ON/OFF response time	Refer- ence
NX-OD5121-5	16	NPN	0.5 A/point, 2 A/Unit	12 to 24 VDC	Switching	0.1 ms max./0.8 ms max.	P. A-71
NX-OD5256-5	points	PNP		24 VDC	Switching Synchro- nous I/O refreshing	0.5 ms max./1.0 ms max.	P. A-73
NX-OD6121-5	32	NPN	0.5 A/point, 2 A/com-	· · · · · · · · · · · · · · · · · · · ·		0.1 ms max./0.8 ms max.	P. A-75
NX-OD6256-5	points	PNP	mon, 4 A/Unit	24 VDC	refreshing	0.5 ms max./1.0 ms max.	P. A-77

# Transistor Output Units (Fujitsu Connector, 30 mm Width)

Model	Num- ber of points	Internal I/O common	Maximum value of load cur- rent	Rated volt- age	I/O refresh- ing method	ON/OFF response time	Refer- ence
NX-OD6121-6	32 points	NPN	0.5 A/point, 2 A/com- mon, 4 A/Unit	12 to 24 VDC	Switching Synchro- nous I/O refreshing and Free-Run refreshing	0.1 ms max./0.8 ms max.	P. A-79

# Relay Output Units (Screwless Clamping Terminal Block, 12 mm Width)

Model	Num ber of poin ts	Relay type	Maximum switching capacity	I/O refresh- ing method	ON/OFF response time	Reference
NX-OC2633	2	N.O.	250 VAC/2 A ( $cosΦ = 1$ ),		15 ms	P. A-81
NX-OC2733	point s	N.O. + N.C.	250 VAC/2 A ( $\cos \Phi = 0.4$ ), F	Free-Run refreshing	max./15 ms max.	P. A-83

# Relay Output Units (Screwless Clamping Terminal Block, 24 mm Width)

Model	Num ber of poin ts	Relay type	Maximum switching capacity	I/O refresh- ing method	ON/OFF response time	Reference
NX-OC4633	8 point s	N.O.	250 VAC/2A (cosφ=1), 250 VAC/2A (cosφ=0.4), 24 VDC/2A, 8 A/Unit	Free-Run refreshing	15 ms max./15 ms max.	P. A-85

# 7-2 Specifications of I/O Data

This section describes I/O data for the Digital Output Units.

#### 7-2-1 Allocable I/O Data

This section describes the allocable I/O data in the Digital Output Unit.

An I/O entry mapping is assigned to the I/O allocation settings for the Digital Output Unit except the Unit that supports output refreshing with specified time stamp.

In the Unit that supports output refreshing with specified time stamp, one I/O entry mapping for input and one I/O entry mapping for output are assigned.

A specific I/O entry is assigned to the I/O entry mapping for each NX Unit model. These allocations are fixed, so you cannot add others or change them.

An I/O entry means the I/O data described in this section. An I/O entry mapping means a collection of I/O entries.

To assign the I/O allocation information of the NX Unit or Slave Terminal to an NJ/NX-series CPU Unit or NY-series Industrial PC, use the I/O ports for the allocated I/O data.

However, for Slave Terminals, I/O ports may not be used depending on the type of communications master or Communications Coupler Unit.

Refer to the user's manual for the connected Communications Coupler Unit for details on how to use I/O data for Slave Terminals.

Refer to the user's manual for the Communication Control Unit for details on how to use I/O data for Communication Control Units.

# NX Units in Free-Run Refreshing or Synchronous I/O Refreshing

#### Two-point Output Units

Data name	Description	Data type	Default value	I/O port name	Index	Subin- dex
Output Bit 00	The output set value for output bit 00.	BOOL	FALSE	Output Bit 00	7000 hex	01 hex
Output Bit 01	The output set value for output bit 01.	BOOL	FALSE	Output Bit 01		02 hex

# • Four-point Output Units

Data name	Description	Data type	Default value	I/O port name	Index	Subin- dex
Output Bit 00	The output set value for output bit 00.	BOOL	FALSE	Output Bit 00	7000 hex	01 hex
Output Bit 01	The output set value for output bit 01.	BOOL	FALSE	Output Bit 01		02 hex
Output Bit 02	The output set value for output bit 02.	BOOL	FALSE	Output Bit 02		03 hex
Output Bit 03	The output set value for output bit 03.	BOOL	FALSE	Output Bit 03		04 hex

# • Eight-point Output Units

Data name	Description	Data type	Default value	I/O port name	Index	Subin- dex
Output Bit 8 bits	The output values for 8 bits.	BYTE	00 hex	Output Bit 8 bits	7001 hex	01 hex
	The following 8 BOOL data are included.					
Output Bit 00	The output set value for output bit 00.	BOOL	FALSE	Output Bit 00		
Output Bit 01	The output set value for output bit 01.	BOOL	FALSE	Output Bit 01		
Output Bit 02	The output set value for output bit 02.	BOOL	FALSE	Output Bit 02		
Output Bit 03	The output set value for output bit 03.	BOOL	FALSE	Output Bit 03		
Output Bit 04	The output set value for output bit 04.	BOOL	FALSE	Output Bit 04		
Output Bit 05	The output set value for output bit 05.	BOOL	FALSE	Output Bit 05		
Output Bit 06	The output set value for output bit 06.	BOOL	FALSE	Output Bit 06		
Output Bit 07	The output set value for output bit 07.	BOOL	FALSE	Output Bit 07		

#### • Sixteen-point Output Units

Data name	Description	Data type	Default value	I/O port name	Index	Subin- dex
Output Bit 16 bits	The output values for 16 bits.	WORD	0000 hex	Output Bit 16 bits	7002 hex	01 hex
	The following 16 BOOL data are included.					
Output Bit 00	The output set value for output bit 00.	BOOL	FALSE	Output Bit 00		
Output Bit 01	The output set value for output bit 01.	BOOL	FALSE	Output Bit 01		
•						
•						
Output Bit 15	The output set value for output bit 15.	BOOL	FALSE	Output Bit 15		

# • Thirty-two-point Output Units

Data name	Description	Data type	Default value	I/O port name	Index	Subin- dex
Output Bit 32 bits	The output values for 32	DWORD	00000000	Output Bit 32	7003 hex	01 hex
	bits.		hex	bits		
	The following 32 BOOL					
	data are included.					
Output Bit 00	The output set value for	BOOL	FALSE	Output Bit 00		
	output bit 00.					
Output Bit 01	The output set value for	BOOL	FALSE	Output Bit 01		
	output bit 01.					
•						
•						
•						
Output Bit 31	The output set value for	BOOL	FALSE	Output Bit 31		
	output bit 31.					

# NX Units in Output Refreshing with Specified Time Stamp

#### • Two-point Output Units

Data name	Description	Data type	Default value	I/O port name	Index	Subin- dex	Unit
Output Bit 00	The output set value for output bit 00.	BOOL	FALSE	Output Bit 00	7000 hex	01 hex	
Output Bit 01	The output set value for output bit 01.	BOOL	FALSE	Output Bit 01		02 hex	
Output Bit 00 Time Stamp	The specified operation time for output bit 00. If the value is 0, the output is refreshed immediately.	ULINT	0	Output Bit 00 Time Stamp	7010 hex	01 hex	ns
Output Bit 01 Time Stamp	The specified operation time for output bit 01. If the value is 0, the output is refreshed immediately.	ULINT	0	Output Bit 01 Time Stamp		02 hex	ns
Output Bit 00 Output Status	The specified time output status for output bit 00.	BOOL	FALSE	Output Bit 00 Output Sta- tus	6011 hex	01 hex	
Output Bit 01 Output Status	The specified time output status for output bit 01.	BOOL	FALSE	Output Bit 01 Output Sta- tus		02 hex	

# 7-3 List of Settings

The followings are the setting descriptions, setting ranges, and default values of the functions that can be used in the Digital Output Units.

The settings are reflected after the Unit is restarted.



#### **Precautions for Safe Use**

The Unit is required to restart after the transfer of Unit operation settings on the Support Software is completed. Always sufficiently check the safety at the connected devices before you transfer the Unit operation settings.

### NX Units in Free-Run Refreshing or Synchronous I/O Refreshing

#### Two-point Output Units

Setting name	Description	Default value	Setting range	Unit	Index	Subin- dex	Refer- ence
Load Rejection Output for Output Bit 00	Set the output at load OFF.	FALSE	TRUE or FALSE		5010 hex	01 hex	P. 7-13
Load Rejection Output for Output Bit 01	FALSE: OFF TRUE: Hold the present value.	FALSE	TRUE or FALSE			02 hex	

#### • Four-point Output Units

Setting name	Description	Default value	Setting range	Unit	Index	Subin- dex	Refer- ence
Load Rejection Output	Set the output at load	FALSE	TRUE or		5010	01 hex	P. 7-13
for Output Bit 00	OFF.		FALSE		hex		
Load Rejection Output	FALSE: OFF	FALSE	TRUE or			02 hex	
for Output Bit 01	TRUE: Hold the present		FALSE				
Load Rejection Output	value.	FALSE	TRUE or			03 hex	
for Output Bit 02			FALSE				
Load Rejection Output		FALSE	TRUE or			04 hex	
for Output Bit 03			FALSE				

# • Eight-point Output Units

Setting name	Description	Default	Setting	Unit	Index	Subin-	Refer-
Setting name	Description	value	range	Oilit	IIIGEX	dex	ence
Load Rejection Output	Set the output at load OFF	00 hex	00 to FF		5011	01 hex	P. 7-13
for Output Bit (8 bits)	in units of 8 bits.		hex		hex		
	Bit 0: Setting for output bit 00						
	Bit 1: Setting for output bit						
	01						
	Bit 2: Setting for output bit						
	02						
	Bit 3: Setting for output bit						
	03						
	Bit 4: Setting for output bit 04						
	Bit 5: Setting for output bit						
	05						
	Bit 6: Setting for output bit						
	06						
	Bit 7: Setting for output bit						
	07						
	FALSE: OFF						
	TRUE: Hold the present						
	value.						

#### • Sixteen-point Output Units

Setting name	Description	Default value	Setting range	Unit	Index	Subin- dex	Refer- ence
Load Rejection Output for Output Bit (16 bits)	Set the output at load OFF in units of 16 bits.	0000 hex	0000 to		5012 hex	01 hex	P. 7-13
	Bit 0: Setting for output bit 00 Bit 1: Setting for output bit 01 •						
	•						
	Bit 15: Setting for output bit 15						
	FALSE: OFF TRUE: Hold the present value.						

#### • Thirty-two-point Output Units

Setting name	Description	Default value	Setting range	Unit	Index	Subin- dex	Refer- ence
Load Rejection Output	Set the output at load OFF	000000	0000000		5013	01 hex	P. 7-13
for Output Bit (32 bits)	in units of 32 bits.	00 hex	0 to		hex		
	Bit 0: Setting for output bit		FFFFFF				
	00		F hex				
	Bit 1: Setting for output bit						
	01						
	•						
	•						
	•						
	Bit 31: Setting for output						
	bit 31						
	FALSE: OFF						
	TRUE: Hold the present						
	value.						

# NX Units in Output Refreshing with Specified Time Stamp

#### • Two-point Output Units

Setting name	Description	Default value	Setting range	Unit	Index	Subin- dex	Refer- ence
Load Rejection Output	Set the output at load	FALSE	TRUE or		5010	01 hex	P. 7-13
for Output Bit 00	OFF.		FALSE		hex		
Load Rejection Output for Output Bit 01	FALSE: OFF TRUE: Hold the present value.	FALSE	TRUE or FALSE			02 hex	

# 7-4 Function

This section describes the Digital Output Unit functions.

Refer to the specifications of each model in A-1 Data Sheet on page A-3 for details on the functions.

#### **List of Digital Output Unit Functions** 7-4-1

Function name	Description	Reference
Free-Run Refreshing	With this I/O refreshing method, the refresh cycle of the NX bus and the I/O refresh cycles of the NX Units are asynchronous.	5-2-4 Free-Run Refreshing on page 5-9
Synchronous I/O Refreshing	With this I/O refreshing method, the timing to read inputs or to refresh outputs is synchronized on a fixed interval between more than one NX Unit connected to a CPU Unit.  In addition, with this I/O refreshing method, the timing to read inputs or to refresh outputs is synchronized on a fixed interval between more than one NX Unit on more than one Slave Terminal.	5-2-6 Synchro- nous Output Refreshing on page 5-17
Time Stamp Refreshing	With this I/O refreshing method, the NX Units record the DC times when inputs change or perform outputs at specified DC times. These times are not synchronized to the NX bus refresh cycles.  Data exchange between the NX Units and the CPU Unit and data exchange between the NX Units and the EtherCAT Coupler Unit are performed cyclically on the NX bus refresh cycles.	5-2-7 Time Stamp Refreshing on page 5-20
Output refreshing with specified time stamp	With this I/O refreshing method, the Output Units refresh outputs at specified DC times.	5-2-9 Output Refreshing with Specified Time Stamp on page 5-28
Load Rejection Output Setting	A function that performs the preset output operation when the Digital Output Unit cannot receive output data due to the following causes:     When the Unit is connected to a CPU Unit: NX bus error, CPU Unit watchdog timer error, etc.     When the Unit is connected to a Communications Coupler Unit: Host error on the Communications Coupler Unit, NX bus error, etc.	7-4-2 Load Rejection Output Setting on page 7-13
	When the Unit is connected to a Communication Control Unit: NX bus error, Communication Control Unit watchdog timer error, etc.	
Load Short-circuit Protection	A function in which the output will turn OFF to protect the output circuit when an overload or load short-circuit occurs due to a failure of the connected external devices.	7-4-3 Load Short-circuit Pro- tection on page 7-17

#### 7-4-2 Load Rejection Output Setting

#### **Purpose**

This function maintains a safe output status by performing the preset output operations when the Digital Output Unit cannot receive output data from a remote device due to the following causes:

- When the Unit is connected to a CPU Unit: NX bus error, CPU Unit watchdog timer error, etc.
- When the Unit is connected to a Communications Coupler Unit: Host error on the Communications Coupler Unit, NX bus error, etc.
- When the Unit is connected to a Communication Control Unit: NX bus error, Communication Control Unit watchdog timer error, etc.

#### **Details on the Function**

Sets whether to hold the output or turn it OFF when an error occurred.

Each output bit can be set independently.

#### Two-point Output Units

Setting name	Description	Default value	Unit
•	Set the output at load OFF.	FALSE	
Output Bit 00	FALSE: OFF		
Load Rejection Output for	TRUE: Hold the present value.	FALSE	
Output Bit 01	·		

#### Four-point Output Units

Setting name	Description	Default value	Unit
Load Rejection Output for Output Bit 00	Set the output at load OFF. FALSE: OFF	FALSE	
Load Rejection Output for Output Bit 01	TRUE: Hold the present value.	FALSE	
Load Rejection Output for Output Bit 02		FALSE	
Load Rejection Output for Output Bit 03		FALSE	

#### • Eight-point Output Units

Setting name	Description	Default value	Unit
Load Rejection Output for Output Bit (8 bits)	Set the output at load OFF in units of 8 bits.  Bit 0: Setting for output bit 00  Bit 1: Setting for output bit 01  Bit 2: Setting for output bit 02  Bit 3: Setting for output bit 03  Bit 4: Setting for output bit 04  Bit 5: Setting for output bit 05  Bit 6: Setting for output bit 06  Bit 7: Setting for output bit 07  FALSE: OFF  TRUE: Hold the present value.	00 hex	

#### • Sixteen-point Output Units

Setting name	Description	Default value	Unit
Load Rejection Output for	Set the output at load OFF in units of 16 bits.	0000 hex	
Output Bit (16 bits)	Bit 0: Setting for output bit 00		
	Bit 1: Setting for output bit 01		
	•		
	•		
	•		
	Bit 15: Setting for output bit 15		
	FALSE: OFF		
	TRUE: Hold the present value.		

#### • Thirty-two-point Output Units

Setting name	Description	Default value	Unit
Load Rejection Output for	Set the output at load OFF in units of 32 bits.	00000000	
Output Bit (32 bits)	Bit 0: Setting for output bit 00 Bit 1: Setting for output bit 01	hex	
	•		
	•		
	•		
	Bit 31: Setting for output bit 31		
	FALSE: OFF TRUE: Hold the present value.		

# **Target NX Units**

All Digital Output Units

#### **Setting Method**

This section describes how to configure settings with the Sysmac Studio.

When you are using Support Software other than the Sysmac Studio, in the Edit Unit Operation Settings Tab Page, set the parameters described in the procedure and transfer the settings to the target NX Unit.

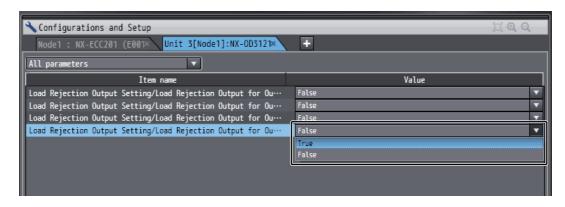
For details on how to display the Edit Unit Operation Settings Tab Page and to transfer settings to an NX Unit with Support Software other than the Sysmac Studio, refer to the operation manual for the Support Software that you are using.

- **1** Display the Edit Unit Operation Settings Tab Page.

  For the display methods, refer to *A-10 Displaying the Edit Unit Operation Settings Tab Page* on page A-172.
- **2** Make the following settings according to the type of NX Unit you want to set.

Two-point or Four-point Output Unit (Data type: BOOL)

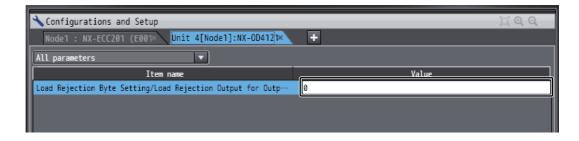
Select *False* (OFF) or *True* (Hold the present value) from the list of Load Rejection Output Setting for which the output bit you want to set.



Eight-point, Sixteen-point, and Thirty-two-point Output Units

Enter a set value in the Value text box. The data type of the set values and the range of the values that you can set vary depending on the number of output points.

Number of output points	Data type	Set value
8 points	USINT	0 to 255
16 points	UINT	0 to 65535
32 points	UDINT	0 to 4294967295





#### **Additional Information**

- If you set a value different from the default value, the Value on the Sysmac Studio is displayed in a different color.
- · You can click the Return to Default Value Button to return all set values on the Sysmac Studio to the default values.
- Help for the settings is displayed at the bottom of the Edit Unit Operation Settings Tab Page.
- Click the Transfer to Unit Button.

The settings are transferred from the Sysmac Studio to the NX Unit.



The settings are reflected after the Unit is restarted.



#### **Precautions for Safe Use**

The Unit is required to restart after the transfer of Unit operation settings on the Support Software is completed. Always sufficiently check the safety at the connected devices before you transfer the Unit operation settings.

## 7-4-3 Load Short-circuit Protection

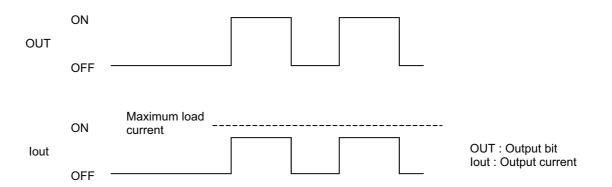
## **Purpose**

This function is used to protect the output circuits of the Digital Output Units when an external connection load short-circuit occurs.

## **Details on the Function**

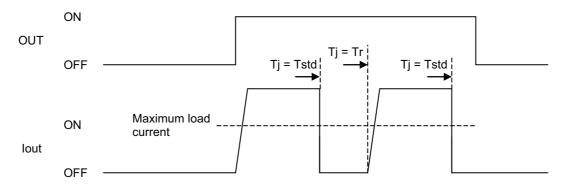
As shown in the figure below, normally when the output bit (OUT) turns ON, the transistor turns ON and then output current (lout) will flow.

The transistor of the Transistor Output Units generates heat when output current (lout) flows.



If an overload or short-circuit occurs, causing the output current (lout) to exceed the maximum value of load current as shown in the figure below and the junction temperature (Tj) of the transistor to reach the thermal shutdown temperature (Tstd) in which a load short-circuit protection operates, the output will turn OFF to protect the transistor from being damaged.

When the junction temperature (Tj) of the transistor drops down to the reset temperature (Tr), the output OFF will be automatically reset and the output current will start flowing.



OUT : Output bit lout : Output current

Tj: Junction temperature of transistor Tstd: Thermal shutdown temperature

Tr : Reset temperature

#### Restrictions on Use

The load short-circuit protection function only protects internal circuits for a short period.

As shown in the figure above, the load short-circuit protection of this NX Unit is automatically released when the Tj equals to Tr.

Therefore, unless the cause of short-circuit is removed, ON/OFF operations are repeated in the output.

If the short-circuit is not corrected, output elements deteriorate. If any external load is short-circuited, immediately turn OFF the applicable output and remove the cause of the short-circuit.

# **Target NX Units**

Digital Output Units of PNP outputs

# **Setting Method**

No setting is required.

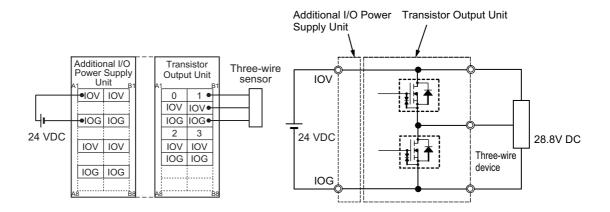
# 7-5 Push-pull Output

The Digital Output Units with the ON/OFF response time of 1  $\mu$ s or less use a push-pull output to increase the speed of the output ON/OFF response.

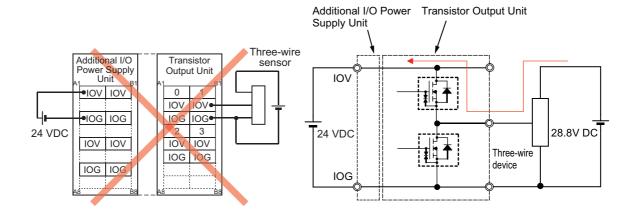
For this type of the Output Units, use the single load power supply for the I/O power and connected external devices.

If multiple power supplies are used, the current may flow into the output bits via the diodes built in the I/O circuit and cause the Output Units to malfunction.

## Good Example



#### Bad Example



# **Precautions when Using the Relay** 7-6 **Output Units**

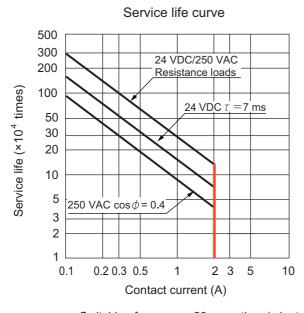
This section describes precautions when using the Relay Output Units.

# **Relay Service Life**

The service life of Relay Output Units depends on the type of load, contact current and ambient temperature.

Use the following diagrams to calculate the relay service life based on the operating conditions, and replace the NX Unit before the end of its service life.

#### Contact Current vs. Service Life Characteristic



Switching frequency: 20 operations/minute



#### **Precautions for Correct Use**

The above chart shows the life characteristics for individual relays. Do not exceed the specifications of the Relay Output Units. If a switching capacity exceeding the specifications is used, the reliability and life expectancy of other parts will be reduced and the NX Unit may malfunction.

# **Inductive Load**

The life of the Relay varies with the load inductance.

If any inductive load is used, we recommend that you use a contact protection circuit. (Contact Protection Circuit on page 7-21).

Be sure to connect a contact protection circuit in parallel with every DC inductive load that is connected to the Contact Output Unit because the usage of a contact protection circuit has a significant effect on the service life of the contact.

# **Contact Protection Circuit**

Contact protection circuits are used with the Contact Output Unit in order to prolong the life of each relay mounted to the Contact Output Unit, prevent noise, and reduce the generation of carbide and nitrate deposits caused by arcs. However, if contact protection circuits are used incorrectly, they can reduce relay service life. Using a contact protection circuit can also cause a delay in the resetting time (shut-off time).

Contact protection circuit examples are listed in the following table.

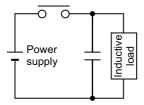
	Circuit	Cur	rent	nt Feature Required elem	
	Circuit	AC	DC	reature	Required element
CR method	Power supply R R	Yes	Yes	If the load is a relay or solenoid, there is a delay in the resetting time.  If the power supply voltage is 24 or 48 V, connect the contact protection circuit in parallel with the load. If the supply voltage is 100 to 200 V, connect the contact protection circuit between the contacts.	The capacitance of the capacitor should be approx. 1 to 0.5 $\mu$ F per contact current of 1 A and resistance of the resistor should be approx. 0.5 to 1 $\Omega$ per contact voltage of 1 V. C: The capacitance of the capacitor should be approx. 0.5 to 1 $\mu$ F per contact current of 1 A. R: The resistance of the resistor should be approx. 0.5 to 1 $\mu$ F per contact current of 1 A. R: The resistance of the resistor should be approx. 0.5 to 1 $\Omega$ per contact voltage of 1 V. These values, however, vary depending on the load and the characteristics of the relay. Decide these values from experiments, and take into consideration that the capacitance suppresses spark discharge when the contacts are separated and the resistance restricts the current that flows into the load when the circuit is closed again. The dielectric strength of the capacitor must be 200 to 300 V. If the circuit is an AC circuit, use a capacitor with no polarity.

	Circuit	Cur	rent	Feature	Required element
	Circuit	AC	DC	reature	Required element
Diode method	Power supply peol	×	Yes	The diode connected in parallel with the load changes energy accumulated by the coil into a current, which then flows into the coil so that the current will be converted into Joule heat by the resistance of the inductive load.  The delay in resetting time caused by this method is longer than that caused by the CR method.	The reversed dielectric strength value of the diode must be at least 10 times as large as the circuit voltage value. The forward current of the diode must be the same as or larger than the load current.  The reversed dielectric strength value of the diode may be two to three times larger than the power supply voltage if the contact protection circuit is applied to electronic circuits with low circuit voltages.
Varistor method	Power supply   Inductive   load	Yes	Yes	The varistor method prevents the imposition of high voltage between the contacts by using the constant voltage characteristic of the varistor. There is a delay in the resetting time.  If the power supply voltage is 24 to 48 V, insert the varistor in parallel with the load. If the supply voltage is 100 to 200 V, insert the varistor between the contacts.	-



### **Precautions for Correct Use**

Do not connect a contact protection circuit with an inductive load as shown in the diagram below.



This contact protection circuit is very effective for preventing spark discharge when the circuit is opened. However, when the contacts are closed, the contacts may be welded due to the current charged in the capacitor. DC inductive loads can be more difficult to switch than resistive loads. If an appropriate contact protection circuit is used, however, DC inductive loads are as easy to switch as resistive loads.



# **Digital Mixed I/O Units**

This section describes the types and functions of Digital Mixed I/O Units and points to consider when these Units are used.

8-1	Types	of Digital Mixed I/O Units	8-2
8-2	Specifi	ications of I/O Data	8-3
	8-2-1	Allocable I/O Data	8-3
8-3	List of	Settings	8-5
	8-3-1	Input Settings	8-5
	8-3-2	Output Settings	8-6
8-4	Functi	on	8-7
	8-4-1	Input Functions	8-7
	8-4-2	Output Functions	8-8

## Types of Digital Mixed I/O Units 8-1

Digital Mixed I/O Units are parts of NX Units, and process both inputs and outputs of digital signals (ON/OFF signals).

The Digital Mixed I/O Unit types are described below.

# DC Input/Transistor Output Units (MIL Connector, 30 mm Width)

Model	Num- ber of points	Internal I/O com- mon	Maximum value of load cur- rent	Rated volt- age	I/O refresh- ing method	ON/OFF response time	Refer- ence
NX-MD6121-5	Out- puts: 16 points	Outputs: NPN Inputs: For both NPN/PNP	0.5 A/point,	Outputs: 12 to 24 VDC Switching Synchro- Synchro- ms max./0.8 ms max./0.8 ms max./0.8		Inputs: 20 µs max./400 µs	P. A-89
NX-MD6256-5	Inputs: 16 points	Outputs: PNP Inputs: For both NPN/PNP	2 A/Unit	Outputs: 24 VDC Inputs: 24 VDC	and Free-Run refreshing	Outputs: 0.5 ms max./1.0 ms max. Inputs: 20 µs max./400 µs max.	P. A-93

# DC Input/Transistor Output Units (Fujitsu Connector, 30 mm Width)

Model	Num- ber of points	Internal I/O common	Maximum value of load cur- rent	Rated volt- age	I/O refresh- ing method	ON/OFF response time	Refer- ence
NX-MD6121-6	Out- puts: 16 points Inputs: 16 points	Outputs: NPN Inputs: For both NPN/PNP	0.5 A/point, 2 A/Unit	Outputs: 12 to 24 VDC Inputs: 24 VDC	Switching Synchro- nous I/O refreshing and Free-Run refreshing	Outputs: 0.1 ms max./0.8 ms max. Inputs: 20 µs max./400 µs max.	P. A-97

# 8-2 Specifications of I/O Data

This section describes I/O data for the Digital Mixed I/O Units.

### 8-2-1 Allocable I/O Data

This section describes the allocable I/O data in the Digital Mixed I/O Units.

An I/O entry mapping is assigned to the I/O allocation settings for the Digital Mixed I/O Units.

A specific I/O entry is assigned to the I/O entry mapping for each NX Unit model. These allocations are fixed, so you cannot add others or change them.

An I/O entry means the I/O data described in this section. An I/O entry mapping means a collection of I/O entries.

To assign the I/O allocation information of the NX Unit or Slave Terminal to an NJ/NX-series CPU Unit or NY-series Industrial PC, use the I/O ports for the allocated I/O data.

However, for Slave Terminals, I/O ports may not be used depending on the type of communications master or Communications Coupler Unit.

Refer to the user's manual for the connected Communications Coupler Unit for details on how to use I/O data for Slave Terminals.

Refer to the user's manual for the Communication Control Unit for details on how to use I/O data for Communication Control Units.

# NX Units in Free-Run Refreshing or Synchronous I/O Refreshing

#### Thirty-two-point Mixed I/O Units

Input section

Data name	Description	Data type	Default value	I/O port name	Index	Subin- dex
Input Bit 16 bits	The input values for 16 bits.	WORD	0000 hex	Input Bit 16 bits	6002 hex	01 hex
	The following 16 BOOL data are included.					
Input Bit 00	The input value for input bit 00.	BOOL	FALSE	Input Bit 00		
Input Bit 01	The input value for input bit 01.	BOOL	FALSE	Input Bit 01		
•						
•						
Input Bit 15	The input value for input bit 15.	BOOL	FALSE	Input Bit 15		

## Output section

Data name	Description	Data type	Default value	I/O port name	Index	Subin- dex
Output Bit 16 bits	The output values for 16 bits.	WORD	0000 hex	Output Bit 16 bits	7002 hex	01 hex
	The following 16 BOOL data are included.					
Output Bit 00	The output set value for output bit 00.	BOOL	FALSE	Output Bit 00		
Output Bit 01	The output set value for output bit 01.	BOOL	FALSE	Output Bit 01		
•						
•						
•						
Output Bit 15	The output set value for output bit 15.	BOOL	FALSE	Output Bit 15		

# 8-3 List of Settings

The following are the setting descriptions, setting ranges, and default values of the functions that can be used in the Digital Mixed I/O Units.

The settings are reflected after the Unit is restarted.



#### **Precautions for Safe Use**

The Unit is required to restart after the transfer of Unit operation settings on the Support Software is completed. Always sufficiently check the safety at the connected devices before you transfer the Unit operation settings.

## 8-3-1 Input Settings

This section describes the allocable I/O data in the Digital Mixed I/O Units.

# NX Units in Free-Run Refreshing or Synchronous I/O Refreshing

## Sixteen-point Input Units

Setting name	Description	Default value	Setting range	Unit	Index	Subin- dex	Refer- ence
Input Filter Value Setting	Set the filter time of input signal. *1	*1	*1		5000 hex	01 hex	P. 6-14
Input Filter Mode Setting	Set the operating mode for the filter. *2	*2	*2			02 hex	P. 6-14

<sup>\*1.</sup> The descriptions of Input Filter Value Setting are as follows.

Set value	Setting description	Default value	Setting range
0	No Filter	3	0 to 11
1	0.25 ms	]	
2	0.5 ms	]	
3	1 ms	7	
4	2 ms		
5	4 ms	]	
6	8 ms	7	
7	16 ms		
8	32 ms	7	
9	64 ms	7	
10	128 ms	7	
11	256 ms	7	

\*2. The descriptions of Input Filter Mode Setting are as follows.

Set value	Setting description	Default value	Setting range
0	Enable ON Filter and OFF Filter	0	0/1
1	Enable Only OFF Filter		

#### 8-3-2 **Output Settings**

# NX Units in Free-Run Refreshing or Synchronous I/O Refreshing

# • Sixteen-point Output Units

Setting name	Description	Default value	Setting range	Unit	Index	Subin- dex	Refer- ence
Load Rejection Output for Output Bit (16 bits)	Set the output at load OFF in units of 16 bits.	0000 hex	0000 to FFFF hex		5012 hex	01 hex	P. 7-13
	Bit 0: Setting for output bit 00						
	Bit 1: Setting for output bit 01						
	•						
	•						
	•						
	Bit 15: Setting for output bit 15						
	FALSE: OFF						
	TRUE: Hold the present value.						

# 8-4 Function

This section describes the Digital Mixed I/O Unit functions.

Refer to the specifications of each model in *A-1 Data Sheet* on page A-3 for details on the functions.

# 8-4-1 Input Functions

Function name	Description	Reference
Free-Run Refreshing	With this I/O refreshing method, the refresh cycle of the NX bus and the I/O refresh cycles of the NX Units are asynchronous.	5-2-4 Free-Run Refreshing on page 5-9
Synchronous I/O Refreshing	With this I/O refreshing method, the timing to read inputs or to refresh outputs is synchronized on a fixed interval between more than one NX Unit connected to a CPU Unit.  In addition, with this I/O refreshing method, the timing to read inputs or to refresh outputs is synchronized on a fixed interval between more than one NX Unit on more than one Slave Terminal.	5-2-5 Synchro- nous Input Refreshing on page 5-13
Input Filter	This function eliminates the chattering or the noises from input signals.  It is used to prevent the error reading due to the noises. You can set the filter time constant.	6-4-2 Input Filter on page 6-14

#### 8-4-2 **Output Functions**

Function name	Description	Reference
Free-Run Refreshing	With this I/O refreshing method, the refresh cycle of the NX bus and the I/O refresh cycles of the NX Units are asynchronous.	5-2-4 Free-Run Refreshing on page 5-9
Synchronous I/O Refreshing	With this I/O refreshing method, the timing to read inputs or to refresh outputs is synchronized on a fixed interval between more than one NX Unit connected to a CPU Unit.  In addition, with this I/O refreshing method, the timing to read inputs or to refresh outputs is synchronized on a fixed interval	5-2-5 Synchro- nous Input Refreshing on page 5-13
	between more than one NX Unit on more than one Slave Terminal.	
Load Rejection Output Setting	A function that performs the preset output operation when the Digital Mixed I/O Unit cannot receive output data due to the following causes:	7-4-2 Load Rejection Output Setting on page 7-13
	When the Unit is connected to a CPU Unit: NX bus error, CPU Unit watchdog timer error, etc.	
	When the Unit is connected to a Communications Coupler Unit: Host error on the Communications Coupler Unit, NX bus error, etc.	
	When the Unit is connected to a Communication Control Unit: NX bus error, Communication Control Unit watchdog timer error, etc.	
Load Short-circuit Protection	A function in which the output will turn OFF to protect the output circuit when an overload or load short-circuit occurs due to a failure of the connected external devices.	7-4-3 Load Short-circuit Pro- tection on page 7-17

# **Troubleshooting**

This section describes the error information and corrections for errors that can occur when the Digital I/O Units are used.

9-1	How to	o Check for Errors 9-2
9-2	Check	ing for Errors with the Indicators
9-3	<b>Check</b> 9-3-1	ing for Errors and Troubleshooting on the Support Software 9-5
	9-3-1	Checking for Errors from the Sysmac Studio
	9-3-3	Event Codes and Corrections for Errors
	9-3-4	Meaning of Error
9-4	Resett	ting Errors
9-5	Troub	les Specific To Each Type of NX Units
	9-5-1	Digital Inputs
	9-5-2	Digital Outputs
9-6	Troub	eshooting Flowchart

#### **How to Check for Errors** 9-1

Use one of the following error checking methods.

- · Checking the indicators
- · Troubleshooting with the Support Software

Refer to the user's manual for the CPU Unit, Communications Coupler Unit, or Communication Control Unit that the NX Units are connected to for details on troubleshooting with the Support Software.

# 9-2 Checking for Errors with the Indicators

You can use the TS indicators on the NX Units to check the NX Unit status and level of errors.

This section describes the meanings of errors that the TS indicator shows and the troubleshooting procedures for them.

In this section, the status of the indicator is indicated with the following abbreviations.

Abbreviation	Indicator status		
Lit	Lit		
Not Lit	Not lit		
FS()	Flashing. The numeric value in parentheses is the flashing interval.		
	Undefined		

# **Main Errors and Corrections**

TS indicator		Cause	Correction				
Green	Red	Cause	Correction				
Lit	Not Lit		(This is the normal status.)				
FS (2 s)	Not Lit	Initializing	(Normal. Wait until the processing is com-				
		Downloading	pleted.)				
Lit	Lit	This status is not present.					
Not Lit	Not Lit	The Unit power supply is not supplied.	Check the following items and supply the Unit power supply correctly.				
			[Check items for power supply]				
			Make sure that the power supply cable is wired correctly.				
			Make sure that the power supply cable is not disconnected.				
			Make sure that power supply voltage is within the specified range.				
			Make sure that the power supply has enough capacity.				
			Make sure that power supply has not failed.				
		Waiting for initialization to start	(Normal. Wait until the processing is com-				
		Restarting	pleted.)				
		If you cannot resolve the problem	after you check the above items and cycle the				
		Unit power supply, the Unit may ha Unit.	ve a hardware failure. If this happens, replace the				
Not Lit	Lit	Hardware failure	If this error occurs after you cycle the Unit power supply, replace the Unit.				
Not Lit	Lit	Non-volatile Memory Hardware	Refer to Event Non-volatile Memory Hardware				
		Error	Error on page 9-11.				
Not Lit	Lit	Control Parameter Error in Mas-	Refer to Event Control Parameter Error in Mas-				
		ter	<i>ter</i> on page 9-12.				
Not Lit	FS (1 s)	NX Unit I/O Communications	Refer to Event NX Unit I/O Communications				
		Error	Error on page 9-13.				

TS indicator		Cause	Correction			
Green	Red	Cause	Correction			
Not Lit	FS (1 s)	NX Unit Output Synchronization	Refer to Event NX Unit Output Synchronization			
		Error	Error on page 9-15.			
Not Lit	Lit	NX Unit Clock Not Synchronized	Refer to Event NX Unit Clock Not Synchronized			
		Error	Error on page 9-16.			

# 9-3 Checking for Errors and Troubleshooting on the Support Software

Error management on the NX Series is based on the methods used for the NJ/NX/NY-series Controllers.

This allows you to use the Support Software to check the meanings of errors and troubleshooting procedures. The confirmation method depends on the Support Software that is used.

# 9-3-1 Checking for Errors from the Sysmac Studio

When an error occurs, you can place the Sysmac Studio online to the Controller or the Communications Coupler Unit to check current Controller errors and the log of past Controller errors.

Refer to the user's manual for the connected CPU Unit, Communications Coupler Unit, or Communication Control Unit for information on checking errors.

## **Current Errors**

Open the Sysmac Studio's Controller Error Tab Page to check the current error's level, source, source details, event name, event codes, details, attached information 1 to 4, and correction. Errors in the observation level are not displayed.



#### **Additional Information**

#### **Number of Current Errors**

The following table gives the number of errors that are reported simultaneously as current errors in each Unit.

Unit	Number of simultaneous error notifications
Digital I/O Unit	When these Units are connected to the CPU Unit, since current errors are managed in the CPU Unit, the number of current errors is limited by the number of errors for the CPU Units.
	For Slave Terminals, since current errors are managed in the Communications Coupler Unit, the number of current errors is limited by the number of errors for the Communications Coupler Unit.
	When these Units are connected to the Communication Control Unit, since current errors are managed in the Communication Control Unit, the number of current errors is limited by the number of errors for the Communication Control Units.

If the number of errors exceeds the maximum number of reportable current errors, errors are reported with a priority given to the oldest and highest-level errors. Errors that exceed the limit on simultaneous error notifications are not reported.

Errors that are not reported are still reflected in the error status.

# Log of Past Errors

Open the Sysmac Studio's Controller Event Log Tab Page to check the times, levels, sources, source details, event names, event codes, details, attached information 1 to 4, and corrections for previous errors.



#### **Additional Information**

#### **Number of Logs of Past Errors**

Event logs in the Digital I/O Units are stored in the CPU Unit, Communications Coupler Unit, or Communication Control Unit to which they are connected.

Refer to the user's manual for the connected CPU Unit, Communications Coupler Unit, or Communication Control Unit for details on the amount of event logs that are stored in the Unit.

Refer to the troubleshooting manual for the connected CPU Unit or Industrial PC and the Sysmac Studio Version 1 Operation Manual (Cat. No. W504) for the items that you can check and the procedures to check for errors.

Refer to 9-3-3 Event Codes and Corrections for Errors on page 9-7 for details on event codes.

#### 9-3-2 **Checking for Errors from Support Software Other Than the Sys**mac Studio

You can check the error descriptions and logs with Support Software other than the Sysmac Studio. For the error checking methods, refer to the user's manual for the connected Communications Coupler Unit and the operation manual for the Support Software.

Refer to 9-3-3 Event Codes and Corrections for Errors on page 9-7 for details on event codes.

The number of current errors and the number of error log errors that occurred in the past in the Digital I/O Units are the same as for the Sysmac Studio.

# 9-3-3 Event Codes and Corrections for Errors

The errors (i.e., events) that occur in the Digital I/O Unit is shown below.

If your NX Unit is connected to a Communication Control Unit, replace CPU Unit with Communication Control Unit in the descriptions provided for "For the NX bus of CPU Units" in the table below.

The following abbreviations are used in the event level column.

Abbreviation	Name				
Maj	Major fault level				
Prt	Partial fault level				
Min	Minor fault level				
Obs	Observation				
Info	Information				

Refer to the troubleshooting manual for the connected CPU Unit or Industrial PC for information on NJ/NX/NY-series event codes.

Event code	Event name	Magning	Assumed cause	Level		Reference			
Event code	Event name	Meaning	Assumed cause		Prt	Min	Obs	Info	Reference
00200000 hex	Non-volatile Memory Hardware Error	An error occurred in non-volatile memory.	Non-volatile memory failure  For the NX bus of CPU Units			٧			P. 9-11
10410000 hex	Control Parameter Error in Mas- ter	An error occurred in the control parameters that are saved in the master.	For the NX bus of CPU Units  The power supply to the CPU Unit was turned OFF while writing the Unit operation settings was in progress. Or there is an error in the area of the non-volatile memory in the CPU Unit in which the Unit operation settings for the relevant NX Unit are saved.  For Communications Coupler Units  The power supply to the Communications Coupler Unit was turned OFF while writing the Unit operation settings was in progress. Or there is an error in the area of the non-volatile memory in the Communications Coupler Unit in which the Unit operation settings for the relevant NX Unit are saved.			1			P. 9-12

Frank anda	Frank name	Magning	Assumed souss			Leve	I		Deference
Event code	Event name	Meaning	Assumed cause	Maj	Prt	Min	Obs	Info	Reference
8020 0000 hex	NX Unit I/O Communications Error	Meaning  An I/O communications error occurred in an NX Unit.	For the NX bus of CPU Units  An error that prevents normal NX bus communications occurred in a CPU Unit.  An NX Unit is not mounted properly.  The power cable for the Unit power supply is disconnected, or the wiring from the Unit power supply to the NX Units is incorrect.  The power cable for the Unit power supply is broken.  The voltage of the Unit power supply is outside the specified range, or the capacity of the Unit power supply is insufficient.  There is a hardware error in an NX Unit.  For Communications Coupler Units  An error that prevents normal NX bus communications occurred in a Communications Coupler Unit.  The NX Unit is not mounted	Мај	Prt	Min √	Obs	Info	P. 9-13
			<ul> <li>properly.</li> <li>The power cable for the Unit power supply is disconnected. Or, the wiring from the Unit power supply to the NX Units is incorrect.</li> <li>The power cable for the Unit power supply is broken.</li> <li>The voltage of the Unit power supply is outside the specified range. Or, the capacity of the Unit power supply is insufficient.</li> </ul>						
			There is a hardware error in the NX Unit.						
80210000 hex	NX Unit Output Synchronization Error	An output synchro- nization error occurred in the NX Unit.	<ul> <li>For the NX bus of CPU Units</li> <li>I/O refreshing on the NX bus is not performed normally due to an error in the CPU Unit.</li> <li>For Communications Coupler Units</li> <li>The communications cable connected to the Communications Coupler Unit is broken or the connection is faulty.</li> <li>The communications cable is affected by noise.</li> </ul>			V			P. 9-15

Event and	Event nerse	Magning	Assumed sous	Level			Reference		
Event code	event code		Maj	Prt	Min	Obs	Info	Reference	
80240000 hex	NX Unit Clock Not Synchro- nized Error	A time information error occurred in an NX Unit.	<ul> <li>For the NX bus of CPU Units</li> <li>There is a hardware error in an NX Unit.</li> <li>There is a hardware error in a CPU Unit.</li> <li>For Communications Coupler Units</li> <li>There is a hardware error in an NX Unit.</li> <li>There is a hardware error in an EtherCAT Coupler Unit.</li> </ul>			<b>V</b>			P. 9-16
70010000 hex	Previous Time Speci- fied	A previous time was specified for output refreshing with a specified time stamp.	<ul> <li>For the NX bus of CPU Units</li> <li>A past time is specified due to an error in the user program.</li> <li>A Task Period Exceeded error occurred in a CPU Unit.</li> <li>For Communications Coupler Units</li> <li>A past time is specified due to an error in the user program.</li> <li>A Task Period Exceeded error occurred in a CPU Unit.</li> <li>The arrival of I/O data at an NX Unit was delayed due to a Communications Synchronization Error or other communications error.</li> </ul>				√ ·		P. 9-17
90400000 hex	Event Log Cleared	The event log was cleared.	The event log was cleared by the user.					<b>V</b>	P. 9-18

#### 9-3-4 **Meaning of Error**

This section describes the information that is given for individual errors.

If your NX Unit is connected to a Communication Control Unit, replace CPU Unit with Communication Control Unit in the descriptions provided for "For the NX bus of CPU Units" in the tables below.

# **Error Descriptions**

The items that are used to describe individual errors (events) are described in the following copy of an error table.

Event name	Gives the nam	e of the error.		Event code	Gives the code of	code of the error.			
Meaning	Gives a short	Gives a short description of the error.							
Source	Gives the sour	ce of the error.	Source details	Gives details on the source of the error.	Detection timing	Tells when the error is detected.			
Error	Level	Tells the level of i	nfluence on	Log category	Tells which log th	ne error is saved			
attributes		control.*1			in.*2				
	Recovery	Gives the recover	ry method.*3						
Effects	User program	Tells what will happen to execution of the user program.*4	Operation		vides special information on the operation that ults from the error.				
Indicators		is of the built-in EtherCerrors in the EtherC	-		•				
System-defined	Variable		Data type		Name				
variables		Lists the variable names, data types, and meanings for system-defined variables that provide direct error notification, that are directly affected by the error, or that contain settings that cause the error.							
Cause and	Assumed cau	se	Correction		Prevention				
correction	Lists the possi	ble causes, correct	tions, and prever	ntive measures for	the error.				
Attached information	This is the attached information that is displayed by the Support Software or an HMI.*5,*6								
Precautions/		tions, restrictions, an							
Remarks	els that can be s	set, the recovery met	hod, operational in	formation, and othe	r information are als	o provided.			

#### \*1. One of the following:

Major fault: Major fault level Partial fault: Partial fault level Minor fault: Minor fault level

Observation Information

### \*2. One of the following:

System: System event log Access: Access event log

#### \*3. One of the following:

Automatic recovery: Normal status is restored automatically when the cause of the error is removed.

Error reset: Normal status is restored when the error is reset after the cause of the error is removed.

Cycle the power supply: Normal status is restored when the power supply to the Controller is turned OFF and then back ON after the cause of the error is removed.

Controller reset: Normal status is restored when the Controller is reset after the cause of the error is removed.

Depends on cause: The recovery method depends on the cause of the error.

## \*4. One of the following:

Continues: Execution of the user program will continue.

Stops: Execution of the user program stops. Starts: Execution of the user program starts.

- \*5. "System information" indicates internal system information that is used by OMRON.
- \*6. Refer to the appendices of the troubleshooting manual for the connected CPU Unit or Industrial PC for the applicable range of the HMI Troubleshooter.

Event name	Non-volatile Memory Hardware Error			Event code	00200000 hex		
Meaning	An error occurre	d in non-volatile me	emory.				
Source	Depends on whe Software is conn system configura	ected and the	Source details	NX Unit	Detection timing	When power is turned ON to the NX Unit	
Error	Level	Minor fault		Log category	System		
attributes	Recovery	For the NX bus of	of CPU Units				
		Cycle the power	supply to the Unit	or restart the NX I	ous.		
		For Communicat	ions Coupler Units	i.			
		Cycle the power	supply to the Unit	or restart the Slav	e Terminal.		
		If the errors are o	detected in the Cor	ntroller, reset all of	f the errors in the	e Controller.	
Effects	User program	Continues.	Operation	I/O refreshing fo	r the NX Unit sto	ps. Messages can-	
				not be sent to th			
Sys-	Variable		Data type		Name		
tem-defined variables	None						
Cause and	Assumed cause	е	Correction		Prevention		
correction	Non-volatile mer	nory failure.	For the NX bus of CPU Units None				
			Cycle the power supply to the Unit				
			or restart the NX bus. If the error				
			persists even after	-			
			vant NX Unit.	, replace the rele-			
				ions Couplor			
			For Communications Coupler Units				
				supply to the Unit			
				e Terminal. If the			
			<u> </u>	n after you make			
			the above correc	•			
A44 I I	Name		relevant NX Unit.				
Attached information	None						
Precautions/	None						
riecaulions/	INOUE						

Event name	Control Paramete	er Error in Master		Event code	10410000 hex	
Meaning	An error occurred	d in the control par	ameters that are s	saved in the master.		
Source	Depends on whe Software is conne system configura	ected and the	Source details	NX Unit	Detection timing	When power is turned ON to the NX Unit
Error	Level	Minor fault		Log category	System	•
attributes	Recovery	For the NX bus of				C Unit.  NX Unit and then  the NX Unit and  Jnit.
Effects	User program	Continues.	Coupler Unit.  Operation	I/O refreshing for	the NX Unit stops	<u> </u>
Sys-	Variable	Continues.	Data type	I wo retresting for	Name	
tem-defined	None					
variables	140110					
Cause and	Assumed cause		Correction		Prevention	
correction	For the NX bus o	f CPU Units				
	The power supply to the CPU Unit was turned OFF while writing the Unit operation settings was in progress. Or there is an error in the area of the non-volatile memory in the CPU Unit in which the Unit operation settings for the relevant NX Unit are saved.		tings of the NX U error persists eve	gs of the NX Unit again. If the or persists even after you make above correction, replace the		
	For Communications Coupler Units					
	The power supply nications Coupler OFF while writing tion settings was there is an error in non-volatile mem munications Couple Unit operation	e power supply to the Commu- ations Coupler Unit was turned tir F while writing the Unit opera- a settings was in progress. Or re is an error in the area of the		ownload the Unit operation set- ngs of the NX Unit again. If the rror occurs again even after you take the above correction, eplace the Communications Cou- er Unit.		the power supply cations Coupler er of the Unit is for the NX Unit software or save neters by a mes- iss.
Attached	None					
information						
Precautions/ Remarks	None					

NX Unit I/O Comi	munications Error		Event code	80200000 hex		
An I/O communications error occurred in an NX Unit.						
Depends on where the Support		Source details	NX Unit	Detection	Continuously	
Software is connected and the				timing		
system configuration	tion.					
Level	Minor fault Log category System					
Recovery	For the NX bus o	f CPU Units				
	When Fail-soft Operation Is Set to Stop					
		Reset the error in	the NX Bus Func	tion Module.		
		When Fail-soft O	peration Is Set to I	n Is Set to <i>Fail-soft</i>		
	Reset the error in the NX Unit.					
	For Communications Coupler Units					
	When Fail-soft Operation Is Set to <i>Stop</i>					
	If the errors are detected in the Controller, reset all of Controller.				the errors in the	
				,	rrors in the Com-	
		When Fail-soft O	peration Is Set to I	Fail-soft		
		Reset errors in th	e Communications	s Coupler Unit and	d NX Unit.	
User program	Continues.	Operation	The NX Unit will	continue to operat	e.	
			Input data: Updat	ting input values s	tops.	
			Output data: The output values depend on the		end on the Load	
		Rejection Output Setting.				
Variable		Data type		Name		
None						
	An I/O communic Depends on where Software is connected by the configuration of the configurat	An I/O communications error occurs Depends on where the Support Software is connected and the system configuration.  Level Minor fault  Recovery For the NX bus of  For Communication  User program Continues.	An I/O communications error occurred in an NX Unit.  Depends on where the Support Software is connected and the system configuration.  Level Minor fault  Recovery For the NX bus of CPU Units When Fail-soft O Reset the error in When Fail-soft O Reset the error in When Fail-soft O If the errors are of Controller.   An I/O communications error occurred in an NX Unit.  Depends on where the Support Software is connected and the system configuration.  Level Minor fault Log category  Recovery For the NX bus of CPU Units  When Fail-soft Operation Is Set to a Reset the error in the NX Bus Fund When Fail-soft Operation Is Set to a Reset the error in the NX Unit.  For Communications Coupler Units  When Fail-soft Operation Is Set to a Reset the errors are detected in the Cornor Controller.  If the errors are not detected in the munications Coupler Unit and NX UNIT.  When Fail-soft Operation Is Set to a Reset errors in the Communications  When Fail-soft Operation Is Set to a Reset errors in the Communication.  User program Continues. Operation The NX Unit will a Input data: Updato Output data: The Rejection Output  Variable Data type	An I/O communications error occurred in an NX Unit.  Depends on where the Support Software is connected and the system configuration.  Level Minor fault Log category System  For the NX bus of CPU Units When Fail-soft Operation Is Set to Stop Reset the error in the NX Bus Function Module.  When Fail-soft Operation Is Set to Fail-soft Reset the error in the NX Unit.  For Communications Coupler Units When Fail-soft Operation Is Set to Stop If the errors are detected in the Controller, reset all of Controller.  If the errors are not detected in the Controller, reset emunications Coupler Unit and NX Unit.  When Fail-soft Operation Is Set to Fail-soft Reset errors in the Communications Coupler Unit and NX Unit.  When Fail-soft Operation Is Set to Fail-soft Reset errors in the Communications Coupler Unit and NX Unit.  When Fail-soft Operation Is Set to Fail-soft Reset errors in the Communications Coupler Unit and NX Unit.  When Fail-soft Operation Is Set to Fail-soft Reset errors in the Communications Coupler Unit and NX Unit.  When Fail-soft Operation Is Set to Fail-soft Reset errors in the Communications Coupler Unit and NX Unit.  When Fail-soft Operation Is Set to Fail-soft Reset errors in the Communications Coupler Unit and NX Unit.  When Fail-soft Operation Is Set to Fail-soft Reset errors in the Communications Coupler Unit and NX Unit.  When Fail-soft Operation Is Set to Fail-soft Reset errors in the Communications Coupler Unit and NX Unit.  When Fail-soft Operation Is Set to Stop In the NX Unit will continue to operate Input data: The output values departed the Communications Coupler Unit and NX Unit.  Variable Data type Name		

Cause and	Assumed cause	Correction	Prevention				
correction	For the NX bus of CPU Units						
	An error that prevents normal NX	Check the error that occurred in	Take preventive measures against				
	bus communications occurred in a	the CPU Unit and perform the	the error that occurred in the CPU				
	CPU Unit.	required corrections.	Unit.				
	An NX Unit is not mounted prop-	Mount the NX Units and End	Mount the NX Units and End				
	erly.	Cover securely and secure them	Cover securely and secure them				
		with End Plates.	with End Plates.				
	The power cable for the Unit	Wire the Unit power supply to the	Wire the Unit power supply to the				
	power supply is disconnected, or	NX Units securely.	NX Units securely.				
	the wiring from the Unit power						
	supply to the NX Units is incorrect.						
	The power cable for the Unit	If the power cable between the	None				
	power supply is broken.	Unit power supply and the NX					
		Units is broken, replace it.					
	The voltage of the Unit power sup-	Configure the power supply sys-	Configure the power supply sys-				
	ply is outside the specified range,	tem configuration correctly	tem configuration correctly				
	or the capacity of the Unit power	according to the power supply	according to the power supply				
	supply is insufficient.	design method.	design method.				
	There is a hardware error in an	If the error persists even after you	None				
	NX Unit.	make the above correction,					
	replace the NX Unit.						
	For Communications Coupler Units	Take proventive processes against					
	An error that prevents normal NX bus communications occurred in a	Check the error that occurred in the Communications Coupler Unit	Take preventive measures against the error that occurred in the Com-				
	Communications Coupler Unit.	and perform the required correc-	munications Coupler Unit.				
	Communications Coupler Onit.	tions.	manications coupler onit.				
	The NX Unit is not mounted prop-	Mount the NX Units and End	Mount the NX Units and End				
	erly.	Cover securely and secure them	Cover securely and secure them				
		with End Plates.	with End Plates.				
	The power cable for the Unit	Correctly wire the Unit power sup-	Correctly wire the Unit power sup-				
	power supply is disconnected. Or,	ply to the NX Units.	ply to the NX Units.				
	the wiring from the Unit power						
	supply to the NX Units is incorrect.						
	The power cable for the Unit	If the power cable between the	None				
	power supply is broken.	Unit power supply and the NX					
		Units is broken, replace it.					
	The voltage of the Unit power sup-	Correctly configure the power sup-	Correctly configure the power sup-				
	ply is outside the specified range.	ply system according to the power	ply system according to the power				
	Or, the capacity of the Unit power	supply design methods.	supply design methods.				
	supply is insufficient.						
	There is a hardware error in the	If the error occurs again even after	None				
	NX Unit.	you make the above correction,					
		replace the NX Unit.					
Attached	None						
information							
Precautions/	None						
Remarks							

Event name	NX Unit Output Synchronization Error		ror	Event code	80210000 hex			
Meaning		ronization error occ		nit.				
Source	Depends on who Software is conr	Depends on where the Support Software is connected and the system configuration.		NX Unit	Detection timing	Continuously		
Error	Level	Minor fault		Log category	System			
attributes	Recovery	For Communicat						
		Reset all of the e	Reset all of the errors in the Controller.					
Effects	User program	Continues.	Operation	The NX Unit will	continue to operat	e.		
				Input data: Upda	ting input values s	tops.		
				Output data: The output values depend on the Lo Rejection Output Setting.				
Sys-	Variable		Data type	Name				
tem-defined variables	None							
Cause and	Assumed cause	е	Correction		Prevention			
correction	For the NX bus	of CPU Units						
	I/O refreshing on the NX bus is not performed normally due to an error in the CPU Unit.		Check the error that occurred in the CPU Unit and perform the required corrections.		Take preventive measures against the error that occurred in the CPU Unit.			
	For Communica	tions Coupler Units						
	The communications cable connected to the Communications Coupler Unit is broken or the connection is faulty.		Replace the communications cable or wire the cable correctly.		Wire the communications cable correctly.			
	The communications cable is affected by noise.		Set the Consecu Communications Count parameter Communications suitable value that problems in oper	Error Detection for the Coupler Unit to a at will not cause	Implement noise countermeasures. Refer to the operation manuals for the specific Units for noise countermeasures			
			Implement noise countermeasures if there is excessive noise.					
Attached information	None							
Precautions/ Remarks	None							

Event name	NX Unit Clock No	ot Synchronized E	rror	Event code	80240000 hex			
Meaning	A time informatio	n error occurred in	n an NX Unit.					
Source	Depends on where the Support Software is connected and the system configuration.		Source details	NX Unit	Detection timing	Continuously		
Error	Level	Minor fault		Log category	System			
attributes	Recovery For the NX bus of CPU Units							
		Cycle the power	supply to the Unit.					
		For Communicat	tions Coupler Units	;				
		Cycle the power	Cycle the power supply to the Unit and then reset all of the errors in the Controller.					
Effects	User program	Continues.	Operation	The NX Unit will	continue to operat	e.		
				Input data: Upda	nput data: Updating input values stops.			
				Output data: The output values depend on the Lo Rejection Output Setting.		end on the Load		
Sys-	Variable		Data type		Name			
tem-defined variables	None							
Cause and	Assumed cause	•	Correction		Prevention			
correction	For the NX bus of	of CPU Units	•					
	There is a hardware error in ar NX Unit.		If the error occurs only in a specific NX Unit, replace the relevant NX Unit.		None			
	There is a hardware error in a		If the error occur	s in all of the NX	None			
	CPU Unit.		Units mounted on a CPU Unit,					
			replace the CPU Unit.					
	For Communications Coupler Units							
	There is a hardware error NX Unit.		If the error occurs only in a specific NX Unit, replace the relevant NX Unit.		None			
	There is a hardw EtherCAT Couple		If the error occur Units mounted or tions Coupler Un Communications	n a Communica- it, replace the	None			
Attached information	None		1	•	1			
Precautions/ Remarks	None							

Event name	Previous Time Sp			Event code	70010000 hex	
Meaning	A previous time was specified for output refreshing with a specified			th a specified time	stamp.	
Source	Depends on where the Support		Source details	e details NX Unit	Detection	Continuously
	Software is conn				timing	
	system configuration.					
Error	Level	Observation		Log category	System	
attributes	Recovery	Reset error in the				
Effects	User program	Continues.	Operation	-	that is specified for	or the previous
				time is not output		
Sys-	Variable		Data type		Name	
tem-defined	None					
variables					-	
Cause and	Assumed cause		Correction		Prevention	
correction	For the NX bus o		T		T	
	A past time is spe		Correct the user p	-	Check in the user program to	
	error in the user program.		does not specify a past time.		make sure that it does not specify	
			a past time.		·	
	A Task Period Exceeded error occurred in a CPU Unit.		Perform the required corrections		Take preventive measures against the Task Period Exceeded error	
			for the Task Period Exceeded error that occurred in the CPU Unit.		that occurred in the CPU Unit.	
	For Communications Coupler Units					
	A past time is specified due to an		Correct the user program so that it   Check in the user program to			
	error in the user		does not specify a past time. If the error persists even though the program does not specify a past time, change the specified time to a		make sure that it does not specify a past time. If the error persists even though the program does not specify a past time, change the	
			later time.		specified time to a later time.	
	A Task Period Ex	ceeded error	Perform the required corrections for the Task Period Exceeded		Take preventive measures against the Task Period Exceeded error	
	occurred in a CP	U Unit.				
				rror that occurred in the CPU		he CPU Unit.
			Unit.			
	The arrival of I/O		Refer to the corre		-	neasures against
	Unit was delayed		Communications	•		ons Synchroniza-
	munications Synd		Error that occurre		tion Error that oc	
	or other commun	ications error.	cations Coupler Uthe error.	onit to prevent	Communications	Coupler Offic.
Attached	None		•		•	-
information						
Precautions/	None					
Remarks						

Event name	Event Log Cleared			Event code	90400000 hex	
Meaning	The event log was cleared.					
Source	Depends on where the Support Software is connected and the system configuration.		Source details	NX Unit	Detection timing	When commanded from user
Error attributes	Level	Information		Log category	Access	
	Recovery					
Effects	User program	Continues.	Operation	Not affected.	1.	
Sys-	Variable		Data type		Name	
tem-defined variables	None					
Cause and	Assumed cause		Correction		Prevention	
correction	The event log wa user.	t log was cleared by the				
Attached	Attached information: Events that were cleared					
information	1: The system event log was cleared.					
	2: The access event log was cleared.					
Precautions/	None					
Remarks						

# 9-4 Resetting Errors

Refer to the user's manual for the connected CPU Unit, Communications Coupler Unit, or Communication Control Unit for information on how to reset errors.

# **Troubles Specific To Each Type of NX** 9-5 **Units**

#### 9-5-1 **Digital Inputs**

Problem	Assumed cause	Correction
Although a connected	The I/O power is not supplied.	Check that the I/O power is supplied.
external device is ON,	The I/O power supply voltage	Set the I/O power supply voltage within the rated
nothing is input and the	is outside the rated range.	range.
input indicator is not lit	The Unit is not wired correctly	Check the wiring with the connected external
either.	with the connected external	device.
	device.	
	The wiring to the connected	Check the wiring with the connected external
	external device is discon-	device.
	nected.	
	A connected external device	Replace the connected external device.
	is defective.	
A connected external	An NX bus error or a commu-	When the Unit is connected to the CPU Unit or
device is ON and the input indicator is lit, but nothing	nications error occurred.	Communication Control Unit, check if a NX bus error occurred.
is input.		In the case of a Slave Terminal, check if a NX bus
		or host communication error occurred.
There is a delay in the ON	An input filter may be set.	Set the input filter value to 0. Alternatively, change
and OFF timing for input		the input filter to an appropriate value.
values.		

### 9-5-2 Digital Outputs

Problem	Assumed cause	Correction
When the output is ON,	The I/O power is not supplied.	Check that the I/O power is supplied.
nothing is output although	The I/O power supply voltage	Set the I/O power supply voltage within the rated
the output indicator is lit.	is outside the rated range.	range.
	The Unit is not wired correctly	Check the wiring with the connected external
	with the connected external	device.
	device.	
	The wiring to the connected	Check the wiring with the connected external
	external device is discon-	device.
	nected.	
	A connected external device	Replace the connected external device.
	is defective.	
	Load short-circuit protection is	Refer to 7-4-3 Load Short-circuit Protection on page
	in progress.	7-17 and correct the problem.
Although the output is ON,	A communications error	Check if a communications (NX bus) error
nothing is output and the	occurred.	occurred.
output indicator is not lit		
either.		
Cannot hold outputs when	The load rejection output set-	Set the load rejection output setting to "Hold the
NX bus errors or commu-	ting is set to "OFF".	present value".
nications errors occur.		
Cannot clear outputs NX	The load rejection output set-	Set the load rejection output setting to "OFF".
bus errors or when com-	ting is set to "Hold the present	
munications errors occur.	value".	

#### **Troubleshooting Flowchart** 9-6

Refer to the user's manual for the connected CPU Unit, Communications Coupler Unit, or Communication Control Unit for details on the standard troubleshooting process when an error occurs.



## **Inspection and Maintenance**

This section describes how to clean, inspect, and maintain the system.

10-1 Clean	ing and Inspection	10-2
10-1-1	Cleaning	10-2
10-1-2	Periodic Inspection	10-2
10-2 Mainte	ananca Procedures	10-5

## 10-1 Cleaning and Inspection

This section describes daily device maintenance such as cleaning and inspection.

Make sure to perform daily or periodic inspections in order to maintain the Digital I/O Unit's functions in the best operating condition.

#### 10-1-1 Cleaning

Perform the following cleaning procedures periodically to ensure Digital I/O Units are maintained in the best operating condition.

- Wipe the equipment over with a soft, dry cloth when performing daily cleaning.
- · If dirt remains even after wiping with a soft, dry cloth, wipe with a cloth that has been wet with a sufficiently diluted detergent (2%) and wrung dry.
- Units will become stained if items such as rubber, vinyl products, or adhesive tape are left on the NX Unit for a long period. Remove such items during regular cleaning.



#### **Precautions for Correct Use**

- · Never use benzene, thinners, other volatile solvents, or chemical cloths.
- · Do not touch the NX bus connectors.

#### 10-1-2 Periodic Inspection

NX Units do not have parts with a specific life. However, its elements can deteriorate under improper environmental conditions. Periodic inspections are thus required to ensure that the required conditions are being maintained.

Inspection is recommended at least once every six months to a year, but more frequent inspections may be necessary depending on the severe environments.

Take immediate steps to correct the situation if any of the conditions in the following table are not met.

### Periodic Inspection Items

No.	Inspec- tion item	Inspection details	Criteria	Correction
1	External power sup- ply	Is the power supply voltage measured at the terminal block within standards?	Within the power supply voltage range	Use a voltage tester to check the power supply at the terminals. Take necessary steps to bring the power supply within the power supply voltage range.
2	I/O power supply	Is the power supply voltage measured at the I/O terminal block within standards?	Voltages must be within I/O specifications of each NX Unit.	Use a voltage tester to check the power voltage at the terminals. Take necessary steps to bring the I/O power supply within NX Unit standards.
3	Ambient environ- ment	Is the ambient operating temperature within standards?	0 to 55°C	Use a thermometer to check the temperature and ensure that the ambient operating temperature remains within the allowed range of 0 to 55°C.
		Is the ambient operating humidity within standards?	Relative humidity must be 10% to 95% with no condensation.	Use a hygrometer to check the humidity and ensure that the ambient operating humidity remains between 10% and 95%.
				Make sure that condensation does not occur due to rapid changes in temperature.
		Is it subject to direct sunlight?	Not in direct sunlight	Protect the Controller if necessary.
		Is there an accumulation of dirt, dust, salt, metal powder, etc.?	No accumulation	Clean and protect the Controller if necessary.
		Is there water, oil, or chemical sprays hitting the Controller?	No spray	Clean and protect the Controller if necessary.
		Are there corrosive or flammable gases in the area of the Controller?	No spray	Check by smell or use a sensor.
		Is the Unit subject to shock or vibration?	Vibration resistance and shock resistance must be within specifications.	Install cushioning or other vibration and shock absorbing equipment if necessary.
		Are there noise sources near the Controller?	No significant noise sources	Either separate the Controller and noise source, or protect the Controller.
4	Installation and wiring	Are the DIN track mounting hooks for each NX Unit securely locked?	No looseness	Securely lock the DIN track mounting hooks.
		Are the cable connectors fully inserted and locked?	No looseness	Correct any improperly installed connectors.
		Are there any loose screws on the End Plates (PFP-M)?	No looseness	Tighten loose screws with a Phillips-head screwdriver.
		Are the NX Units connected to each other along the hookup guides and inserted until they touch the DIN track?	You must connect and fix the NX Units to the DIN track.	Connect the NX Units to each other along the hookup guides and insert them until they touch the DIN track.
		Are there any damaged external wiring cables?	No visible damage	Check visually and replace cables if necessary.

#### **Tools Required for Inspections**

#### Required Tools

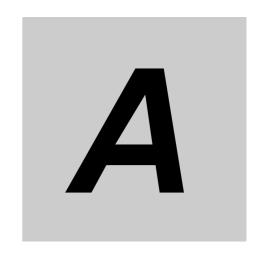
- · Phillips screwdriver
- · Flat-blade screwdriver
- · Voltage tester or digital voltmeter
- · Industrial alcohol and pure cotton cloth

#### Tools Required Occasionally

- Oscilloscope
- Thermometer and hygrometer

## **10-2 Maintenance Procedures**

When you replace a Digital I/O Unit, follow the procedure in the user's manual for the connected CPU Unit, Communications Coupler Unit, or Communication Control Unit.



## **Appendices**

This section describes the data sheets of the Digital I/O Units and their dimensions.

A-1	Data S	Sheet	<b>A-</b> 3
	A-1-1	Model List	
	A-1-2	Digital Input Units	
	A-1-3	Digital Output Units	
	A-1-4	Digital Mixed I/O Units	A-87
A-2	Dimen	isions	<b>A</b> -101
	A-2-1	Screwless Clamping Terminal Block Type	
	A-2-2	M3 Screw Terminal Block Type	
	A-2-3	Connector Types	
A-3	Conne	ecting Connector-Terminal Block Conversion Units	
	and I/0	O Relay Terminals	A-107
	A-3-1	Patterns for Combining Connector-Terminal Block Conversion Units	
		and I/O Relay Terminals	
	A-3-2	Combinations of Connections	
	A-3-3	Connector-Terminal Block Conversion Unit Connection Diagrams	
	A-3-4	Connection Diagrams for I/O Relay Terminals	
A-4	EMC [	Directive Measures for Relay Outputs	<b>A</b> -139
A-5	List of	NX Objects	A-140
	A-5-1	Format of Object Descriptions	A-140
	A-5-2	Digital Input Units	A-141
	A-5-3	Digital Output Units	A-149
	A-5-4	Digital Mixed I/O Units	A-158
A-6	List of	Screwless Clamping Terminal Block Models	A-163
	A-6-1	Model Notation	A-163
	A-6-2	List of Terminal Block Models	A-163
<b>A-7</b>	Versio	on Information with CPU Units	<b>A</b> -164
	A-7-1	Relationship between Unit Versions of Units	A-164
A-8	Versio	on Information with Communications Coupler Units	A-166
	A-8-1	Connection to an EtherCAT Coupler Unit	
	A-8-2	Connection to an EtherNet/IP Coupler Unit	
A-9	Versio	on Information with Communication Control Units	A-170
-	A-9-1	Relationship between Unit Versions of Units	
		·	

A-10 Displa	ying the Edit Unit Operation Settings Tab Page	A-172
A-10-1	Connection to the CPU Unit or the Communication Control Unit	A-172
A-10-2	Slave Terminal	A-174

#### **A-1 Data Sheet**

The specifications of individual Digital I/O Unit are shown below.

#### A-1-1 **Model List**

#### DC Input Units (Screwless Clamping Terminal Block, 12 mm Width)

Model	Num ber of point s	Internal I/O common	Rated input voltage	I/O refreshing method ON/OFF respo		Reference
NX-ID3317			12 to 24 VDC	Switching Synchro- nous I/O refreshing	20 μs max./400 μs max.	P. A-10
NX-ID3343		NPN		and Free-Run refresh- ing	100 ns max./100 ns	P. A-12
NX-ID3344	4		24 VDC	Input refreshing with input changed time only	max.	P. A-14
NX-ID3417	point s		12 to 24 VDC	Switching Synchro- nous I/O refreshing and Free-Run refresh- ing	20 μs max./400 μs max.	P. A-16
NX-ID3443		PNP			100 ns max./100 ns	P. A-18
NX-ID3444				Input refreshing with input changed time only	max.	P. A-20
NX-ID4342	8	NPN	24 VDC			P. A-22
NX-ID4442	point s	PNP		Switching Synchro- nous I/O refreshing	20 μs max./400 μs	P. A-24
NX-ID5342	16	NPN		and Free-Run refresh-	max.	P. A-26
NX-ID5442	point s	PNP		ing		P. A-28

#### DC Input Units (M3 Screw Terminal Block, 30 mm Width)

Model	Num ber of point s	Internal I/O common	Rated input voltage	I/O refreshing method	ON/OFF response time	Reference
NX-ID5142-1	16 point s	For both NPN/PNP	24 VDC	Switching Synchro- nous I/O refreshing and Free-Run refresh- ing	20 μs max./400 μs max.	P. A-30

#### DC Input Units (MIL Connector, 30 mm Width)

Model	Num ber of point s	Internal I/O common	Rated input voltage	I/O refreshing method	ON/OFF response time	Reference
NX-ID5142-5	16 point s	For both NPN/PNP	24 VDC	Switching Synchro- nous I/O refreshing and	20 μs max./400 μs	P. A-32
NX-ID6142-5	32 point s	For both NPN/PNP	24 VDC	Free-Run refreshing	max.	P. A-34

#### DC Input Units (Fujitsu Connector, 30 mm Width)

Model	Num ber of point s	Internal I/O common	Rated input voltage	I/O refreshing method	ON/OFF response time	Reference
NX-ID6142-6	32 point s	For both NPN/PNP	24 VDC	Switching Synchro- nous I/O refreshing and Free-Run refresh- ing	20 μs max./400 μs max.	P. A-37

## AC Input Units (Screwless Clamping Terminal Block, 12 mm Width)

Model	Num ber of point s	Rated input voltage	I/O refreshing method	ON/OFF response time	Reference
NX-IA3117	4 point s	200 to 240 VAC, 50/60 Hz (170 to 264 VAC, ±3 Hz)	Free-Run refreshing	10 ms max./40 ms max.	P. A-40

## Transistor Output Units (Screwless Clamping Terminal Block, 12 mm Width)

Model	Num ber of point s	Internal I/O common	Maximum value of load current	Rated volt- age	I/O refresh- ing method	ON/OFF response time	Reference
NX-OD2154	2	NPN			Output	300 ns	P. A-45
NX-OD2258	point s	PNP	0.5 A/point, 1 A/Unit	24 VDC	refreshing with specified time stamp only	max./300 ns max.	P. A-47
NX-OD3121		NPN		12 to 24 VDC		0.1 ms max./0.8 ms max.	P. A-49
NX-OD3153		INI IN	0.5 A/point, 2			300 ns max./300 ns max.	P. A-51
NX-OD3256	4 point s	nt A/Unit	A/Unit 24 VDC		0.5 ms max./1.0 ms max.	P. A-53	
NX-OD3257		PNP			Switching Syn- chronous I/O refreshing and Free-Run	300 ns max./300 ns max.	P. A-55
NX-OD3268			2 A/point, 8 A/Unit			0.5 ms max./1.0 ms max.	P. A-57
NX-OD4121	8 point	NPN		12 to 24 VDC	refreshing	0.1 ms max./0.8 ms max.	P. A-59
NX-OD4256	s 16 point	PNP	0.5 A/point, 4	24 VDC		0.5 ms max./1.0 ms max.	P. A-61
NX-OD5121		NPN	A/Unit	12 to 24 VDC		0.1 ms max./0.8 ms max.	P. A-63
NX-OD5256	s	PNP		24 VDC		0.5 ms max./1.0 ms max.	P. A-65

### Transistor Output Units (M3 Screw Terminal Block, 30 mm Width)

Model	Num ber of point s	Internal I/O common	Maximum value of load current	Rated volt- age	I/O refresh- ing method	ON/OFF response time	Reference
NX-OD5121-1	16 point	NPN	0.5 A/point, 5	12 to 24 VDC	Switching Syn- chronous I/O refreshing and Free-Run refreshing	0.1 ms max./0.8 ms max.	P. A-67
NX-OD5256-1	S	PNP	A/Unit	24 VDC		0.5 ms max./1.0 ms max.	P. A-69

### Transistor Output Units (MIL Connector, 30 mm Width)

Model	Number of points	Internal I/O common	Maximum value of load current	Rated volt- age	I/O refresh- ing method	ON/OFF response time	Refer- ence
NX-OD5121-5	- 16 points	NPN	0.5 A/point, 2 A/Unit	12 to 24 VDC	Switching Syn- chronous I/O refreshing and Free-Run refreshing	0.1 ms max./0.8 ms max.	P. A-71
NX-OD5256-5	To points	PNP		24 VDC		0.5 ms max./1.0 ms max.	P. A-73
NX-OD6121-5	- 32 points	NPN	0.5 A/point, 2 A/common, 4 A/Unit	12 to 24 VDC		0.1 ms max./0.8 ms max.	P. A-75
NX-OD6256-5	7 32 points	PNP		24 VDC		0.5 ms max./1.0 ms max.	P. A-77

#### Transistor Output Units (Fujitsu Connector, 30 mm Width)

Model	Number of points	Internal I/O common	Maximum value of load current	Rated volt- age	I/O refresh- ing method	ON/OFF response time	Refer- ence
NX-OD6121-6	32 points	NPN	0.5 A/point, 2 A/common, 4 A/Unit	12 to 24 VDC	Switching Syn- chronous I/O refreshing and Free-Run refreshing	0.1 ms max./0.8 ms max.	P. A-79

# Relay Output Units (Screwless Clamping Terminal Block, 12 mm Width)

Model	Num ber of point s	Relay type	Maximum switching capacity	I/O refresh- ing method	ON/OFF response time	Reference
NX-OC2633	2	N.O.	250 VAC/2 A (cosΦ = 1), 250	Free-Run	15 ms max./15	P. A-81
NX-OC2733	point s	N.O. + N.C.	VAC/2 A (cosФ = 0.4), 24 VDC/2 A, 4 A/Unit	refreshing	ms max.	P. A-83

## Relay Output Units (Screwless Clamping Terminal Block, 24 mm Width)

Model	Num ber of point s	Relay type	Maximum switching capacity	I/O refresh- ing method	ON/OFF response time	Reference
NX-OC4633	8 point s	N.O.	250 VAC/2A(cosφ=1), 250 VAC/2A(cosφ=0.4), 24 VDC/2A, 8 A/Unit	Free-Run refreshing	15 ms max./15 ms max.	P. A-85

#### DC Input/Transistor Output Units (MIL Connector, 30 mm Width)

Model	Number of points	Internal I/O common	Maximum value of load current	Rated volt- age	I/O refresh- ing method	ON/OFF response time	Refer- ence
NX-MD6121-5		Outputs: NPN Inputs: For		Outputs: 12 to 24 VDC		Outputs: 0.1 ms max./0.8 ms max.	P. A-89
NA-INDUTZT-3	Outputs: 16 points	both NPN/PNP	both	Inputs: 24 VDC	Switching Syn- chronous I/O refreshing and Free-Run refreshing	Inputs: 20 µs max./400 µs max.	F. A-09
NY MD6256 5	Inputs: 16 points	Outputs: PNP Inputs: For	A/Unit	Outputs: 24 VDC		Outputs: 0.5 ms max./1.0 ms max.	P. A-93
NA-IVIDU230-3	NX-MD6256-5	both NPN/PNP		Inputs: 24 VDC		Inputs: 20 μs max./400 μs max.	

#### DC Input/Transistor Output Units (Fujitsu Connector, 30 mm Width)

Model	Number of points	Internal I/O common	Maximum value of load current	Rated volt- age	I/O refresh- ing method	ON/OFF response time	Refer- ence
NX-MD6121-6	Outputs: 16 points Inputs: 16 points	Outputs: NPN Inputs: For both NPN/PNP	0.5 A/point, 2 A/Unit	Outputs: 12 to 24 VDC Inputs: 24 VDC	Switching Syn- chronous I/O refreshing and Free-Run refreshing	Outputs: 0.1 ms max./0.8 ms max. Inputs: 20 µs max./400 µs max.	P. A-97

#### A-1-2 Digital Input Units

#### Description of Items on Data Sheet of the DC Input Units

The meanings of the items on the data sheet of the DC Input Unit are explained in the table below.

Item	Description					
Unit name	The name of the Unit.					
Model	The model of the Unit.					
Number of points	The number of input points provided by the Unit.					
External connection	The type of terminal block and connector that is used for connecting the Unit. The number of termi-					
terminals	nals on the terminal block is also described when a screwless clamping terminal block is used.					
I/O refreshing method	he I/O refreshing methods that are used by the Unit. Free-Run refreshing, synchronous I/O refreshing and input refreshing with input changed time are available.					
Indicators	The type of indicators on the Unit and the layout of those indicators.*1					
Internal I/O common	The polarity of the input devices that are connected to the Unit. NPN connection and PNP connecton are available.					
Rated input voltage	The rated input voltage and range of the Unit.					
Input current	The input current at the rated voltage of the Unit.					
ON voltage/ON current	The input voltage in which the Unit input turns ON, and corresponding input current.					
OFF voltage/OFF cur- rent	The input voltage in which the Unit input turns OFF, and corresponding input current.					
ON/OFF response	The delay time for which the status change of the input terminals reaches the internal circuit of the					
time	Unit. The input filter time below is not included. It is described according to the ON/OFF sequence.					
Input filter time	The filter time when the status of the internal circuit is read as the data to the internal of the Unit. It is same for both ON/OFF. The filter time to be set by the Support Software is described.					
Dimensions	The dimensions of the Unit. They are described as W x H x D. The unit is "mm".					
Isolation method	The isolation method between the input circuit and internal circuit of the Unit.					
Insulation resistance	The insulation resistance between the input circuit and internal circuit of the Unit.					
Dielectric strength	The dielectric strength between the input circuit and internal circuit of the Unit.					
I/O power supply method	The method for supplying I/O power to the Unit. The supply method is determined for each Unit. The power is supplied from the NX bus or the external source.					
Current capacity of I/O	The current capacity of the power supply terminals (IOV/IOG) of the Unit. Do not exceed this value					
power supply terminal	when supplying the I/O power to the connected external devices.					
NX Unit power consumption	The power consumption of the NX Unit power supply of the Unit. The power consumption of the Unit connected to each of the following Units is separately given. If some of the following Units can not be connected to the Unit, relevant information is omitted.  • CPU Unit					
	Communications Coupler Unit					
	Communication Control Unit					
Current consumption	The current consumption from I/O power supply of the Unit. The above input current and current consumption of any connected external devices are excluded.					
from I/O power supply Weight	The weight of the Unit.					
Circuit layout	The input circuit layout of the Unit.					
Installation orienta-	The installation orientation of the Unit. The installation orientation of the Unit connected to each of					
tion and restrictions	the following Units is separately given, along with details of the specifications restricted due to the installation orientation, if any. If some of the following Units can not be connected to the Unit, relevant information is omitted.					
	CPU Unit					
	Communications Coupler Unit					
	Communication Control Unit					
Terminal connection diagram	A diagram of the connection between the Unit and connected external devices. When an I/O Power Supply Connection Unit or a Shield Connection Unit is required to be connected to the connected external devices, the description for such is included.					
Disconnec- tion/Short-circuit detection	The function of the Unit to detect a disconnection/short-circuit.					
Protective function	The protective function that the Unit has.					

<sup>\*1.</sup> The layout of the indicators after the appearance change is shown for models released in or before September 2018. For details on the applicable models and the changes, refer to 3-2-3 Appearance Change of the Indicators on page 3-17.

#### Description of Items on Data Sheet of the AC Input Units

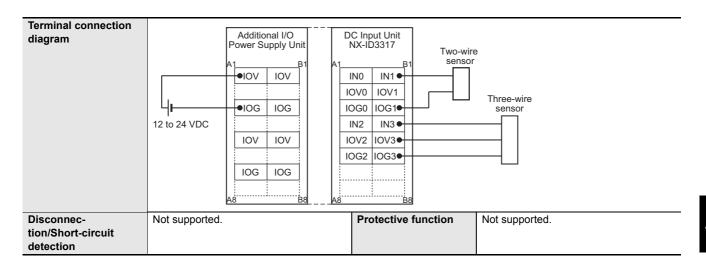
The meanings of the items on the data sheet of the AC Input Units are explained in the table below.

Item	Description
Unit name	The name of the Unit.
Model	The model of the Unit.
Number of points	The number of input points provided by the Unit.
External connection	The type of terminal block and connector that is used for connecting the Unit. The number of termi-
terminals	nals on the terminal block is also described when a screwless clamping terminal block is used.
I/O refreshing method	The I/O refreshing methods that are used by the Unit. Free-Run refreshing, synchronous I/O refreshing and input refreshing with input changed time are available.
Indicators	The type of indicators on the Unit and the layout of those indicators.*1
Internal I/O common	The polarity of the input devices that are connected to the Unit. NPN connection and PNP connection are available.
Rated input voltage	The rated input voltage and range of the Unit.
Input current	The input current at the rated voltage of the Unit.
ON voltage/ON current	The input voltage in which the Unit input turns ON, and corresponding input current.
OFF voltage/OFF cur- rent	The input voltage in which the Unit input turns OFF, and corresponding input current.
ON/OFF response time	The delay time for which the status change of the input terminals reaches the internal circuit of the Unit. The input filter time below is not included. It is described according to the ON/OFF sequence.
Input filter time	The filter time when the status of the internal circuit is read as the data to the internal of the Unit. It is same for both ON/OFF. The filter time to be set by the Support Software is described.
Dimensions	The dimensions of the Unit. They are described as W x H x D. The unit is "mm".
Isolation method	The isolation method between the input circuit and internal circuit of the Unit.
Insulation resistance	The insulation resistance between the input circuit and internal circuit of the Unit.
Dielectric strength	The dielectric strength between the input circuit and internal circuit of the Unit.
I/O power supply method	The method for supplying I/O power to the Unit. The supply method is determined for each Unit. The power is supplied from the NX bus or the external source.
Current capacity of I/O power supply terminal	The current capacity of the power supply terminals of the Unit. Do not exceed this value when supplying the I/O power to the connected external devices.
NX Unit power consumption	The power consumption of the NX Unit power supply of the Unit. The power consumption of the Unit connected to each of the following Units is separately given. If some of the following Units can not be connected to the Unit, relevant information is omitted.  • CPU Unit  • Communications Coupler Unit  • Communication Control Unit
Current consumption from I/O power supply	The current consumption from I/O power supply of the Unit. The above input current and current consumption of any connected external devices are excluded.
Weight	The weight of the Unit.
Circuit layout	The input circuit layout of the Unit.
Installation orienta- tion and restrictions	The installation orientation of the Unit. The installation orientation of the Unit connected to each of the following Units is separately given, along with details of the specifications restricted due to the installation orientation, if any. If some of the following Units can not be connected to the Unit, relevant information is omitted.  • CPU Unit
	Communications Coupler Unit
	Communication Control Unit
Terminal connection diagram	A diagram of the connection between the Unit and connected external devices. When an I/O Power Supply Connection Unit or a Shield Connection Unit is required to be connected to the connected external devices, the description for such is included.
Disconnec- tion/Short-circuit detection	The function of the Unit to detect a disconnection/short-circuit.
Protective function	The protective function that the Unit has.

<sup>\*1.</sup> The layout of the indicators after the appearance change is shown for models released in or before September 2018. For details on the applicable models and the changes, refer to 3-2-3 Appearance Change of the Indicators on page 3-17.

## DC Input Units (Screwless Clamping Terminal Block, 12 mm Width)

Unit name	DC Input Unit	Model	NX-ID3317
Number of points	4 points	External connection	Screwless clamping terminal block (12 ter-
		terminals	minals)
I/O refreshing method	Switching Synchronous I/O refreshing and F		Lubu
Indicators	TS indicator, input indicators	Internal I/O common	NPN
	ID3317	Rated input voltage	12 to 24 VDC (9 to 28.8 VDC)
	■TS	Input current	6 mA typical (at 24 VDC), rated current
	0 1	ON voltage/ON current	9 VDC min./3 mA min. (between IOV and each signal)
	2 3	OFF voltage/OFF cur-	2 VDC max./1 mA max. (between IOV and
		rent	each signal)
		ON/OFF response time	20 μs max./400 μs max.
		Input filter time	No filter, 0.25 ms, 0.5 ms, 1 ms (default), 2
			ms, 4 ms, 8 ms, 16 ms, 32 ms, 64 ms, 128
			ms, 256 ms
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation
Insulation resistance	20 MΩ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply	Supply from the NX bus	Current capacity of I/O	IOV: 0.1 A/terminal max., IOG: 0.1 A/termi-
method	Supply from the 14% bus	power supply terminal	nal max.
NX Unit power con-	Connected to a CPU Unit or Commu-	Current consumption	No consumption
sumption	nication Control Unit	from I/O power supply	·
	0.90 W max.		
	Connected to a Communications Cou-		
	pler Unit		
	0.50 W max.		
Weight	65 g max.		
Circuit layout			
	IOV0 to 3	r	conits
		\$ \ <b>\_</b> \$	Internal circuits
	Terminal block	rent control	ltern
	IN0 to IN3 0	circuit	
	IOG0 to 3		
	NX bus		U/O power supply + ☐ NX hijs
	connector		NX bus connector
	(left) LI/O power supply –		─────────────────────────────────────
Installation orienta-	Installation orientation:		
tion and restrictions	Connected to a CPU Unit or Communic	ation Control Unit	
	Possible in upright installation.		
	Connected to a Communications Coupl	er Unit	
	Possible in 6 orientations.		
	Restrictions: No restrictions		



Unit name	DC Input Unit	Model	NX-ID3343
Number of points	4 points	External connection terminals	Screwless clamping terminal block (12 terminals)
I/O refreshing method	Switching Synchronous I/O refreshing and F	ree-Run refreshing	
Indicators	TS indicator, input indicators	Internal I/O common	NPN
	ID0040	Rated input voltage	24 VDC (15 to 28.8 VDC)
	ID3343	Input current	3.5 mA typical (at 24 VDC), rated current
	0 1 2 3	ON voltage/ON current	15 VDC min./3 mA min. (between IOV and each signal)
	2 3	OFF voltage/OFF cur-	5 VDC max./1 mA max. (between IOV and
		rent	each signal)
		ON/OFF response time	100 ns max./100 ns max.
		Input filter time	No filter, 1 μs, 2 μs, 4 μs, 8 μs (default), 16 μs, 32 μs, 64 μs, 128 μs, 256 μs
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Digital isolator isolation
Insulation resistance	$20~\text{M}\Omega$ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply	Supply from the NX bus	Current capacity of I/O	IOV: 0.1 A/terminal max., IOG: 0.1 A/termi-
method		power supply terminal	nal max.
NX Unit power con-	Connected to a CPU Unit or Commu-	Current consumption	30 mA max.
sumption	nication Control Unit	from I/O power supply	
	0.90 W max.		
	Connected to a Communications Cou- plant Unit		
	pler Unit 0.55 W max.		
Weight	65 g max.		
Circuit layout	65 g Illax.		
Installation orientation and restrictions	Terminal block  IN0 to IN3  NX bus connector (left)  I/O power supply + I/O power supply - I/O power supply		I/O power supply + NX bus connector (right)
	Restrictions: No restrictions		
Terminal connection diagram	Power Supply Unit  A1  B1  OIOV IOV  IC  IC  IC  IC  IC  IC  IC  IC  IC  I	C Input Unit   Two-wire sensor   N0   IN1	Three-wire sensor

Disconnec-	Not supported.	Protective function	Not supported.
tion/Short-circuit			
detection			

Unit name	DC Input Unit	Model	NX-ID3344
Number of points	4 points	External connection terminals	Screwless clamping terminal block (12 terminals)
I/O refreshing method	Input refreshing with input changed time		
Indicators	TS indicator, input indicators	Internal I/O common	NPN
		Rated input voltage	24 VDC (15 to 28.8 VDC)
	ID3344	Input current	3.5 mA typical (at 24 VDC), rated current
	■TS	ON voltage/ON current	15 VDC min./3 mA min. (between IOV and
	0 1 2 3		each signal)
		OFF voltage/OFF cur-	5 VDC max./1 mA max. (between IOV and
		rent	each signal)
		ON/OFF response time	100 ns max./100 ns max.
		Input filter time	No filter*1
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Digital isolator isolation
Insulation resistance	20 MΩ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply	Supply from the NX bus	Current capacity of I/O	IOV: 0.1 A/terminal max., IOG: 0.1 A/termi-
method	,	power supply terminal	nal max.
NX Unit power con-	Connected to a CPU Unit	Current consumption	30 mA max.
sumption	0.90 W max.	from I/O power supply	
	Connected to a Communications Cou-		
	pler Unit		
	0.50 W max.		
Weight	65 g max.		
Circuit layout			
	□ IOV0 to 3♦	Power	
		supply	
		<b>\$</b>	i i i i i i i i i i i i i i i i i i i
	Terminal block INO to IN3	rent control =	
		rent control circuit	oicouits
		ifi	nal
	LIOG0 to 30		Internal (
		_	
	NV has FI/O power supply to		U/O power supply + ☐ NX his
	NX bus connector		I/O power supply + 7 NX bus connector
	(left) LI/O power supply –		I/O power supply – (right)
Installation orienta-	Installation orientation:		
tion and restrictions			
	Connected to a CPU Unit  Page 1 to a control of the control o		
	Possible in upright installation.	11.29	
	Connected to a Communications Coupl Possible in 6 orientations.	er Unit	
	Possible in 6 orientations.		
	Restrictions: No restrictions		
Terminal connection			
diagram		C Input Unit NX-ID3344	_
		I WO-WIR	
	A1 B1 A1	INO IN1	
		OV0 IOV1	
		OG0 IOG1	Three-wire sensor
	'   <u>                                </u>	IN2 IN3	
	l   <del>                                   </del>	0V2 I0V3	
	<del>                               </del>	OG3 IOG3	
	IOG IOG		
	A8 B8 A8	B8	

Disconnec-	Not supported.	Protective function	Not supported.
tion/Short-circuit			
detection			

<sup>\*1.</sup> This model does not support the input filter. If the Unit is susceptible to noise, take countermeasures such as separating or shielding the Unit and signal lines from the noise source. Refer to *Countermeasures to Reduce the Effects of Noise* on page 4-53 for information on countermeasures.

Unit name	DC Input Unit	Model	NX-ID3417
Number of points	4 points	External connection terminals	Screwless clamping terminal block (12 terminals)
I/O refreshing method	Switching Synchronous I/O refreshing and F	_	
Indicators	TS indicator, input indicators	Internal I/O common	PNP
	ID3417	Rated input voltage	12 to 24 VDC (9 to 28.8 VDC)
	●TS 0 1 2 3	Input current ON voltage/ON current	6 mA typical (at 24 VDC), rated current 9 VDC min./3 mA min. (between IOG and each signal)
	2 3	OFF voltage/OFF cur-	2 VDC max./1 mA max. (between IOG and
		rent	each signal)
		ON/OFF response time	20 μs max./400 μs max.
		Input filter time	No filter, 0.25 ms, 0.5 ms, 1 ms (default), 2 ms, 4 ms, 8 ms, 16 ms, 32 ms, 64 ms, 128 ms, 256 ms
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation
Insulation resistance	$20~\text{M}\Omega$ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply	Supply from the NX bus	Current capacity of I/O	IOV: 0.1 A/terminal max., IOG: 0.1 A/termi-
method		power supply terminal	nal max.
NX Unit power con- sumption	Connected to a CPU Unit or Commu- nication Control Unit	Current consumption from I/O power supply	No consumption
Jumpuon	0.90 W max.	nom no power supply	
	Connected to a Communications Cou-		
	pler Unit		
	0.50 W max.		
Weight	65 g max.		
Installation orientation and restrictions	Installation orientation:  Connected to a CPU Unit or Communic Possible in upright installation.  Connected to a Communications Coupl Possible in 6 orientations.  Restrictions: No restrictions		I/O power supply + NX bus connector (right)
Terminal connection			
diagram	Power Supply Unit  A1  B1  IOV  IOV  IOV  IOV  IOV  IOV  IOV  IO	C Input Unit NX-ID3417  Two-wire sensor  N0 IN1   DV0 IOV1  DG0 IOG1  N2 IN3   DV2 IOV3  DG2 IOG3  B8	Three-wire sensor

Disconnec-	Not supported.	Protective function	Not supported.
tion/Short-circuit			
detection			

Unit name	DC Input Unit	Model	NX-ID3443
Number of points	4 points	External connection terminals	Screwless clamping terminal block (12 terminals)
I/O refreshing method	Switching Synchronous I/O refreshing and F	ree-Run refreshing	· · ·
Indicators	TS indicator, input indicators	Internal I/O common	PNP
		Rated input voltage	24 VDC (15 to 28.8 VDC)
	ID3443	Input current	3.5 mA typical (at 24 VDC), rated current
	DTS	ON voltage/ON current	15 VDC min./3 mA min. (between IOG and
	0 1 2 3		each signal)
		OFF voltage/OFF cur-	5 VDC max./1 mA max. (between IOG and
		rent	each signal)
		ON/OFF response time	100 ns max./100 ns max.
		Input filter time	No filter, 1 μs, 2 μs, 4 μs, 8 μs (default), 16 μs, 32 μs, 64 μs, 128 μs, 256 μs
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Digital isolator isolation
Insulation resistance	$20~\text{M}\Omega$ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply	Supply from the NX bus	Current capacity of I/O	IOV: 0.1 A/terminal max., IOG: 0.1 A/termi-
method		power supply terminal	nal max.
NX Unit power con-	Connected to a CPU Unit or Commu-	Current consumption	30 mA max.
sumption	nication Control Unit	from I/O power supply	
	0.90 W max.		
	Connected to a Communications Coupler Unit		
	0.55 W max.		
Waight			
Weight Circuit layout	65 g max.		
Circuit layout			
		Power	
	IOV0 to 3	supply	Ž.
		Current control	
	Terminal block IN0 to IN3	circuit	
		\ \\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	
	LIOG0 to 3	Current control circuit	Internal circuits
		L	
	NX bus		
	connector		connector
	(left) LI/O power supply – O		I/O power supply – (right)
Installation orienta-	Installation orientation:		
tion and restrictions	Connected to a CPU Unit or Communic	ation Control Unit	
	Possible in upright installation.		
	Connected to a Communications Coupl	er Unit	
	Possible in 6 orientations.		
	Restrictions: No restrictions		
Terminal connection			
diagram	Additional I/O DO Power Supply Unit N	C Input Unit IX-ID3443	
	A1 B1 A1	Two-wire sensor	
		NO IN1	
		OV0 IOV1	
	IOG IOG IC	OGO IOG1	Three-wire sensor
	'   <del>  -   -  </del>     <del>  -  </del>	N2 IN3 •	$-\Box$
	l   <del>i i  </del> i    ⊢"	0V2 IOV3	
	<del>                                   </del>	0G2 10G3	
	IOG IOG		
	A8 B8 _ A8	i B8	
	1		

Disconnec-	Not supported.	Protective function	Not supported.
tion/Short-circuit			
detection			

Unit name	DC Input Unit	Model	NX-ID3444
Number of points	4 points	External connection terminals	Screwless clamping terminal block (12 terminals)
I/O refreshing method	Input refreshing with input changed time	T	Loup
Indicators	TS indicator, input indicators	Internal I/O common Rated input voltage	PNP 24 VDC (15 to 28.8 VDC)
	ID3444	Input current	3.5 mA typical (at 24 VDC), rated current
	<b>■</b> TS	ON voltage/ON current	15 VDC min./3 mA min. (between IOG and
	0 1 2 3	· ·	each signal)
		OFF voltage/OFF cur-	5 VDC max./1 mA max. (between IOG and
		ON/OFF response time	each signal) 100 ns max./100 ns max.
		Input filter time	No filter*1
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Digital isolator isolation
Insulation resistance	$20 \text{ M}\Omega$ min. between isolated circuits (at	Dielectric strength	510 VAC between isolated circuits for 1
	100 VDC)	2.0.00009	minute at a leakage current of 5 mA max.
I/O power supply	Supply from the NX bus	Current capacity of I/O	IOV: 0.1 A/terminal max., IOG: 0.1 A/termi-
method		power supply terminal	nal max.
NX Unit power consumption	Connected to a CPU Unit     0.90 W max.	Current consumption from I/O power supply	30 mA max.
Jumpuon	Connected to a Communications Cou-	nom no power suppry	
	pler Unit		
	0.50 W max.		
Weight	65 g max.		
Circuit layout			
	J	Power	
	IOV0 to 3	supply	
	Terminal block IN0 to IN3	Current control	
	Tomming Book   Into to Into	Current control	circuits
	IOG0 to 3	\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \	Internal
	Liodo to 3 O		
	NX bus \[ I/O power supply + \( \)		U/O power supply + ☐ NX bus
	connector		connector
	(left) LI/O power supply –		
In stallation only at-	La challation agic shallon		
Installation orienta- tion and restrictions	Installation orientation:		
	Connected to a CPU Unit     Possible in upright installation.		
	Connected to a Communications Coupl	er Unit	
	Possible in 6 orientations.		
	Restrictions: No restrictions		
Terminal connection		N. (11.%	
diagram		CInput Unit X-ID3444 Two-wire	
	A1	B1 sensor	
		√0 IN1 •	
		V0 IOV1	Three-wire
		G0 IOG1 V2 IN3 •	sensor
		V2 IOV3	
		G2 IOG3●	
	IOG IOG		_
	<u>  A8 B8  _                                 </u>	B8	,
Disconnec-	Not supported.	Protective function	Not supported.
tion/Short-circuit detection			
			l

\*1. This model does not support the input filter. If the Unit is susceptible to noise, take countermeasures such as separating or shielding the Unit and signal lines from the noise source. Refer to *Countermeasures to Reduce the Effects of Noise* on page 4-53 for information on countermeasures.

Unit name	DC Input Unit	Model	NX-ID4342
Number of points	8 points	External connection terminals	Screwless clamping terminal block (16 terminals)
I/O refreshing method	Switching Synchronous I/O refreshing and F	_	
Indicators	TS indicator, input indicators	Internal I/O common	NPN
	ID4342	Rated input voltage	24 VDC (15 to 28.8 VDC)
	DTS 0 1 2 3	ON voltage/ON current	3.5 mA typical (at 24 VDC), rated current 15 VDC min./3 mA min. (between IOV and each signal)
	4 5	OFF voltage/OFF cur-	5 VDC max./1 mA max. (between IOV and
	6 7	ON/OFF response time	each signal)  20 µs max./400 µs max.
		Input filter time	No filter, 0.25 ms, 0.5 ms, 1 ms (default), 2
		mpat mior time	ms, 4 ms, 8 ms, 16 ms, 32 ms, 64 ms, 128 ms, 256 ms
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation
Insulation resistance	20 M $\Omega$ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply method	Supply from the NX bus	Current capacity of I/O power supply terminal	IOG: 0.1 A/terminal max.
NX Unit power consumption	Connected to a CPU Unit or Communication Control Unit     0.90 W max.	Current consumption from I/O power supply	No consumption
	Connected to a Communications Coupler Unit		
	0.50 W max.		
Weight Circuit layout	65 g max.		
	Terminal block IN0 to IN7 Curry IOG0 to 7  NX bus connector (left) I/O power supply -	ent control circuit	I/O power supply + NX bus connector (right)
Installation orienta-	Installation orientation:		
tion and restrictions	<ul> <li>Connected to a CPU Unit or Communic Possible in upright installation.</li> <li>Connected to a Communications Coupl Possible in 6 orientations.</li> </ul> Restrictions: No restrictions		
Terminal connection			
diagram	IOV   IOV	NX-ID4342	Two-wire sensor  Three-wire sensor

Disconnec-	Not supported.	Protective function	Not supported.
tion/Short-circuit			
detection			

Unit name	DC Input Unit	Model	NX-ID4442
Number of points	8 points	External connection terminals	Screwless clamping terminal block (16 terminals)
I/O refreshing method	Switching Synchronous I/O refreshing and F	ree-Run refreshing	
Indicators	TS indicator, input indicators	Internal I/O common	PNP
	ID 4440	Rated input voltage	24 VDC (15 to 28.8 VDC)
	ID4442 PTS	Input current	3.5 mA typical (at 24 VDC), rated current
	0 1 2 3	ON voltage/ON current	15 VDC min./3 mA min. (between IOG and each signal)
	4 5	OFF voltage/OFF cur-	5 VDC max./1 mA max. (between IOG and
	6 7	rent	each signal)
		ON/OFF response time	20 μs max./400 μs max.
		Input filter time	No filter, 0.25 ms, 0.5 ms, 1 ms (default), 2 ms, 4 ms, 8 ms, 16 ms, 32 ms, 64 ms, 128 ms, 256 ms
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation
Insulation resistance	$20~\text{M}\Omega$ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply	Supply from the NX bus	Current capacity of I/O	IOV: 0.1 A/terminal max.
method		power supply terminal	
NX Unit power consumption	Connected to a CPU Unit or Communication Control Unit	Current consumption from I/O power supply	No consumption
	0.90 W max.		
	Connected to a Communications Cou-		
	pler Unit		
	0.50 W max.		
Weight Circuit layout	65 g max.		
Installation orientation and restrictions			I/O power supply + NX bus connector (right)
Terminal connection diagram	Additional I/O Power Supply Unit  A1 B1 IOG	Supply DC Input Unit NX-ID4442    IOG	Two-wire sensor  Three-wire sensor

Disconnec-	Not supported.	Protective function	Not supported.
tion/Short-circuit			
detection			

Unit name	DC Input Unit	Model	NX-ID5342
Number of points	16 points	External connection terminals	Screwless clamping terminal block (16 terminals)
I/O refreshing method	Switching Synchronous I/O refreshing and F		
Indicators	TS indicator, input indicators	Internal I/O common	NPN
	ID5342	Rated input voltage	24 VDC (15 to 28.8 VDC)
	DTS	Input current ON voltage/ON current	2.5 mA typical (at 24 VDC), rated current 15 VDC min./2 mA min. (between IOV and
	0 1 2 3 4 5 6 7	ON VOILAGE/ON CAITEIN	each signal)
	8 9 10 11	OFF voltage/OFF cur-	5 VDC max./0.5 mA max. (between IOV and
	12 13 14 15	rent	each signal)
		ON/OFF response time Input filter time	20 μs max./400 μs max.  No filter, 0.25 ms, 0.5 ms, 1 ms (default), 2
		input inter time	ms, 4 ms, 8 ms, 16 ms, 32 ms, 64 ms, 128 ms, 256 ms
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation
Insulation resistance	$20~\text{M}\Omega$ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply method	Supply from the NX bus	Current capacity of I/O power supply terminal	Without I/O power supply terminals
NX Unit power con-	Connected to a CPU Unit or Commu- nication Control Unit	Current consumption from I/O power supply	No consumption
sumption	0.90 W max.	nom no power supply	
	Connected to a Communications Cou-		
	pler Unit		
	0.55 W max.		
Weight Circuit layout	65 g max.		
Installation orientation and restrictions	Terminal block IN0 to IN15  NX bus connector (left)  I/O power supply -  Installation orientation:  Connected to a CPU Unit or Communic Possible in upright installation.  Connected to a Communications Coupl Possible in 6 orientations.  Restrictions: No restrictions		I/O power supply + NX bus connector (right)
Terminal connection		<del></del>	
diagram	Power Supply Unit Connection Uni	Y   I/O Power Supply to Connection Unit	2 IN3 4 IN5 6 IN7 8 IN9 0 IN11 2 IN13

Disconnec-	Not supported.	Protective function	Not supported.
tion/Short-circuit			
detection			

Number of points  I/O refreshing method Indicators	16 points	External connection	Screwless clamping terminal block (16 ter-
	Switching Synchronous I/O refreshing and E	terminals	minals)
Indicators	Switching Synchronous I/O refreshing and Free-Run refreshing		
	TS indicator, input indicators	Internal I/O common	PNP
	ID5442	Rated input voltage	24 VDC (15 to 28.8 VDC)
	■TS	Input current ON voltage/ON current	2.5 mA typical (at 24 VDC), rated current 15 VDC min./2 mA min. (between IOG and
	0 1 2 3 4 5 6 7	Oit voitage/oit carrent	each signal)
	8 9 10 11	OFF voltage/OFF cur-	5 VDC max./0.5 mA max. (between IOG and
	12 13 14 15	rent	each signal)
		ON/OFF response time Input filter time	20 μs max./400 μs max.  No filter, 0.25 ms, 0.5 ms, 1 ms (default), 2
		input inter time	ms, 4 ms, 8 ms, 16 ms, 32 ms, 64 ms, 128 ms, 256 ms
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation
Insulation resistance	$20~\text{M}\Omega$ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply method	Supply from the NX bus	Current capacity of I/O power supply terminal	Without I/O power supply terminals
NX Unit power consumption	Connected to a CPU Unit or Commu- nication Control Unit	Current consumption from I/O power supply	No consumption
oumpaon.	0.90 W max.	nom we penor cappry	
	Connected to a Communications Cou-		
	pler Unit		
10/a: mla4	0.55 W max.		
Weight Circuit layout	65 g max.		
		nt control irreuit	I/O power supply + NX bus connector (right)
Installation orienta-	Installation orientation:		
tion and restrictions	Connected to a CPU Unit or Communication Control Unit     Possible in upright installation.		
	<ul> <li>Connected to a Communications Coupl Possible in 6 orientations.</li> </ul>	er Unit	
	Possible in 6 orientations.		
	Restrictions: No restrictions		
Terminal connection		y I/O Power Supply DC	Input I Init
diagram	Power Supply Unit Connection Uni	t Connection Unit N	Input Unit (-ID5442
	IOV   IOV	A1	2 IN3 4 IN5 6 IN7 8 IN9 0 IN11 2 IN13

Disconnec-	Not supported.	Protective function	Not supported.
tion/Short-circuit			
detection			

# DC Input Units (M3 Screw Terminal Block, 30 mm Width)

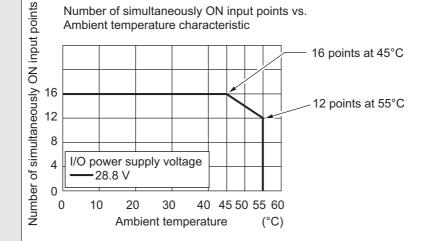
Unit name	DC Input Unit	Model	NX-ID5142-1
Number of points	16 points	External connection terminals	M3 screw terminal block (18 terminals)
I/O refreshing method	Switching Synchronous I/O refreshing and F		
Indicators	TS indicator, input indicators	Internal I/O common	For both NPN/PNP
	IDE142_1	Rated input voltage	24 VDC (15 to 28.8 VDC)
	ID5142−1 • • • • • • • • • • • • • • • • • • •	Input current	7 mA typical (at 24 VDC)
	0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15	ON voltage/ON current	15 VDC min./3 mA min. (between COM and each signal)
		OFF voltage/OFF cur- rent	5 VDC max./1 mA max. (between COM and each signal)
		ON/OFF response time	20 µs max./400 µs max.
		Input filter time	No filter, 0.25 ms, 0.5 ms, 1 ms (default), 2 ms, 4 ms, 8 ms, 16 ms, 32 ms, 64 ms, 128 ms, 256 ms
Dimensions	30 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation
Insulation resistance	$20~\text{M}\Omega$ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply method	Supply from external source	Current capacity of I/O power supply terminal	Without I/O power supply terminals
NX Unit power consumption	Connected to a CPU Unit or Communication Control Unit 0.85 W max. Connected to a Communications Coupler Unit 0.55 W max.	Current consumption from I/O power supply	No consumption
Weight	125 g max.		
Circuit layout	Terminal block $\begin{array}{ c c c c c c c c c c c c c c c c c c c$	Input indicator Internal circuits	I/O power supply + I/O power supply - (right)

Installation orientation:

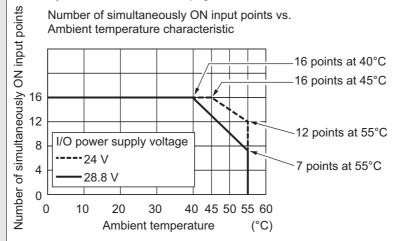
- Connected to a CPU Unit or Communication Control Unit Possible in upright installation.
- Connected to a Communications Coupler Unit Possible in 6 orientations.

Restrictions: As shown in the following.

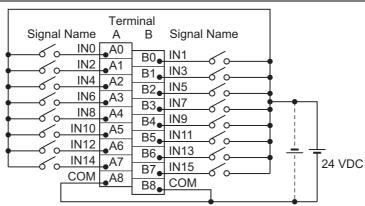
• For upright installation



· For any installation other than upright



# Terminal connection diagram



- The polarity of the input power supply can be connected in either direction.
- Terminal numbers in the terminal connection diagram are used in this manual, but they are not printed on all Units.

Disconnection/Short-circuit detection Not supported.

Protective function

Not supported.

# DC Input Units (MIL Connector, 30 mm Width)

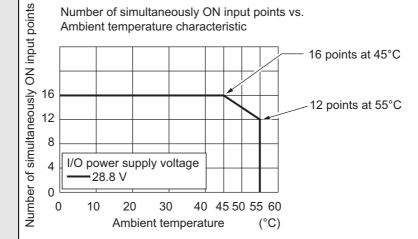
Unit name	DC Input Unit	Model	NX-ID5142-5
Number of points	16 points	External connection terminals	MIL connector (20 terminals)
I/O refreshing method	Switching Synchronous I/O refreshing and F		
Indicators	TS indicator, input indicators	Internal I/O common	For both NPN/PNP
	IDE142 E	Rated input voltage	24 VDC (15 to 28.8 VDC)
	ID5142-5 ■TS	Input current	7 mA typical (at 24 VDC)
	0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15	ON voltage/ON current	15 VDC min./3 mA min. (between COM and each signal)
		OFF voltage/OFF cur- rent	5 VDC max./1 mA max. (between COM and each signal)
		ON/OFF response time	20 μs max./400 μs max.
		Input filter time	No filter, 0.25 ms, 0.5 ms, 1 ms (default), 2 ms, 4 ms, 8 ms, 16 ms, 32 ms, 64 ms, 128 ms, 256 ms
Dimensions	30 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation
Insulation resistance	$20~\text{M}\Omega$ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply method	Supply from external source	Current capacity of I/O power supply terminal	Without I/O power supply terminals
NX Unit power consumption	Connected to a CPU Unit or Communication Control Unit 0.85 W max. Connected to a Communications Coupler Unit 0.55 W max.	Current consumption from I/O power supply	No consumption
Weight	85 g max.		
Circuit layout	$\begin{array}{c c} \text{Connector} & \begin{array}{c} \text{INO} & \\ \text{to} & \\ \text{IN15} & \\ \text{COM} & \\ \text{COM} & \\ \text{Connector} \\ \text{(left)} & \begin{array}{c} \text{I/O power} \\ \text{supply} + \\ \text{I/O power} \\ \text{supply} - \\ \end{array} \end{array}$	Input indicator Internal circuits	I/O power supply + I/O power supply - (right)

Installation orientation:

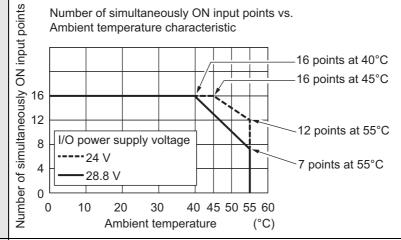
- Connected to a CPU Unit or Communication Control Unit Possible in upright installation.
- Connected to a Communications Coupler Unit Possible in 6 orientations.

Restrictions: As shown in the following.

· For upright installation



• For any installation other than upright



# Terminal connection diagram

	Signal	Conn	ector	Signal
24 VDC	name	р	in	name
[- <b> </b>  -;	NC	1	2	NC
	COM	3	4	COM
	IN15	5	6	IN07
	IN14	7	8	IN06
	IN13	9	10	IN05
	IN12	11	12	IN04
	IN11	13	14	IN03
	IN10	15	16	IN02
	IN09	17	18	IN01
	IN08	19	20	IN00

- The polarity of the input power supply can be connected in either direction.
- Be sure to wire both pins 3 and 4 (COM), and set the same polarity for both pins.

tion/Short-circuit detection	Disconnec-	Not supported.	Protective function	Not supported.
detection	tion/Short-circuit			
	detection			

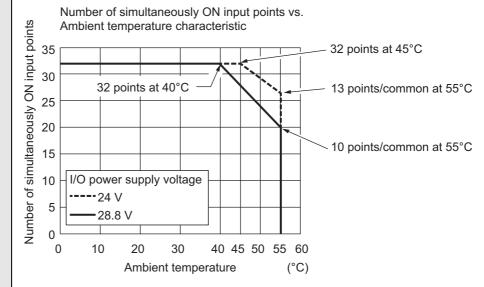
Unit name	DC Input Unit	Model	NX-ID6142-5
Number of points	32 points	External connection terminals	MIL connector (40 terminals)
I/O refreshing method	Switching Synchronous I/O refreshing and F	ree-Run refreshing	
Indicators	TS indicator, input indicators	Internal I/O common	For both NPN/PNP
	ID 04 40 F	Rated input voltage	24 VDC (19 to 28.8 VDC)
	ID6142-5 ▶™	Input current	4.1 mA typical (24 VDC)
	0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15	ON voltage/ON current	19 VDC min./3 mA min. (between COM and each signal)
	16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31	OFF voltage/OFF cur- rent	5 VDC max./1 mA max. (between COM and each signal)
		ON/OFF response time	20 μs max./400 μs max.
		Input filter time	No filter, 0.25 ms, 0.5 ms, 1 ms (default), 2 ms, 4 ms, 8 ms, 16 ms, 32 ms, 64 ms, 128 ms, 256 ms
Dimensions	30 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation
Insulation resistance	20 MΩ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply method	Supply from external source	Current capacity of I/O power supply terminal	Without I/O power supply terminals
NX Unit power consumption	Connected to a CPU Unit or Communication Control Unit 0.90 W max. Connected to a Communications Coupler Unit 0.60 W max.	Current consumption from I/O power supply	No consumption
Weight	90 g max.		
Circuit layout	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	indicator   I/O p	y + connector (right)

Installation orientation:

- Connected to a CPU Unit or Communication Control Unit Possible in upright installation.
- Connected to a Communications Coupler Unit Possible in 6 orientations.

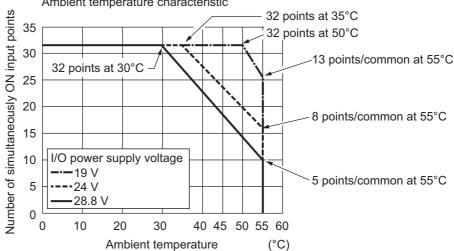
Restrictions: As shown in the following.

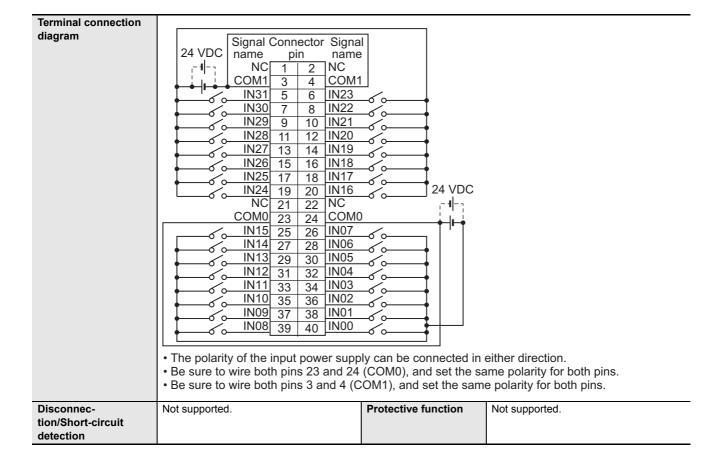
• For upright installation



· For any installation other than upright

Number of simultaneously ON input points vs. Ambient temperature characteristic





# DC Input Units (Fujitsu Connector, 30 mm Width)

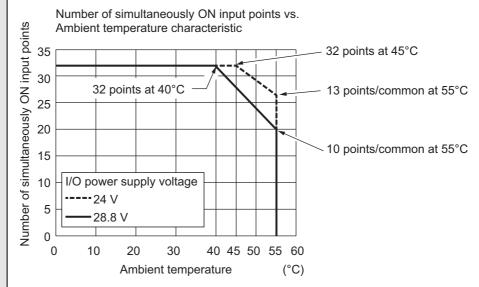
Unit name	DC Input Unit	Model	NX-ID6142-6
Number of points	32 points	External connection	Fujitsu connector (40 terminals)
		terminals	
I/O refreshing method	Switching Synchronous I/O refreshing and F	ree-Run refreshing	
Indicators	TS indicator, input indicators	Internal I/O common	For both NPN/PNP
	ID6142-6	Rated input voltage	24 VDC (19 to 28.8 VDC)
	DTS	Input current	4.1 mA typical (24 VDC)
	0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15	ON voltage/ON current	19 VDC min./3 mA min. (between COM and each signal)
	16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31	OFF voltage/OFF cur- rent	5 VDC max./1 mA max. (between COM and each signal)
		ON/OFF response time	20 μs max./400 μs max.
		Input filter time	No filter, 0.25 ms, 0.5 ms, 1 ms (default), 2 ms, 4 ms, 8 ms, 16 ms, 32 ms, 64 ms, 128 ms, 256 ms
Dimensions	30 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation
Insulation resistance	20 MΩ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply method	Supply from external source	Current capacity of I/O power supply terminal	Without I/O power supply terminals
NX Unit power con-	Connected to a CPU Unit or Commu-	Current consumption	No consumption
sumption	nication Control Unit	from I/O power supply	
	0.95 W max.		
	Connected to a Communications Cou-		
	pler Unit		
	0.55 W max.		
Weight	90 g max.		
Circuit layout	$\begin{array}{c c} \text{Connector} & \begin{array}{c c} \text{IN0} & 3.3 \text{ k}\Omega \\ \text{to} & \text{IN15} & \\ \text{COM0} & 3.3 \text{ k}\Omega \\ \text{IN16} & 3.3 \text{ k}\Omega \\ \text{IN16} & \\ \text{to} & \\ \text{IN31} & \\ \text{COM1} & \\ \text{COM2} &$	indicator Internal circuits   I/O po supply   I/O po supply	y + connector (right)

Installation orientation:

- Connected to a CPU Unit or Communication Control Unit Possible in upright installation.
- Connected to a Communications Coupler Unit Possible in 6 orientations.

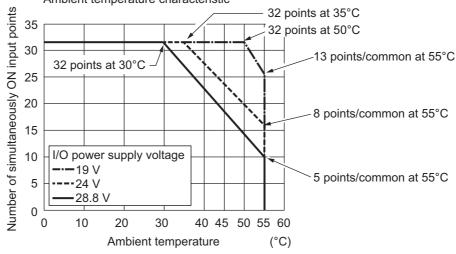
Restrictions: As shown in the following.

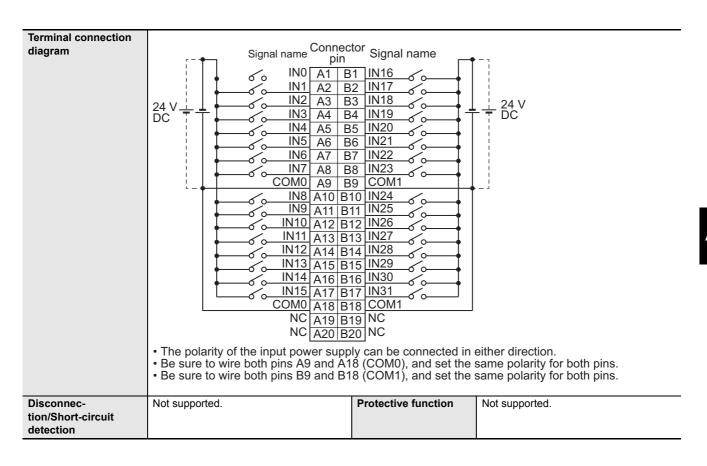
• For upright installation



· For any installation other than upright

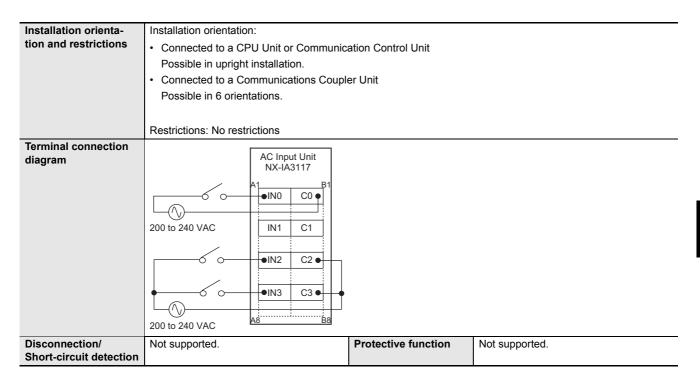
Number of simultaneously ON input points vs. Ambient temperature characteristic





# AC Input Units (Screwless Clamping Terminal Block, 12 mm Width)

Unit name	AC Input Unit	Model	NX-IA3117
Number of points	4 points, independent contacts	External connection	Screwless clamping terminal block (8 ter-
		terminals	minals)
I/O refreshing method	Free-Run refreshing	T	
Indicators	TS indicator, input indicators	Internal I/O common	No polarity
	IA3117	Rated input voltage	200 to 240 VAC, 50/60 Hz (170 to 264 VAC, ±3 Hz)
	●TS 0 1	Input current	9 mA typical (at 200 VAC, 50 Hz)
	2 3		11 mA typical (at 200 VAC, 60 Hz)
		ON voltage/ON current	120 VAC min./4 mA min.
		OFF voltage/OFF cur- rent	40 VAC max./2 mA max.
		ON/OFF response time	10 ms max./40 ms max.
		Input filter time	No filter, 0.25 ms, 0.5 ms, 1 ms (default), 2 ms, 4 ms, 8 ms, 16 ms, 32 ms, 64 ms, 128 ms, 256 ms
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation
Insulation resistance	Between each AC input circuit: $20~\text{M}\Omega$ min. (at $500~\text{VDC}$ )  Between the external terminals and the functional ground terminal: $20~\text{M}\Omega$ min.	Dielectric strength	Between each AC input circuit: 3700 VAC for 1 min at a leakage current of 5 mA max. Between the external terminals and func-
	(at 500 VDC)		tional ground terminal: 2300 VAC for 1
	Between the external terminals and internal circuits: 20 MΩ min. (at 500 VDC)		min at a leakage current of 5 mA max.  Between the external terminals and inter-
	Between the internal circuit and the functional ground terminal: $20 \text{ M}\Omega$ min. (at		nal circuits: 2300 VAC for 1 min at a leakage current of 5 mA max.
	100 VDC)		Between the internal circuit and the functional ground terminal: 510 VAC for 1 min at a leakage current of 5 mA max.
I/O power supply method	Supplied from external source.	Current capacity of I/O power supply terminal	Without I/O power supply terminals
NX Unit power consumption	Connected to a CPU Unit or Communication Control Unit 0.80 W max. Connected to a Communications Coupler Unit 0.50 W max.	Current consumption from I/O power supply	No consumption
Weight	60 g max.		
Circuit layout			
	Terminal block  C0 to C3  NX bus connector (left)  I/O power supply +		I/O power supply + NX bus connector (right)



# A-1-3 Digital Output Units

### Description of Items on the Data Sheet of the Transistor Output Unit

The meanings of the items on the data sheet of the Transistor Output Units are explained in the table below.

Item	Description	
Unit name	The name of the Unit.	
Model	The model of the Unit.	
Number of points	The number of output points provided by the Unit.	
External connection terminals	The type of terminal block and connector that is used for connecting the Unit. The number of terminals on the terminal block is also described when a correlated element terminal block is used.	
I/O refreshing method	nals on the terminal block is also described when a screwless clamping terminal block is used.  The I/O refreshing methods that are used by the Unit. Free-Run refreshing and synchronous I/O	
i/O refreshing method	refreshing are available.	
	The I/O refreshing methods that are used by the Unit. Free-Run refreshing, synchronous I/O	
	refreshing and output refreshing with specified time stamp are available.	
Indicators	The type of indicators on the Unit and the layout of those indicators.*1	
Internal I/O common	The polarity of the output devices that are connected to the Unit. NPN connection and PNP con-	
	nection are available.	
Rated voltage	The rated output voltage of the Unit.	
Operating load volt-	The output load voltage range of the Unit.	
age range		
Maximum value of	The maximum output load current of the Unit. The specifications for each output point and for the	
load current	Unit are described. The specifications for each common are described depending on model.	
Maximum inrush cur- rent	The maximum allowable inrush current of the Unit. Any inrush current from an external connection load must be kept to or below this value.	
Leakage current	The leakage current when the output of the Unit is OFF.	
Residual voltage	The residual voltage when the output of the Unit is ON.	
ON/OFF response	The delay time for which data in the internal circuit is reflected in the state of output elements of the	
time	Unit. It is described according to the ON/OFF sequence.	
Dimensions	The dimensions of the Unit. They are described as W x H x D. The unit is "mm".	
Isolation method	The isolation method of the output circuit and internal circuit of the Unit.	
Insulation resistance	The insulation resistance between the output circuit and internal circuit of the Unit.	
Dielectric strength	The dielectric strength between the output circuit and internal circuit of the Unit.	
I/O power supply	The method for supplying I/O power to the Unit. The supply method is determined for each Unit.	
method	The power is supplied from the NX bus or the external source.	
Current capacity of I/O	The current capacity of the I/O power supply terminals (IOV/IOG) of the Unit. Do not exceed this	
power supply terminal	value when supplying the I/O power to the connected external devices.	
NX Unit power consumption	The power consumption of the NX Unit power supply of the Unit. The power consumption of the Unit connected to each of the following Units is separately given. If some of the following Units can	
Sumption	not be connected to the Unit, relevant information is omitted.	
	CPU Unit	
	Communications Coupler Unit	
	Communication Control Unit	
Current consumption	The current consumption from I/O power supply of the Unit. The load current of any external con-	
from I/O power supply	nection load and current consumption of any connected external devices are not included.	
Weight	The weight of the Unit.	
Circuit layout	The output circuit layout of the Unit.	
Installation orienta-	The installation orientation of the Unit. The installation orientation of the Unit connected to each of	
tion and restrictions	the following Units is separately given, along with details of the specifications restricted due to the	
	installation orientation, if any. If some of the following Units can not be connected to the Unit, relevant information is omitted.	
	CPU Unit     Communications Coupler Unit	
	Communications Coupler Unit     Communication Control Unit	
	Communication Control Unit	

Terminal connection diagram	A diagram of the connection between the Unit and connected external devices. When an I/O Power Supply Connection Unit or a Shield Connection Unit is required to be connected to the connected external devices, the description for such is included.
Disconnection/Short-circuit detection	The function of the Unit to detect a disconnection/short-circuit.
Protective function	The protective function that the Unit has.

<sup>\*1.</sup> The layout of the indicators after the appearance change is shown for models released in or before September 2018. For details on the applicable models and the changes, refer to 3-2-3 Appearance Change of the Indicators on page 3-17.

# Description of Items on the Data Sheet of the Relay Output Unit

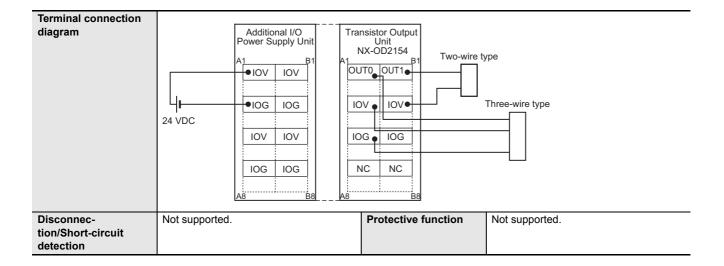
The meanings of the items on the data sheet of the Relay Output Unit are explained in the table below.

Item	Description		
Unit name	The name of the Unit.		
Model	The model of the Unit.		
Number of points	The number of output points provided by the Unit.		
External connection	The type of terminal block and connector that is used for connecting the Unit. The number of termi-		
terminals	nals on the terminal block is also described when a screwless clamping terminal block is used.		
I/O refreshing method	The I/O refreshing methods that are used by the Unit. Free-Run refreshing and synchronous I/O		
	refreshing are available.		
Indicators	The type of indicators on the Unit and the layout of those indicators.*1		
Relay type	The type of relay that is connected to the Unit. There are N.O. and N.O. + N.C		
Maximum switching capacity	The maximum value of switchable current of the connected relay.		
Minimum switching capacity	The minimum value of switchable current of the connected relay.		
Relay service life	The service life of the connected relay.		
ON/OFF response time	The delay time for which data in the internal circuit is reflected in the state of output elements of the Unit. It is described according to the ON/OFF sequence.		
Dimensions	The dimensions of the Unit. They are described as W x H x D. The unit is "mm".		
Isolation method	The isolation method of the output circuit and internal circuit of the Unit.		
Insulation resistance	The insulation resistance between the output circuit and internal circuit of the Unit.		
Dielectric strength	The dielectric strength between the output circuit and internal circuit of the Unit.		
Vibration resistance	The vibration-resistance specifications of the Unit. Some are different from the general specifications.		
Shock resistance	These are the shock-resistance specifications of the Unit. Some are different from the general specifications.		
I/O power supply method	The method for supplying I/O power to the Unit. The supply method is determined for each Unit. The power is supplied from the NX bus or the external source.		
Current capacity of I/O power supply terminal	The current capacity of the I/O power supply terminals (IOV/IOG) of the Unit. Do not exceed this value when supplying the I/O power to the connected external devices.		
NX Unit power consumption	The power consumption of the NX Unit power supply of the Unit. The power consumption of the Unit connected to each of the following Units is separately given. If some of the following Units can not be connected to the Unit, relevant information is omitted.  • CPU Unit		
	Communications Coupler Unit		
	Communication Control Unit		
Current consumption from I/O power supply	The current consumption from I/O power supply of the Unit. The load current of any external connection load and current consumption of any connected external devices are not included.		
Weight	The weight of the Unit.		
Circuit layout	The output circuit layout of the Unit.		
Installation orienta-	The installation orientation of the Unit. The installation orientation of the Unit connected to each of		
tion and restrictions	the following Units is separately given, along with details of the specifications restricted due to the installation orientation, if any. If some of the following Units can not be connected to the Unit, relevant information is omitted.		
	CPU Unit		
	Communications Coupler Unit		
	Communication Control Unit		
Terminal connection diagram	A diagram of the connection between the Unit and connected external devices. When an I/O Power Supply Connection Unit or a Shield Connection Unit is required to be connected to the connected external devices, the description for such is included.		
Disconnec- tion/Short-circuit detection	The function of the Unit to detect a disconnection/short-circuit.		
Protective function	The protective function that the Unit has.		
1 Totalive fulletion	The procedure function that the Onit has.		

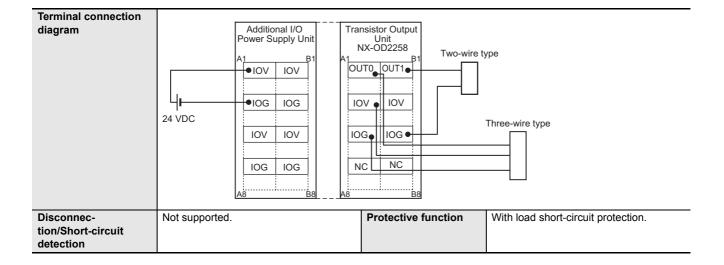
<sup>\*1.</sup> The layout of the indicators after the appearance change is shown for models released in or before September 2018. For details on the applicable models and the changes, refer to 3-2-3 Appearance Change of the Indicators on page 3-17.

# Transistor Output Units (Screwless Clamping Terminal Block, 12 mm Width)

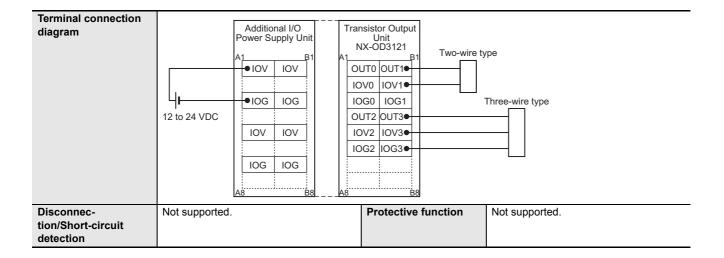
Unit name	Transistor Output Unit	Model	NX-OD2154
Number of points	2 points	External connection terminals	Screwless clamping terminal block (8 terminals)
I/O refreshing method	Output refreshing with specified time stamp		
Indicators	TS indicator, output indicator	Internal I/O common	NPN
	000454	Rated voltage	24 VDC
	OD2154	Operating load voltage range	15 to 28.8 VDC
	0 1	Maximum value of load current	0.5 A/point, 1 A/Unit
		Maximum inrush cur- rent	4.0 A/point, 10 ms max.
		Leakage current	0.1 mA max.
		Residual voltage	1.5 V max.
		ON/OFF response time	300 ns max./300 ns max.
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Digital isolator isolation
Insulation resistance	20 MΩ min. between isolated circuits (at	Dielectric strength	510 VAC between isolated circuits for 1
	100 VDC)		minute at a leakage current of 5 mA max.
I/O power supply method	Supply from the NX bus	Current capacity of I/O power supply terminal	IOV: 0.5 A/terminal max., IOG: 0.5 A/terminal max.
NX Unit power con-	Connected to a CPU Unit	Current consumption	30 mA max.
sumption	0.85 W max.	from I/O power supply	
	Connected to a Communications Cou-		
	pler Unit		
	0.45 W max.		
Weight	70 g max.		
Circuit layout	NX bus connector (left)	Duye circuit.	OUT0 to OUT1  Terminal block  I/O power supply + NX bus connector (right)
Installation orienta	'	* *	
Installation orienta- tion and restrictions	<ul> <li>Installation orientation:</li> <li>Connected to a CPU Unit Possible in upright installation.</li> <li>Connected to a Communications Couple Possible in 6 orientations.</li> </ul> Restrictions: No restrictions	er Unit	



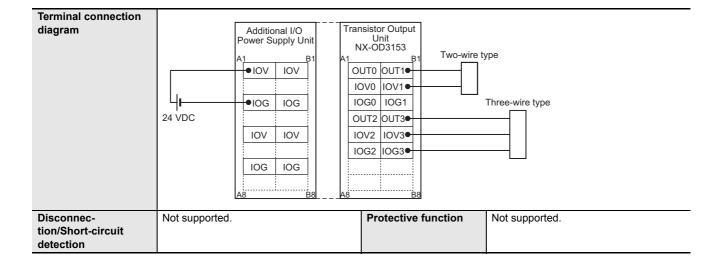
Unit name	Transistor Output Unit	Model	NX-OD2258
Number of points	2 points	External connection terminals	Screwless clamping terminal block (8 terminals)
I/O refreshing method	Output refreshing with specified time stamp		
Indicators	TS indicator, output indicator	Internal I/O common	PNP
	00000	Rated voltage	24 VDC
	OD2258 ■TS	Operating load voltage range	15 to 28.8 VDC
	0 1	Maximum value of load current	0.5 A/point, 1 A/Unit
		Maximum inrush cur- rent	4.0 A/point, 10 ms max.
		Leakage current	0.1 mA max.
		Residual voltage	1.5 V max.
		ON/OFF response time	300 ns max./300 ns max.
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Digital isolator isolation
Insulation resistance	20 M $\Omega$ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply method	Supply from the NX bus	Current capacity of I/O power supply terminal	IOV: 0.5 A/terminal max., IOG: 0.5 A/terminal max.
NX Unit power consumption	Connected to a CPU Unit 0.85 W max. Connected to a Communications Coupler Unit	Current consumption from I/O power supply	40 mA max.
	0.50 W max.		
Weight	70 g max.		
	NX bus connector (left)  NX bus connector (left)  I/O power supply -	push-pull output circuit.	OUT0 to OUT1  Terminal block  I/O power supply + NX bus connector (right)
Installation orienta-	Installation orientation:	• •	
tion and restrictions	<ul> <li>Connected to a CPU Unit         Possible in upright installation.     </li> <li>Connected to a Communications Coupl         Possible in 6 orientations.     </li> </ul>	er Unit	
	Restrictions: No restrictions		



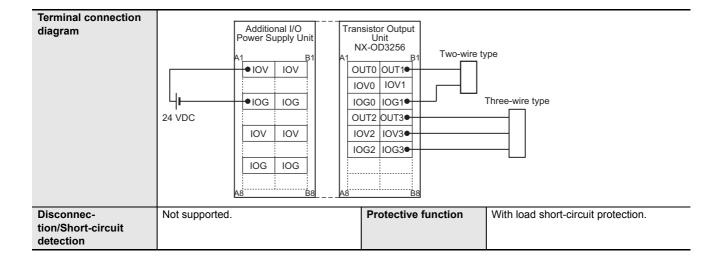
Unit name	Transistor Output Unit	Model	NX-OD3121
Number of points	4 points	External connection terminals	Screwless clamping terminal block (12 terminals)
I/O refreshing method	Switching Synchronous I/O refreshing and F		Timaloy
Indicators	TS indicator, output indicator	Internal I/O common	NPN
		Rated voltage	12 to 24 VDC
	OD3121	Operating load voltage	10.2 to 28.8 VDC
	■TS	range	
	0 1 2 3	Maximum value of load	0.5 A/point, 2 A/Unit
	2 3	current	
		Maximum inrush cur- rent	4.0 A/point, 10 ms max.
		Leakage current	0.1 mA max.
		Residual voltage	1.5 V max.
		ON/OFF response time	0.1 ms max./0.8 ms max.
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation
Insulation resistance	20 MΩ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply	Supply from the NX bus	Current capacity of I/O	IOV: 0.5 A/terminal max., IOG: 0.5 A/termi-
method		power supply terminal	nal max.
NX Unit power consumption	Connected to a CPU Unit or Commu- nication Control Unit	Current consumption from I/O power supply	10 mA max.
	0.90 W max.		
	Connected to a Communications Coupler Unit		
	0.55 W max.		
Weight	70 g max.		
Circuit layout	70 g max.		
	NX bus connector (left)  I/O power supply -		IOV0 to 3 OUT0 to OUT3  Terminal block  I/O power supply + NX bus connector (right)
Installation orienta-	Installation orientation:		
tion and restrictions	Connected to a CPU Unit or Communic	ation Control Unit	
	Possible in upright installation.		
	Connected to a Communications Coupl	er Unit	
	Possible in 6 orientations.	or offic	
	i ossible iii o ollettlatiolis.		
	Restrictions: No restrictions		



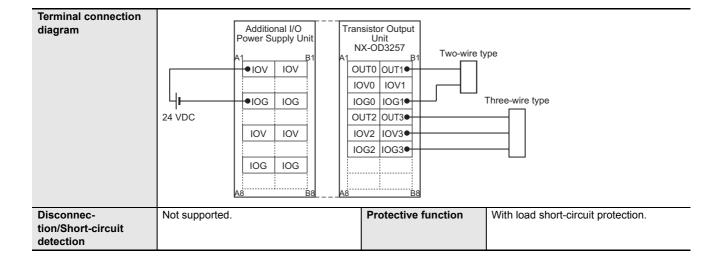
Unit name	Transistor Output Unit	Model	NX-OD3153
Number of points	4 points	External connection terminals	Screwless clamping terminal block (12 terminals)
I/O refreshing method	Switching Synchronous I/O refreshing and F	ree-Run refreshing	
Indicators	TS indicator, output indicator	Internal I/O common	NPN
	000450	Rated voltage	24 VDC
	OD3153	Operating load voltage range	15 to 28.8 VDC
	0 1 2 3	Maximum value of load current	0.5 A/point, 2 A/Unit
		Maximum inrush cur- rent	4.0 A/point, 10 ms max.
		Leakage current	0.1 mA max.
		Residual voltage	1.5 V max.
		ON/OFF response time	300 ns max./300 ns max.
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Digital isolator isolation
Insulation resistance	$20~\text{M}\Omega$ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply method	Supply from the NX bus	Current capacity of I/O power supply terminal	IOV: 0.5 A/terminal max., IOG: 0.5 A/terminal max.
NX Unit power consumption	Connected to a CPU Unit or Communication Control Unit 0.90 W max. Connected to a Communications Coupler Unit 0.50 W max.	Current consumption from I/O power supply	30 mA max.
Weight			
Circuit layout	70 g max.		
	NX bus connector (left)  I/O power supply - I/O power supply - This Unit uses a part of the supply - I/O power supply - I/O pow	oush-pull output circuit.	OUT0 to OUT3  Terminal block  I/O power supply + NX bus connector (right)
Installation orients		•	
Installation orienta- tion and restrictions	<ul> <li>Installation orientation:</li> <li>Connected to a CPU Unit or Communic Possible in upright installation.</li> <li>Connected to a Communications Couple Possible in 6 orientations.</li> </ul> Restrictions: No restrictions		



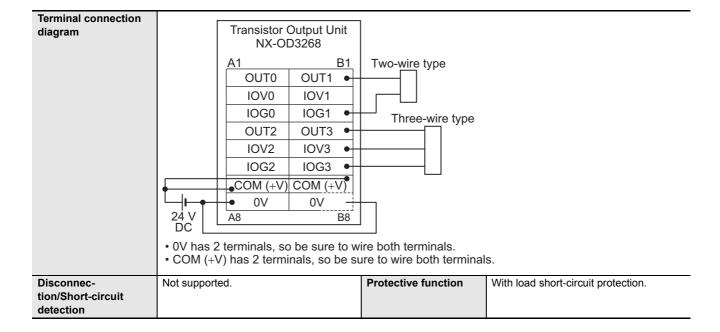
Number of points  I/O refreshing method Indicators	Transistor Output Unit 4 points	Model External connection	NX-OD3256  Screwless clamping terminal block (12 ter-
I/O refreshing method			
		terminals	minals)
Indicators	Switching Synchronous I/O refreshing and F	ree-Run refreshing	
เกนเปลเบาร	TS indicator, output indicator	Internal I/O common	PNP
	OD3256	Rated voltage	24 VDC
	₽TS	Operating load voltage range	15 to 28.8 VDC
	0 1 2 3	Maximum value of load current	0.5 A/point, 2 A/Unit
		Maximum inrush cur- rent	4.0 A/point, 10 ms max.
		Leakage current	0.1 mA max.
		Residual voltage	1.5 V max.
		ON/OFF response time	0.5 ms max./1.0 ms max.
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation
Insulation resistance	20 M $\Omega$ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply method	Supply from the NX bus	Current capacity of I/O power supply terminal	IOV: 0.5 A/terminal max., IOG: 0.5 A/terminal max.
NX Unit power con-	Connected to a CPU Unit or Commu-	Current consumption	20 mA max.
sumption	nication Control Unit	from I/O power supply	
	0.90 W max.		
	Connected to a Communications Cou-		
	pler Unit		
	0.55 W max.		
Weight	70 g max.		
Circuit layout	**		
	OUT0 to OUT3		OUT0 to OUT3
	NX bus connector (left) I/O power supply +		I/O power supply + NX bus connector (right)
Installation orienta- tion and restrictions	<ul> <li>Installation orientation:</li> <li>Connected to a CPU Unit or Communic Possible in upright installation.</li> <li>Connected to a Communications Couple Possible in 6 orientations.</li> </ul> Restrictions: No restrictions		



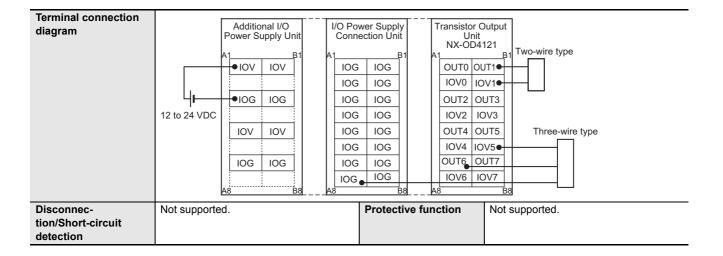
Unit name	Transistor Output Unit	Model	NX-OD3257
Number of points	4 points	External connection	Screwless clamping terminal block (12 ter-
Training or points	, perme	terminals	minals)
I/O refreshing method	Switching Synchronous I/O refreshing and F	ree-Run refreshing	
Indicators	TS indicator, output indicator	Internal I/O common	PNP
	000057	Rated voltage	24 VDC
	OD3257	Operating load voltage range	15 to 28.8 VDC
	0 1 2 3	Maximum value of load current	0.5 A/point, 2 A/Unit
		Maximum inrush cur-	4.0 A/point, 10 ms max.
		Leakage current	0.1 mA max.
		Residual voltage	1.5 V max.
		ON/OFF response time	300 ns max./300 ns max.
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Digital isolator isolation
Insulation resistance	20 MΩ min. between isolated circuits (at	Dielectric strength	510 VAC between isolated circuits for 1
	100 VDC)	<b>.</b>	minute at a leakage current of 5 mA max.
I/O power supply	Supply from the NX bus	Current capacity of I/O	IOV: 0.5 A/terminal max., IOG: 0.5 A/termi-
method		power supply terminal	nal max.
NX Unit power consumption	Connected to a CPU Unit or Communication Control Unit     0.85 W max.	Current consumption from I/O power supply	40 mA max.
	Connected to a Communications Coupler Unit		
	0.50 W max.		
Weight	70 g max.		<u> </u>
	NX bus connector (left)  I/O power supply - This Unit uses a reconstruction or country.	Drive circuit  Short-circuit  one circuit	IOV0 to 3  Terminal block  OUT0 to OUT3  I/O power supply + NX bus connector (right)
1 4 11 41			
Installation orienta- tion and restrictions	<ul> <li>Installation orientation:</li> <li>Connected to a CPU Unit or Communication:</li> <li>Possible in upright installation.</li> <li>Connected to a Communications Couple Possible in 6 orientations.</li> </ul> Restrictions: No restrictions		



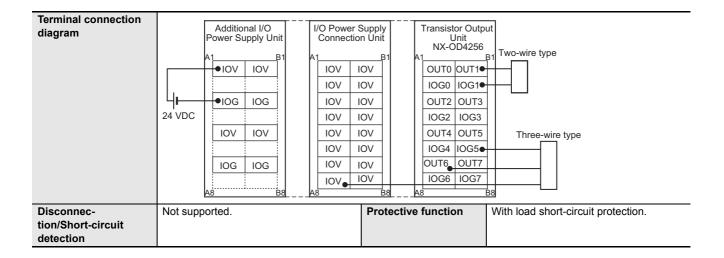
Unit name	Transistor Output Unit	Model	NX-OD3268
Number of points	4 points	External connection	Screwless clamping terminal block (16 ter-
		terminals	minals)
I/O refreshing method	Switching Synchronous I/O refreshing and Free-Run refreshing		
Indicators	TS indicator, output indicator	Internal I/O common	PNP
	OD3268	Rated voltage	24 VDC
	DTS	Operating load voltage range	15 to 28.8 VDC
	0 1	Maximum value of load	2 A/point, 8 A/Unit
	2 3	current	27 V POINT, 07 V OT III
		Maximum inrush cur-	4.0 A/point, 10 ms max.
	<u> </u>	rent	
		Leakage current	0.1 mA max.
		Residual voltage	1.5 V max.
Dimensions	42 (M) × 400 (L) × 74 (D)	ON/OFF response time	0.5 ms max./1.0 ms max.
Dimensions Insulation resistance	12 (W) x 100 (H) x 71 (D) 20 MΩ min. between isolated circuits (at	Isolation method	Photocoupler isolation 510 VAC between isolated circuits for 1
insulation resistance	20 MΩ min. between isolated circuits (at 100 VDC)	Dielectric strength	minute at a leakage current of 5 mA max.
I/O power supply	Supply from external source	Current capacity of I/O	IOV: 2 A/terminal max., IOG: 2 A/terminal
method		power supply terminal	max., COM (+V): 4 A/terminal max., 0V: 4
			A/terminal max.
NX Unit power con- sumption	Connected to a CPU Unit or Commu- nication Control Unit	Current consumption from I/O power supply	20 mA max.
Sumption	0.85 W max.	nom no power supply	
	Connected to a Communications Cou-		
	pler Unit		
	0.50 W max.		
Weight	70 g max.		
Circuit layout			
Installation orienta-	NX bus connector (left)  I/O power supply + I/O power supply –  Installation orientation:	Short-circuit	IOV 0 to IOV 3 COM (+V)  OUT 0 to OUT 3  IOG 0 to IOG 3  OV I/O power supply + I/O power supply - I/O power
tion and restrictions	<ul> <li>Connected to a CPU Unit or Communic Possible in upright installation.</li> <li>Connected to a Communications Coupl Possible in 6 orientations.</li> </ul> Restrictions: No restrictions		



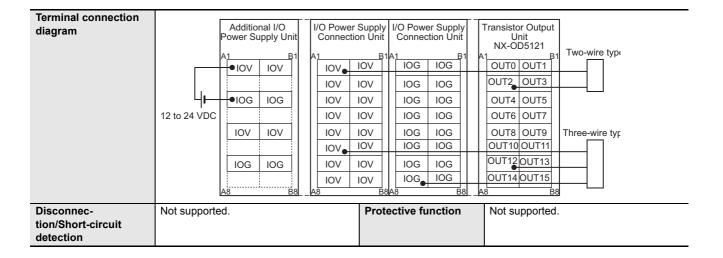
Unit name	Transistor Output Unit	Model	NX-OD4121
Number of points	8 points	External connection terminals	Screwless clamping terminal block (16 terminals)
I/O refreshing method	Switching Synchronous I/O refreshing and F	ree-Run refreshing	
Indicators	TS indicator, output indicator	Internal I/O common	NPN
	OD 4404	Rated voltage	12 to 24 VDC
	OD4121	Operating load voltage range	10.2 to 28.8 VDC
	0 1 2 3 4 5	Maximum value of load current	0.5 A/point, 4 A/Unit
	6 7	Maximum inrush cur- rent	4.0 A/point, 10 ms max.
		Leakage current	0.1 mA max.
		Residual voltage	1.5 V max.
		ON/OFF response time	0.1 ms max./0.8 ms max.
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation
Insulation resistance	20 M $\Omega$ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply method	Supply from the NX bus	Current capacity of I/O power supply terminal	IOV: 0.5 A/terminal max.
NX Unit power consumption	Connected to a CPU Unit or Communication Control Unit O.90 W max. Connected to a Communications Coupler Unit O.55 W max.	Current consumption from I/O power supply	10 mA max.
Weight	0.55 W max. 70 g max.		
Circuit layout	NX bus connector (left)  I/O power supply -		I/O power supply + NX bus connector (right)
Installation orienta- tion and restrictions	Installation orientation:  Connected to a CPU Unit or Communic Possible in upright installation.  Connected to a Communications Coupl Possible in 6 orientations.  Restrictions: No restrictions		



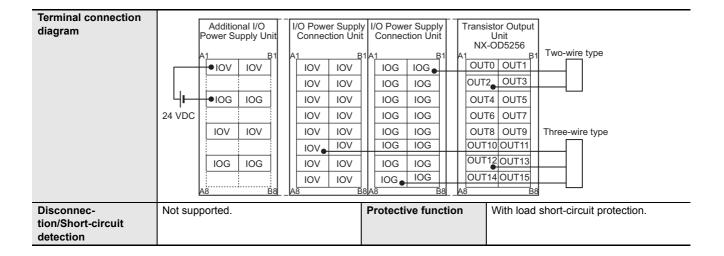
Half areas	Transistas Outsut Hait	Madal	LNV OD4050
Unit name	Transistor Output Unit	Model External connection	NX-OD4256  Scrowless clamping terminal block (16 ter
Number of points	8 points	terminals	Screwless clamping terminal block (16 terminals)
I/O refreshing method	Switching Synchronous I/O refreshing and Free-Run refreshing		
Indicators	TS indicator, output indicator	Internal I/O common	PNP
	OD4256	Rated voltage	24 VDC
	₽TS	Operating load voltage range	15 to 28.8 VDC
	0 1 2 3 4 5	Maximum value of load current	0.5 A/point, 4 A/Unit
	6 7	Maximum inrush cur- rent	4.0 A/point, 10 ms max.
		Leakage current	0.1 mA max.
		Residual voltage	1.5 V max.
		ON/OFF response time	0.5 ms max./1.0 ms max.
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation
Insulation resistance	20 MΩ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply method	Supply from the NX bus	Current capacity of I/O power supply terminal	IOG: 0.5 A/terminal max.
NX Unit power con-	Connected to a CPU Unit or Commu-	Current consumption	30 mA max.
sumption	nication Control Unit	from I/O power supply	
	1.00 W max.		
	Connected to a Communications Cou-		
	pler Unit		
	0.65 W max.		
Weight	70 g max.		
Circuit layout	NX bus connector (left)  I/O power supply +	Short-circuit protection	OUT0 to OUT7  Terminal block  IOG0 to 7  I/O power supply +  I/O power supply -  I/O power supply -  I/O power supply -
Installation orienta- tion and restrictions	Installation orientation: Connected to a CPU Unit or Communic Possible in upright installation. Connected to a Communications Coupl Possible in 6 orientations.  Restrictions: No restrictions		



Unit name	Transistor Output Unit	Model	NX-OD5121
Number of points	16 points	External connection	Screwless clamping terminal block (16 ter-
		terminals	minals)
I/O refreshing method	Switching Synchronous I/O refreshing and F		
Indicators	TS indicator, output indicator	Internal I/O common	NPN
	OD5121	Rated voltage	12 to 24 VDC
	■TS 0 1 2 3	Operating load voltage range	10.2 to 28.8 VDC
	4 5 6 7 8 9 10 11	Maximum value of load current	0.5 A/point, 4 A/Unit
	12 13 14 15	Maximum inrush cur- rent	4.0 A/point, 10 ms max.
		Leakage current	0.1 mA max.
		Residual voltage	1.5 V max.
		ON/OFF response time	0.1 ms max./0.8 ms max.
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation
Insulation resistance	20 MΩ min. between isolated circuits (at	Dielectric strength	510 VAC between isolated circuits for 1
	100 VDC)		minute at a leakage current of 5 mA max.
I/O power supply method	Supply from the NX bus	Current capacity of I/O power supply terminal	Without I/O power supply terminals
NX Unit power consumption	Connected to a CPU Unit or Communication Control Unit	Current consumption from I/O power supply	20 mA max.
	<ul><li>1.00 W max.</li><li>Connected to a Communications Coupler Unit</li><li>0.65 W max.</li></ul>		
Weight	70 g max.		
Circuit layout	NX bus connector (left)  I/O power supply + I/O power supply - I/O pow		
Installation orienta- tion and restrictions	<ul> <li>Installation orientation:</li> <li>Connected to a CPU Unit or Communic Possible in upright installation.</li> <li>Connected to a Communications Coupl Possible in 6 orientations.</li> </ul> Restrictions: No restrictions		

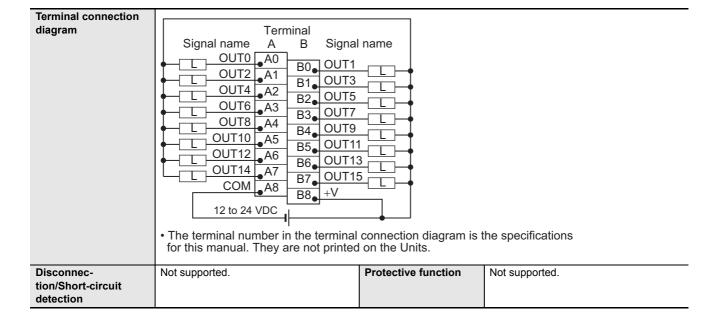


Unit name	Transistor Output Unit	Model	NX-OD5256	
Number of points	16 points	External connection	Screwless clamping terminal block (16 ter-	
	·	terminals	minals)	
I/O refreshing method	Switching Synchronous I/O refreshing and Free-Run refreshing			
Indicators	TS indicator, output indicator	Internal I/O common	PNP	
	OD5256	Rated voltage	24 VDC	
	DTS	Operating load voltage	15 to 28.8 VDC	
	0 1 2 3	range Maximum value of load	0.5 A/point, 4 A/Unit	
	4 5 6 7 8 9 10 11	current	0.5 Arpoint, 4 Aronit	
	12 13 14 15	Maximum inrush cur- rent	4.0 A/point, 10 ms max.	
		Leakage current	0.1 mA max.	
		Residual voltage	1.5 V max.	
		ON/OFF response time	0.5 ms max./1.0 ms max.	
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation	
Insulation resistance	$20~\text{M}\Omega$ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.	
I/O power supply method	Supply from the NX bus	Current capacity of I/O power supply terminal	Without I/O power supply terminals	
NX Unit power con-	Connected to a CPU Unit or Commu- nication Control Unit	Current consumption	40 mA max.	
sumption		from I/O power supply		
	1.10 W max.			
	Connected to a Communications Coupler Unit			
	0.70 W max.			
Weight	70 g max.			
Circuit layout	7 0 g			
	NX bus connector (left)  I/O power supply -	Short-diraul protection	OUT0 to OUT15 Terminal block  I/O power supply + NX bus connector (right)	
Installation orienta- tion and restrictions	Installation orientation: Connected to a CPU Unit or Communic Possible in upright installation. Connected to a Communications Coupl Possible in 6 orientations.  Restrictions: No restrictions			

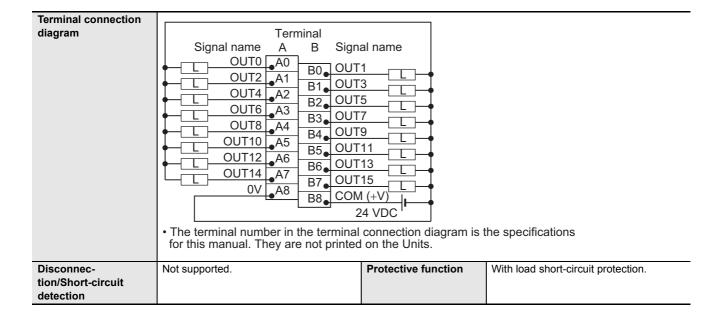


## Transistor Output Units (M3 Screw Terminal Block, 30 mm Width)

Unit name	Transistor Output Unit	Model	NX-OD5121-1	
Number of points	16 points	External connection terminals	M3 screw terminal block (18 terminals)	
I/O refreshing method	Switching Synchronous I/O refreshing and F	ree-Run refreshing		
Indicators	TS indicator, output indicator	Internal I/O common	NPN	
	005104 4	Rated voltage	12 to 24 VDC	
	OD5121-1	Operating load voltage range	10.2 to 28.8 VDC	
	0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15	Maximum value of load current	0.5 A/point, 5 A/Unit	
		Maximum inrush cur- rent	4.0 A/point, 10 ms max.	
		Leakage current	0.1 mA max.	
		Residual voltage	1.5 V max.	
		ON/OFF response time	0.1 ms max./0.8 ms max.	
Dimensions	30 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation	
Insulation resistance	$20~\text{M}\Omega$ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.	
I/O power supply method	Supply from the external source	Current capacity of I/O power supply terminal	Without I/O power supply terminals	
NX Unit power con-	Connected to a CPU Unit or Commu-	Current consumption	30 mA max.	
sumption	nication Control Unit	from I/O power supply		
	0.90 W max.			
	Connected to a Communications Cou-			
	pler Unit			
Maria Ind	0.60 W max.			
Weight	125 g max.			
Circuit layout	Internal circuits		O+V OUT0 to OUT15 Terminal block COM	
Installation orienta-	NX bus connector (left)  Installation orientation:		I/O power supply + l/O power supply - NX bus connector (right)	
tion and restrictions	<ul> <li>Connected to a CPU Unit or Communic Possible in upright installation.</li> <li>Connected to a Communications Coupl Possible in 6 orientations.</li> </ul> Restrictions: No restrictions			

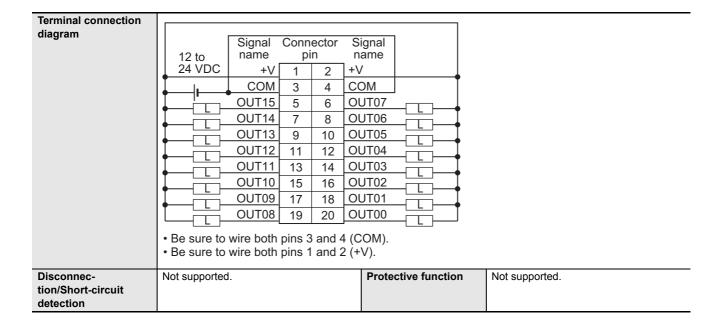


Unit name	Transistor Output Unit	Model	NX-OD5256-1
Number of points	16 points	External connection terminals	M3 screw terminal block (18 terminals)
I/O refreshing method	Switching Synchronous I/O refreshing and F	ree-Run refreshing	
Indicators	TS indicator, output indicator	Internal I/O common	PNP
	OD5256-1	Rated voltage	24 VDC
	DD3230-1 DTS 0 1 2 3 4 5 6 7	Operating load voltage range	20.4 to 28.8 VDC
	8 9 10 11 12 13 14 15	Maximum value of load current	0.5 A/point, 5 A/Unit
		Maximum inrush cur- rent	4.0 A/point, 10 ms max.
		Leakage current	0.1 mA max.
		Residual voltage	1.5 V max.
		ON/OFF response time	0.5 ms max./1.0 ms max.
Dimensions	30 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation
Insulation resistance	20 M $\Omega$ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply method	Supply from external source	Current capacity of I/O power supply terminal	Without I/O power supply terminals
NX Unit power consumption	Connected to a CPU Unit or Communication Control Unit	Current consumption from I/O power supply	30 mA max.
	0.95 W max.		
	Connected to a Communications Coupler Unit		
	0.65 W max.		
Weight	125 g max.		
Circuit layout	// (t)	Short-circuit	OUT0 to OUT15  OV  I/O power supply + I/O power supply + I/O power supply + I/O power (right)
Installation orienta- tion and restrictions	<ul> <li>(left) supply - suppl</li></ul>		

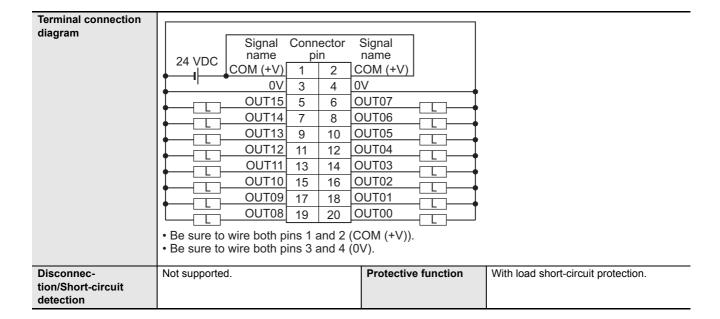


## Transistor Output Units (MIL Connector, 30 mm Width)

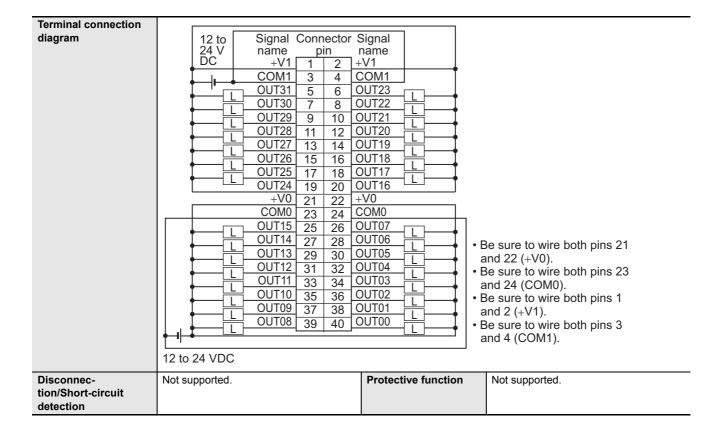
Unit name	Transistor Output Unit	Model	NX-OD5121-5	
Number of points	16 points	External connection terminals	MIL connector (20 terminals)	
I/O refreshing method	Switching Synchronous I/O refreshing and F	ree-Run refreshing		
Indicators	TS indicator, output indicator	Internal I/O common	NPN	
	ODE121 E	Rated voltage	12 to 24 VDC	
	OD5121-5	Operating load voltage range	10.2 to 28.8 VDC	
	0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15	Maximum value of load current	0.5 A/point, 2 A/Unit	
		Maximum inrush cur- rent	4.0 A/point, 10 ms max.	
		Leakage current	0.1 mA max.	
		Residual voltage	1.5 V max.	
		ON/OFF response time	0.1 ms max./0.8 ms max.	
Dimensions	30 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation	
Insulation resistance	$20~\text{M}\Omega$ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.	
I/O power supply method	Supply from external source	Current capacity of I/O power supply terminal	Without I/O power supply terminals	
NX Unit power con-	Connected to a CPU Unit or Commu-	Current consumption	30 mA max.	
sumption	nication Control Unit	from I/O power supply		
	0.95 W max.			
	Connected to a Communications Cou-			
	pler Unit			
Wateht	0.60 W max.			
Weight Circuit layout	80 g max.			
	NX bus I/O power supply +		+V +V OUT0 to OUT15  Connector  COM COM I/O power supply + Supply + Connector	
Installation orienta-	connector I/O power supply –		\[ \lambda \ \la	
tion and restrictions	<ul> <li>Installation orientation:</li> <li>Connected to a CPU Unit or Communication Control Unit         Possible in upright installation.     </li> <li>Connected to a Communications Coupler Unit         Possible in 6 orientations.     </li> </ul> Restrictions: No restrictions			
	<u> </u>			



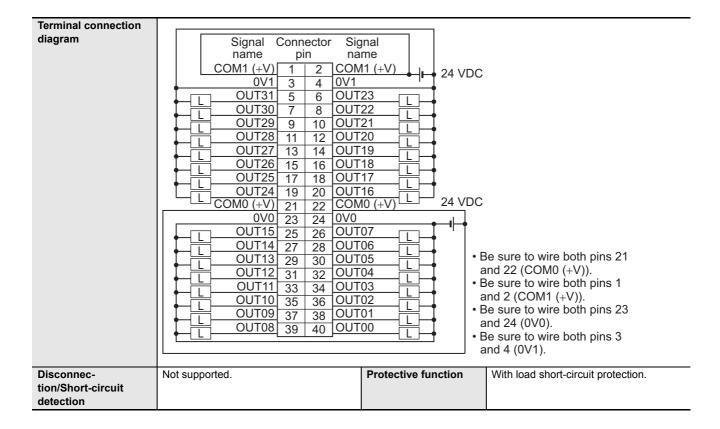
Unit name	Transistor Output Unit	Model	NX-OD5256-5
Number of points	16 points	External connection terminals	MIL connector (20 terminals)
I/O refreshing method	Switching Synchronous I/O refreshing and Free-Run refreshing		
Indicators	TS indicator, output indicator	Internal I/O common	PNP
		Rated voltage	24 VDC
	<b>OD5256-5</b>	Operating load voltage	20.4 to 28.8 VDC
	0 1 2 3 4 5 6 7	range	
	8 9 10 11 12 13 14 15	Maximum value of load current	0.5 A/point, 2 A/Unit
		Maximum inrush cur- rent	4.0 A/point, 10 ms max.
		Leakage current	0.1 mA max.
		Residual voltage	1.5 V max.
		ON/OFF response time	0.5 ms max./1.0 ms max.
Dimensions	30 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation
Insulation resistance	$20~\text{M}\Omega$ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply method	Supplied from external source.	Current capacity of I/O power supply terminal	Without I/O power supply terminals
NX Unit power consumption	Connected to a CPU Unit or Commu- nication Control Unit	Current consumption from I/O power supply	40 mA max.
Campaon	1.00 W max.	nom no ponor cuppry	
	Connected to a Communications Cou-		
	pler Unit		
	0.70 W max.		
Weight	85 g max.		
Circuit layout	NX bus connector (left)  I/O power supply + I/O power supply –	Short-circuit	COM (+V) COM (+V)  COnnector  OUT0 to OUT15  OV  I/O power supply + I/O power supply - VO power supply
Installation orienta- tion and restrictions	Installation orientation:  Connected to a CPU Unit or Communication Control Unit Possible in upright installation.  Connected to a Communications Coupler Unit Possible in 6 orientations.  Restrictions: No restrictions		



Unit name	Transistor Output Unit	Model NX-OD6121-5	
Number of points	32 points	External connection terminals	MIL connector (40 terminals)
I/O refreshing method	Switching Synchronous I/O refreshing and F	ree-Run refreshing	
Indicators	TS indicator, output indicator	Internal I/O common	NPN
	OD6121-5	Rated voltage	12 to 24 VDC
	DTS	Operating load voltage range	10.2 to 28.8 VDC
	0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23	Maximum value of load current	0.5 A/point, 2 A/common, 4 A/Unit
	24 25 26 27 28 29 30 31	Maximum inrush cur- rent	4.0 A/point, 10 ms max.
		Leakage current	0.1 mA max.
		Residual voltage	1.5 V max.
		ON/OFF response time	0.1 ms max./0.8 ms max.
Dimensions	30 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation
Insulation resistance	20 MΩ min. between isolated circuits (at	Dielectric strength	510 VAC between isolated circuits for 1
	100 VDC)		minute at a leakage current of 5 mA max.
I/O power supply method	Supply from external source	Current capacity of I/O power supply terminal	Without I/O power supply terminals
NX Unit power consumption	Connected to a CPU Unit or Communication Control Unit     1.00 W max.     Connected to a Communications Coupler Unit     0.80 W max.		50 mA max.
Weight	90 g max.		
Circuit layout	90 g max.		
	NX bus connector (left)  I/O power supply + I/O power supply - I/O pow	COI COI COI COI I/O Sup I/O	M0 M0 M0 Connector T16 DUT31
Installation orienta-	Installation orientation:		
tion and restrictions	<ul> <li>Connected to a CPU Unit or Communic Possible in upright installation.</li> <li>Connected to a Communications Coupl Possible in 6 orientations.</li> </ul> Restrictions: No restrictions		
	INCOLLICIONO. INO ICOLLICIONO		

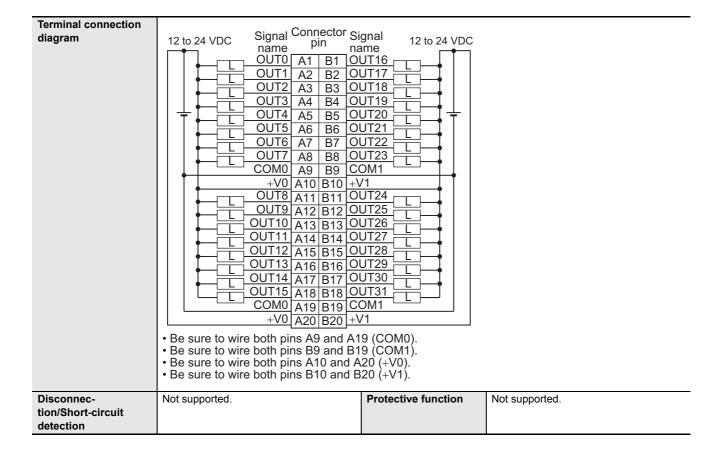


Unit name	Transistor Output Unit	Model	NX-OD6256-5
Number of points	32 points	External connection terminals	MIL connector (40 terminals)
I/O refreshing method	Switching Synchronous I/O refreshing and F	ree-Run refreshing	
Indicators	TS indicator, output indicator	Internal I/O common	PNP
	OD6256-5	Rated voltage	24 VDC
	UD0290-9 ■TS	Operating load voltage	20.4 to 28.8 VDC
	0 1 2 3 4 5 6 7	range	
	8 9 10 11 12 13 14 15	Maximum value of load	0.5 A/point, 2 A/common, 4 A/Unit
	16 17 18 19 20 21 22 23	current Maximum inrush cur-	4.0.0 // a sint 40 mag mag)
	24 25 26 27 28 29 30 31	rent	4.0 A/point, 10 ms max.
		Leakage current	0.1 mA max.
		Residual voltage	1.5 V max.
		ON/OFF response time	0.5 ms max./1.0 ms max.
Dimensions	30 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation
Insulation resistance	$20~\text{M}\Omega$ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.
I/O power supply	Supply from external source	Current capacity of I/O	Without I/O power supply terminals
method		power supply terminal	
NX Unit power consumption	Connected to a CPU Unit or Commu- nication Control Unit	Current consumption from I/O power supply	80 mA max.
	1.30 W max.		
	Connected to a Communications Cou-		
	pler Unit		
	1.00 W max.		
Weight Circuit layout	95 g max.		
	NX bus connector (left)  NX bus connector supply + I/O power supply -	Short-circuit protection	COM0 (+V) COM0 (+V)  OUT0 to OUT15  0V0  0V0  COM1 (+V)  COM1 (+V)  OUT16 to OUT31  0V1  1/O power supply + 1/O power supply - VX bus connector (right)
Installation orienta-	Installation orientation:		
tion and restrictions	Connected to a CPU Unit or Communic	ation Control Unit	
	Possible in upright installation.	adon Control Crift	
	Connected to a Communications Couple	er l Init	
	Possible in 6 orientations.	o. om	
	Restrictions: No restrictions		



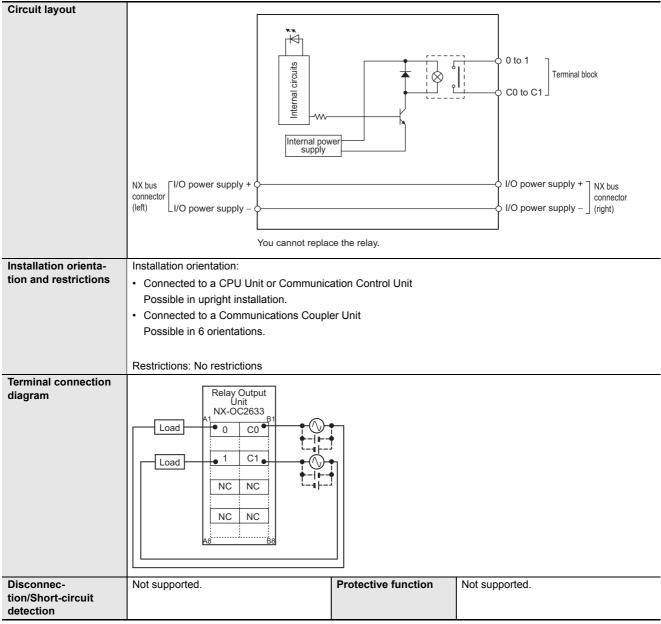
## Transistor Output Units (Fujitsu Connector, 30 mm Width)

Number of points  I/O refreshing method Indicators	32 points  Switching Synchronous I/O refreshing and F TS indicator, output indicator	External connection terminals	Fujitsu connector (40 terminals)	
		ree-Run refreshina		
Indicators	TS indicator, output indicator			
			NPN	
	OD6121-6	Rated voltage	12 to 24 VDC	
	DTS 0 1 2 3 4 5 6 7	Operating load voltage range	10.2 to 28.8 VDC	
	8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23	Maximum value of load current	0.5 A/point, 2 A/common, 4 A/Unit	
	24 25 26 27 28 29 30 31	Maximum inrush cur- rent	4.0 A/point, 10 ms max.	
		Leakage current	0.1 mA max.	
		Residual voltage	1.5 V max.	
		ON/OFF response time	0.1 ms max./0.8 ms max.	
Dimensions	30 (W) x 100 (H) x 71 (D)	Isolation method	Photocoupler isolation	
Insulation resistance	20 MΩ min. between isolated circuits (at 100 VDC)	Dielectric strength	510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.	
I/O power supply method	Supply from external source	Current capacity of I/O power supply terminal	Without I/O power supply terminals	
NX Unit power con-	Connected to a CPU Unit or Commu-	Current consumption	50 mA max.	
sumption	nication Control Unit	from I/O power supply		
	1.10 W max.			
	Connected to a Communications Cou-			
	pler Unit 0.80 W max.			
Weight	90 g max.			
Circuit layout	90 g max.			
	NX bus connector (left)  I/O power supply + I/O power supply -	COI COI +V1 +V1 OU to C	M0 M0 M0 Connector T16 DUT31	
In adultable to de		·		
Installation orienta- tion and restrictions	<ul> <li>Installation orientation:</li> <li>Connected to a CPU Unit or Communication.</li> <li>Connected to a Communications Couple Possible in 6 orientations.</li> </ul> Restrictions: No restrictions			



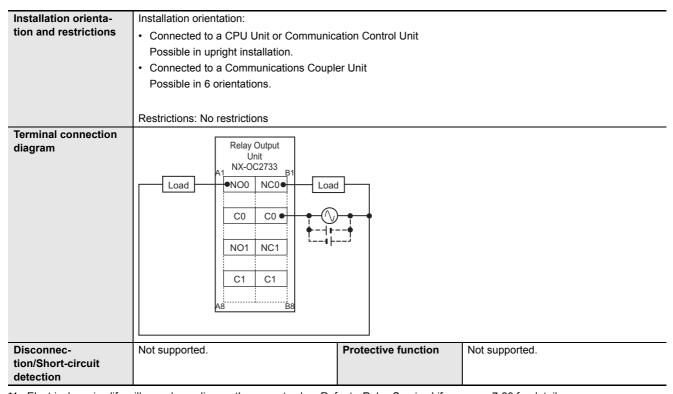
# Relay Output Units (Screwless Clamping Terminal Block, 12 mm Width)

Unit name	Relay Output Unit	Model	NX-OC2633
Number of points	2 points, independent contacts	ts, independent contacts  External connection terminals	
I/O refreshing method	Free-Run refreshing		
Indicators	TS indicator, output indicator	Relay type	N.O. contact
	OC2633	Maximum switching capacity	250 VAC/2 A (cosΦ = 1), 250 VAC/2 A (cosΦ = 0.4), 24 VDC/2 A, 4 A/Unit
	0 1	Minimum switching capacity	5 VDC, 1 mA
Relay service life	Electrical: 100,000 operations *1 Mechanical: 20,000,000 operations	ON/OFF response time	15 ms max./15 ms max.
Dimensions	12 (W) x 100 (H) x 71 (D)	Isolation method	Relay isolation
Insulation resistance	Between A1/B1 terminals and A3/B3 terminals: 20 MΩ min. (at 500 VDC)  Between the external terminals and the	Dielectric strength	Between A1/B1 terminals and A3/B3 terminals: 2300 VAC for 1 min at a leakage current of 5 mA max.
	functional ground terminal: 20 $M\Omega$ min. (at 500 VDC)		Between the external terminals and the functional ground terminal: 2300 VAC for 1
	Between the external terminals and internal circuits: 20 M $\Omega$ min. (at 500 VDC)		min at a leakage current of 5 mA max.  Between the external terminals and internal
	Between the internal circuit and the functional ground terminal: $20 \text{ M}\Omega$ min. (at 100		circuits: 2300 VAC for 1 min at a leakage current of 5 mA max.
	VDC)		Between the internal circuit and the functional ground terminal: 510 VAC for 1 min at a leakage current of 5 mA max.
Vibration resistance	Conforms to IEC 60068-2-6. 5 to 8.4 Hz with amplitude of 3.5 mm, 8.4	Shock resistance	100 m/s <sup>2</sup> , 3 times each in X, Y, and Z directions
	to 150 Hz, acceleration of 9.8 m/s <sup>2</sup> 100 min each in X, Y, and Z directions (10 sweeps of 10 min each = 100 min total)		
I/O power supply method	Supplied from external source.	Current capacity of I/O power supply terminal	Without I/O power supply terminals
NX Unit power consumption	Connected to a CPU Unit or Communication Control Unit     1.20 W max.     Connected to a Communications Cou-	Current consumption from I/O power supply	No consumption
	pler Unit 0.80 W max.		
Weight			
vveignt	65 g max.		



<sup>\*1.</sup> Electrical service life will vary depending on the current value. Refer to *Precautions when Using the Relay Output Units* on page 7-20 for details.

Unit name	Relay Output Unit	Model	NX-OC2733	
Number of points	2 points, independent contacts	External connection	Screwless clamping terminal block (8 ter-	
Training or points	_ points, maspendent contacts	terminals	minals)	
I/O refreshing method	Free-Run refreshing			
Indicators	TS indicator, output indicator	Relay type	N.O. + N.C. contact	
	002722	Maximum switching	250 VAC/2 A (cosΦ = 1),	
	OC2733	capacity	250 VAC/2 A ( $cosΦ = 0.4$ ),	
	0 1		24 VDC/2 A,	
			4 A/Unit	
		Minimum switching	5 VDC, 10 mA	
		capacity		
Relay service life	Electrical: 100,000 operations*1	ON/OFF response time	15 ms max./15 ms max.	
	Mechanical: 20,000,000 operations			
Dimensions	12 (W) ×100 (H) ×71 (D)	Isolation method	Relay isolation	
Insulation resistance	Between A1/3, B1/3 terminals and A5/7,	Dielectric strength	Between A1/3, B1/3 terminals and A5/7,	
	B5/7 terminals: 20 MΩ min. (at 500 VDC)		B5/7 terminals: 2300 VAC for 1 min at a	
	Between the external terminals and func-		leakage current of 5 mA max.	
	tional ground terminal: 20 MΩ min. (at 500 VDC)		Between the external terminals and the functional ground terminal: 2300 VAC for	
	Between the external terminals and inter-		1 min at a leakage current of 5 mA max.	
	nal circuits: 20 MΩ min. (at 500 VDC)		Between the external terminals and inter-	
	Between the internal circuit and the func-		nal circuits: 2300 VAC for 1 min at a leak-	
	tional ground terminal: 20 MΩ min. (at		age current of 5 mA max.	
	100 VDC)		Between the internal circuit and the functional ground terminal: 510 VAC for 1 min	
			at a leakage current of 5 mA max.	
Vibration resistance	10 to 55 Hz with amplitude of 0.5 mm	Shock resistance	50 m/s <sup>2</sup> , 3 times each in X, Y, and Z directions	
I/O power supply	Supply from external source	Current capacity of I/O	Without I/O power supply terminals	
method		power supply terminal		
NX Unit power con-	Connected to a CPU Unit or Commu- nication Control Unit	Current consumption	No consumption	
sumption	1.30 W max.	from I/O power supply		
	Connected to a Communications Cou-			
	pler Unit			
	0.95 W max.			
Weight	70 g max.			
Circuit layout				
	××			
	cnits		NO0 to NO1	
	NO0 to NO1 Terminal block  NC0 to NC1  Terminal block			
	Internal po supply	wer		
	[-266.9			
	NX bus		I/O power supply + NX bus	
	connector (left) I/O power supply –		connector (right)	
	L I/O power supply – Y	LI/O power supply −  I/O		
	NO0 and NO1	are normally open contacts, a	nd NC0 and NC1 are normally close contacts.	
	You cannot rep		,	



<sup>\*1.</sup> Electrical service life will vary depending on the current value. Refer to Relay Service Life on page 7-20 for details.

## Relay Output Units (Screwless Clamping Terminal Block, 24 mm Width)

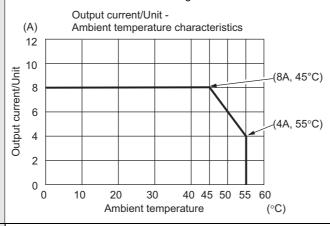
Unit name	Relay Output Unit	Model	NX-OC4633
Number of points	8 points, independent contacts	External connection	Screwless clamping terminal block (8 ter-
•		terminals	minals × 2)
I/O refreshing method	Free-Run refreshing		
Indicators	TS indicator, output indicator	Relay type	N.O. contact
	OC4633	Maximum switching	$250 \text{ VAC/2 A } (\cos \Phi = 1), 250 \text{ VAC/2 A}$ $(\cos \Phi = 0.4), 24 \text{ VDC/2 A},$
	<b>D</b> TS	capacity	8 A/Unit
	0 1	Minimum switching	5 VDC, 1 mA
	2 3 4 5	capacity	0 100, 11111
	6 7		
Relay service life	Electrical: 100,000 operations *1	ON/OFF response time	15 ms max./15 ms max.
•	Mechanical: 20,000,000 operations	·	
Dimensions	24 (W) x 100 (H) x 71 (D)	Isolation method	Relay isolation
Insulation resistance	Between output bits: 20 MΩ min. (at 500	Dielectric strength	Between output bits: 2300 VAC for 1 min at
	VDC)		a leakage current of 5 mA max.
	Between the external terminals and the		Between the external terminals and the
	functional ground terminal: 20 M $\Omega$ min. (at 500 VDC)		functional ground terminal: 2300 VAC for 1 min at a leakage current of 5 mA max.
	Between the external terminals and internal		Between the external terminals and internal
	circuits: 20 MΩ min. (at 500 VDC)		circuits: 2300 VAC for 1 min at a leakage
	Between the internal circuit and the func-		current of 5 mA max.
	tional ground terminal: 20 M $\Omega$ min. (at 100 VDC)		Between the internal circuit and the functional ground terminal: 510 VAC for 1 min
	(20)		at a leakage current of 5 mA max.
Vibration resistance	Conforms to IEC 60068-2-6.	Shock resistance	100 m/s <sup>2</sup> , 3 times each in X, Y, and Z direc-
	5 to 8.4 Hz with amplitude of 3.5 mm, 8.4		tions
	to 150 Hz, acceleration of 9.8 m/s <sup>2</sup> 100 min each in X, Y, and Z directions		
	(10 sweeps of 10 min each = 100 min		
	total)		
I/O power supply method	Supplied from external source.	Current capacity of I/O power supply terminal	Without I/O power supply terminals
NX Unit power con-	Connected to a CPU Unit or Commu-	Current consumption	No consumption
sumption	nication Control Unit	from I/O power supply	The concampaon
	2.00 W max.		
	Connected to a Communications Cou-		
	pler Unit 1.65 W max.		
Weight	140 g max.		
Circuit layout			
<b>,</b>	**		
	rits		0 to 7
	Internal circuits		Terminal block
	terna	]	
	_ <u> </u>	<u> </u>	
	Internal pow supply	ver	
		<b>_</b>	
	NX bus		I/O power supply + NX bus
	connector (left) I/O power supply –		connector √ I/O power supply – (right)
	You cannot repla	ace the relay.	

## Installation orientation and restrictions

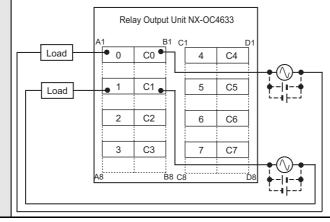
Installation orientation:

- Connected to a CPU Unit or Communication Control Unit Possible in upright installation.
- Connected to a Communications Coupler Unit Possible in 6 orientations.

Restrictions: As shown in the following.



## Terminal connection diagram



<sup>\*1.</sup> Electrical service life will vary depending on the current value. Refer to *Precautions when Using the Relay Output Units* on page 7-20 for details.

## A-1-4 Digital Mixed I/O Units

## Description of Items on the Data Sheet of the DC Input/Transistor Output Units

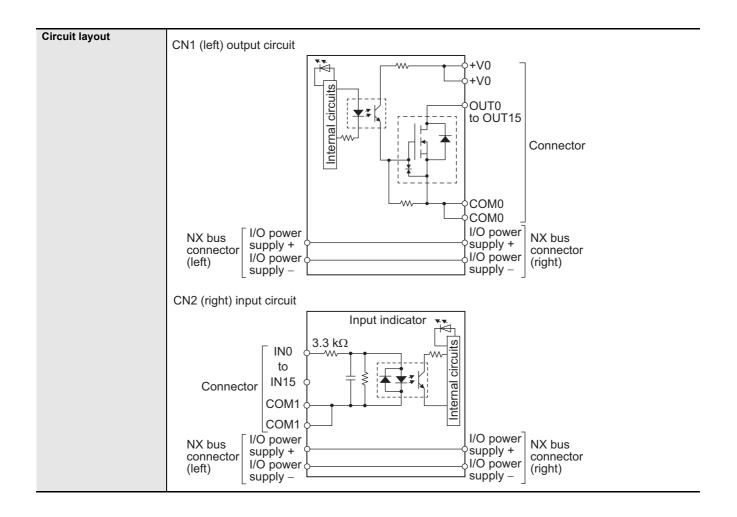
	Item	Description
Unit name		The name of the Unit.
Model		The model of the Unit.
Number of po	oints	The number of input and output points provided by the Unit.
	nection terminals	The type of terminal block and connector that is used for connecting the Unit.
I/O refreshing		The I/O refreshing methods that are used by the Unit. Free-Run refreshing and syn-
	<b>9</b>	chronous I/O refreshing are available.
Output sec-	Internal I/O common	The polarity of the output devices that are connected to the Unit. NPN connection and PNP connection are available.
tion (CN1)	Rated voltage	The rated output voltage of the Unit.
		The output load voltage of the Unit.
	Operating load voltage range	The output load voltage range of the offit.
	Maximum value of load current	The maximum output load current of the Unit. The specifications for each output point and for the Unit are described.
	Maximum inrush cur- rent	The maximum allowable inrush current of the Unit. Any inrush current from an external connection load must be kept to or below this value.
	Leakage current	The leakage current when the output of the Unit is OFF.
	Residual voltage	The residual voltage when the output of the Unit is ON.
	ON/OFF response time	The delay time for which data in the internal circuit is reflected in the state of output elements of the Unit. It is described according to the ON/OFF sequence.
Input sec- tion (CN2)	Internal I/O common	The polarity of the input devices that are connected to the Unit. NPN connection and PNP connection are available.
` '	Rated input voltage	The rated input voltage and range of the Unit.
	Input current	The input current at the rated voltage of the Unit.
	ON voltage/ON current	The input voltage in which the Unit input turns ON, and corresponding input current.
	OFF voltage/OFF current	The input voltage in which the Unit input turns OFF, and corresponding input current.
	ON/OFF response time	The delay time for which the status change of the input terminals reaches the internal circuit of the Unit. The input filter time below is not included. It is described according to the ON/OFF sequence.
	Input filter time	The filter time when the status of the internal circuit is read as the data to the internal of the Unit. It is same for both ON/OFF. The filter time to be set by the Support Software is described.
Indicators		The type of indicators on the Unit and the layout of those indicators.*1
Dimensions		The dimensions of the Unit. They are described as W x H x D. The unit is "mm".
Isolation met	thod	The isolation method of the I/O circuits and internal circuit of the Unit.
Insulation re	sistance	The insulation resistance between the I/O circuits and internal circuit of the Unit.
Dielectric str	ength	The dielectric strength between the I/O circuits and internal circuit of the Unit.
I/O power su	pply method	The method for supplying I/O power to the Unit. The supply method is determined for each Unit. The power is supplied from the NX bus or the external source.
Current capa terminal	city of I/O power supply	The current capacity of the I/O power supply terminals (IOV/IOG) of the Unit. Do not exceed this value when supplying the I/O power to the connected external devices.
NX Unit power consumption		The power consumption of the NX Unit power supply of the Unit.
		The power consumption of the Unit connected to each of the following Units is separately given. If some of the following Units can not be connected to the Unit, relevant information is omitted.
		CPU Unit
		Communications Coupler Unit
		Communication Control Unit
Current consumption from I/O power supply		The current consumption from I/O power supply of the Unit. The load current of any external connection load, input current, and current consumption of any connected external devices are not included.

Item	Description				
Weight	The weight of the Unit.				
Circuit layout	The circuit layout of the I/O circuits of the Unit.				
Installation orientation and restrictions	The installation orientation of the Unit. The installation orientation of the Unit connected to each of the following Units is separately given, along with details of the specifications restricted due to the installation orientation, if any. If some of the following Units can not be connected to the Unit, relevant information is omitted.				
	CPU Unit Communications Coupler Unit Communication Control Unit				
Terminal connection diagram	A diagram of the connection between the Unit and connected external devices.  When an I/O Power Supply Connection Unit or a Shield Connection Unit is required to be connected to the connected external devices, the description for such is included.				
Disconnection/Short-circuit detection	The function of the Unit to detect a disconnection/short-circuit.				
Protective function	The protective function that the Unit has.				

<sup>\*1.</sup> The layout of the indicators after the appearance change is shown for models released in or before September 2018. For details on the applicable models and the changes, refer to 3-2-3 Appearance Change of the Indicators on page 3-17.

## DC Input/Transistor Output Units (MIL Connector, 30 mm Width)

Unit name		DC Input/Transistor Output Unit	Model		NX-MD6121-5	
Number of points		16 inputs/16 outputs	External connection terminals		2 MIL connectors (20 terminals)	
I/O refre	shing method	Switching Synchronous I/O refreshing and Free-Run refreshing				
Out- put	Internal I/O common	NPN	Input sec-	Internal I/O common	For both NPN/PNP	
sec- tion (CN1)	Rated voltage	12 to 24 VDC	tion (CN2)	Rated input voltage	24 VDC (15 to 28.8 VDC)	
	Operating load voltage range	10.2 to 28.8 VDC		Input current	7 mA typical (at 24 VDC)	
	Maximum value of load current	0.5 A/point, 2 A/Unit		ON volt- age/ON cur- rent	15 VDC min./3 mA min. (between COM and each signal)	
	Maximum inrush current	4.0 A/point, 10 ms max.		OFF volt- age/OFF cur- rent	5 VDC max./1 mA max. (between COM and each signal)	
	Leakage cur- rent	0.1 mA max.		ON/OFF response time	20 μs max./400 μs max.	
	Residual volt- age	1.5 V max.		Input filter time	No filter, 0.25 ms, 0.5 ms, 1 ms (default), 2 ms, 4 ms, 8 ms, 16 ms, 32 ms, 64 ms,	
	ON/OFF response time	0.1 ms max./0.8 ms max.			128 ms, 256 ms	
Indicato	ors	TS indicator, I/O indicators	Dimensions		30 (W) x 100 (H) x 71 (D)	
		MD6121-5  CN  1 0 1 2 3 4 5 6 7  1 8 9 10 11 12 13 14 15  2 8 9 10 11 12 13 14 15	Isolation method		Photocoupler isolation	
			Insulation resistance		20 M $\Omega$ min. between isolated circuits (at 100 VDC)	
			Dielectric strength		510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.	
			I/O power supply method		Supply from external source	
			Current capacity of I/O power supply terminal		Without I/O power supply terminals	
			NX Unit power consumption		Connected to a CPU Unit or Commu- nication Control Unit	
					<ul><li>1.00 W max.</li><li>Connected to a Communications Coupler Unit</li><li>0.70 W max.</li></ul>	
			Current consumption from I/O power supply		30 mA max.	
			Weight		105 g max.	



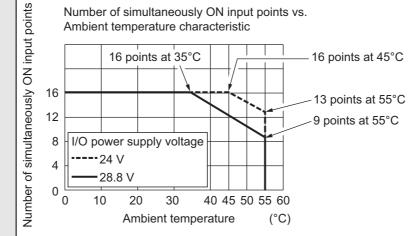
## Installation orientation and restrictions

Installation orientation:

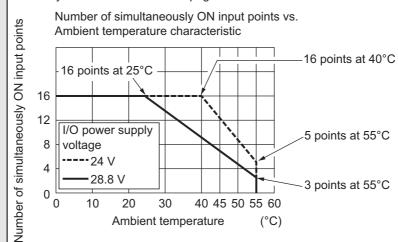
- Connected to a CPU Unit or Communication Control Unit Possible in upright installation.
- Connected to a Communications Coupler Unit Possible in 6 orientations.

Restrictions: As shown in the following.

For upright installation



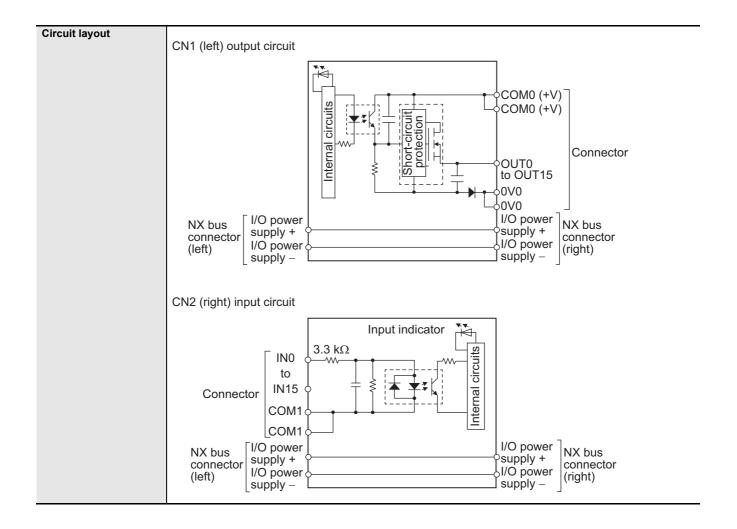
· For any installation other than upright



#### **Terminal connection** CN1 (left) output terminal diagram Signal Connector Signal name name pin OUT0 20 19 OUT8 OUT1 18 17 OUT9 OUT2 16 15 OUT10 OUT3 14 13 OUT11 OUT4 12 11 OUT12 10 9 OUT5 OUT13 OUT6 8 7 <u>OUT14</u> OUT7 6 5 OUT15 COM0 4 3 COM0 2 +V0 1 +V0 12 to 24 VDC • Be sure to wire both pins 3 and 4 (COM0) of CN1. • Be sure to wire both pins 1 and 2 (+V0) of CN1. CN2 (right) input terminal Signal Connector Signal **24 VDC** name pin name 1 2 NC NC COM1 3 4 COM1 **IN15** 5 6 **IN07** IN14 7 8 IN<sub>0</sub>6 IN13 9 | 10 IN05 IN12 11 | 12 **IN04** 13 14 **IN03** IN11 IN10 15 16 IN02 IN09 17 18 IN01 IN08 19 20 IN00 60 • The polarity of the input power supply of CN2 can be connected in either direction. • Be sure to wire both pins 3 and 4 (COM1) of CN2, and set the same polarity for both pins. Disconnec-Not supported. **Protective function** Not supported. tion/Short-circuit

detection

Unit name		DC Input/Transistor Output Unit	Model		NX-MD6256-5	
Number of points		16 inputs/16 outputs	External connection terminals		2 MIL connectors (20 terminals)	
I/O refre	shing method	Switching Synchronous I/O refreshing and Free-Run refreshing				
Out- put sec- tion (CN1)	Internal I/O common	PNP	Input sec-	Internal I/O common	For both NPN/PNP	
	Rated voltage	24 VDC	tion (CN2)	Rated input voltage	24 VDC (15 to 28.8 VDC)	
	Operating load voltage range	20.4 to 28.8 VDC		Input current	7 mA typical (at 24 VDC)	
	Maximum value of load current	0.5 A/point, 2 A/Unit		ON volt- age/ON cur- rent	15 VDC min./3 mA min. (between COM and each signal)	
	Maximum inrush current	4.0 A/point, 10 ms max.		OFF volt- age/OFF cur- rent	5 VDC max./1 mA max. (between COM and each signal)	
	Leakage cur- rent	0.1 mA max.		ON/OFF response time	20 μs max./400 μs max.	
	Residual volt- age	1.5 V max.		Input filter time	No filter, 0.25 ms, 0.5 ms, 1 ms (default), 2 ms, 4 ms, 8 ms, 16 ms, 32 ms, 64 ms,	
	ON/OFF response time	0.5 ms max./1.0 ms max.			128 ms, 256 ms	
Indicato	rs	TS indicator, I/O indicators	Dimensions		30 (W) x 100 (H) x 71 (D)	
		MD6256-5  CN 1	Isolation method		Photocoupler isolation	
			Insulation resistance		20 M $\Omega$ min. between isolated circuits (at 100 VDC)	
			Dielectric strength		510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.	
			I/O power supply method		Supply from external source	
			Current capacity of I/O power supply terminal		Without I/O power supply terminals	
			NX Unit power consumption		Connected to a CPU Unit or Commu- nication Control Unit	
					1.10 W max.     Connected to a Communications     Coupler Unit     0.75 W max.	
			Current consumption from I/O power supply		40 mA max.	
			Weight		110 g max.	



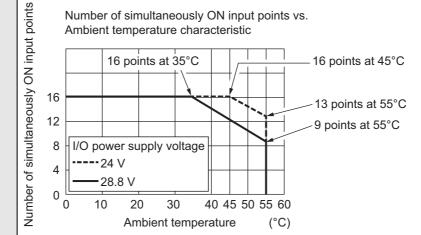
## Installation orientation and restrictions

Installation orientation:

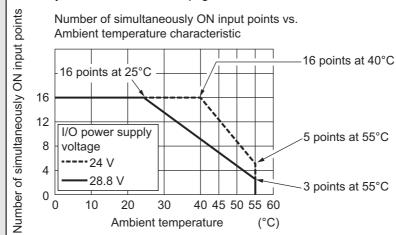
- Connected to a CPU Unit or Communication Control Unit Possible in upright installation.
- Connected to a Communications Coupler Unit Possible in 6 orientations.

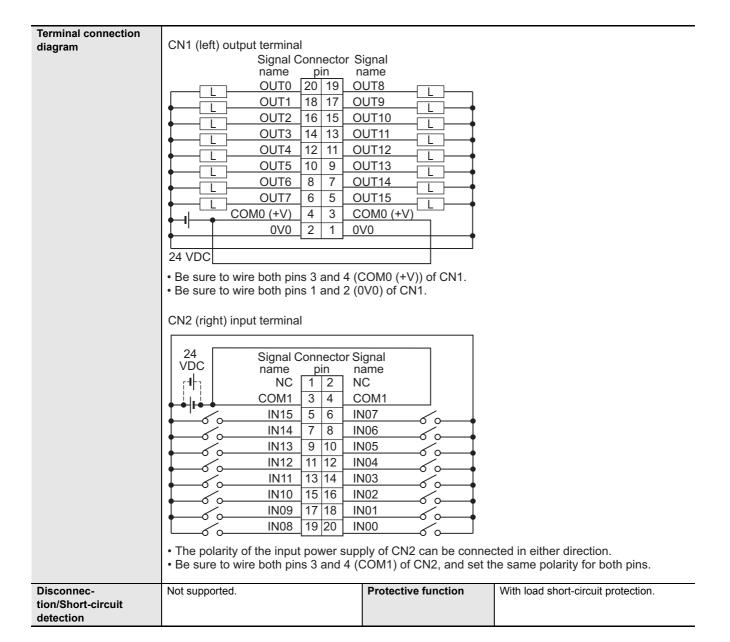
Restrictions: As shown in the following.

For upright installation



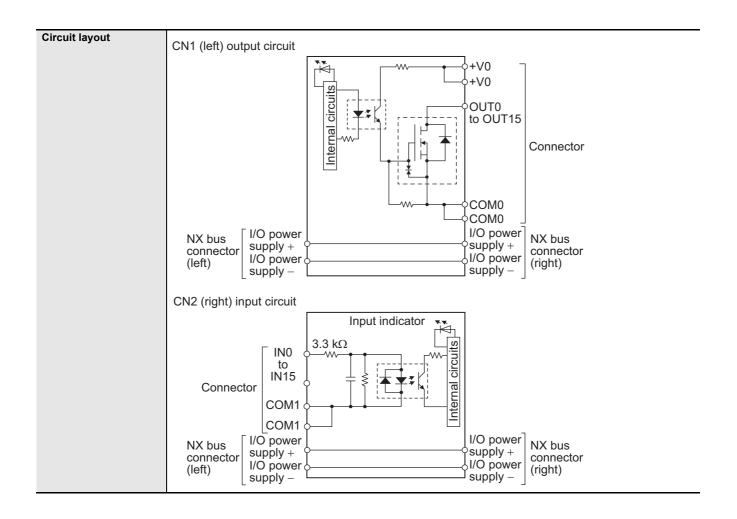
· For any installation other than upright





## DC Input/Transistor Output Units (Fujitsu Connector, 30 mm Width)

Unit name		DC Input/Transistor Output Unit	Model		NX-MD6121-6	
Number of points		16 inputs/16 outputs	External connection terminals		2 Fujitsu connectors (24 terminals)	
I/O refreshing method		Switching Synchronous I/O refreshing and Free-Run refreshing				
Out- put	Internal I/O common	NPN	Input sec-	Internal I/O common	For both NPN/PNP	
sec- tion (CN1)	Rated voltage	12 to 24 VDC	tion (CN2)	Rated input voltage	24 VDC (15 to 28.8 VDC)	
	Operating load voltage range	10.2 to 28.8 VDC		Input current	7 mA typical (at 24 VDC)	
	Maximum value of load current	0.5 A/point, 2 A/Unit		ON volt- age/ON cur- rent	15 VDC min./3 mA min. (between COM and each signal)	
	Maximum inrush current	4.0 A/point, 10 ms max.		OFF volt- age/OFF cur- rent	5 VDC max./1 mA max. (between COM and each signal)	
	Leakage cur- rent	0.1 mA max.		ON/OFF response time	20 μs max./400 μs max.	
	Residual voltage	1.5 V max.  0.1 ms max./0.8 ms max.		Input filter time	No filter, 0.25 ms, 0.5 ms, 1 ms (default), 2 ms, 4 ms, 8 ms, 16 ms, 32 ms, 64 ms, 128 ms, 256 ms	
	response time	0.1 ms max./0.8 ms max.			120 110, 200 110	
Indicators		TS indicator, I/O indicators	Dimensions		30 (W) x 100 (H) x 71 (D)	
		MDC121 C	Isolation method		Photocoupler isolation	
		MD6121-6  CN 1 0 1 2 3 4 5 6 7 1 8 9 10 11 12 13 14 15 2 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15	Dielectric strength		20 M $\Omega$ min. between isolated circuits (at 100 VDC)	
					510 VAC between isolated circuits for 1 minute at a leakage current of 5 mA max.	
			I/O power supply method		Supply from external source	
			Current capacity of I/O power supply terminal		Without I/O power supply terminals	
			NX Unit power consumption		Connected to a CPU Unit or Commu- nication Control Unit	
					<ul><li>1.00 W max.</li><li>Connected to a Communications Coupler Unit</li><li>0.70 W max.</li></ul>	
			Current consumption from I/O power supply		30 mA max.	
			Weight		95 g max.	



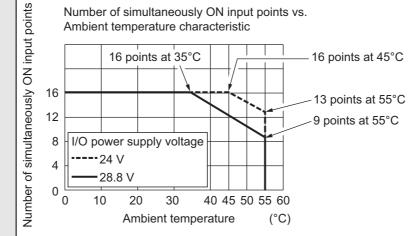
## Installation orientation and restrictions

Installation orientation:

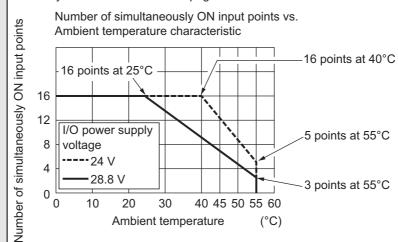
- Connected to a CPU Unit or Communication Control Unit Possible in upright installation.
- Connected to a Communications Coupler Unit Possible in 6 orientations.

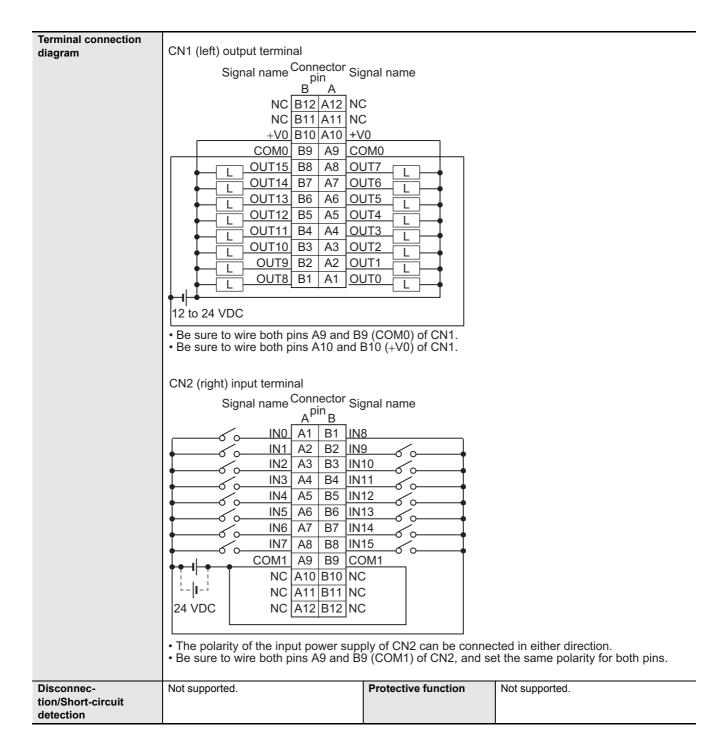
Restrictions: As shown in the following.

For upright installation



· For any installation other than upright

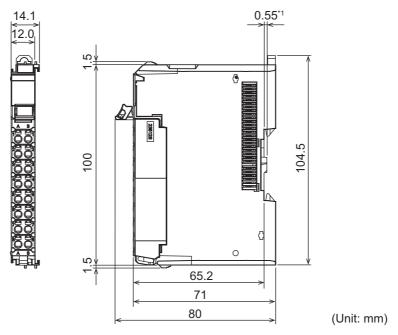




# **A-2 Dimensions**

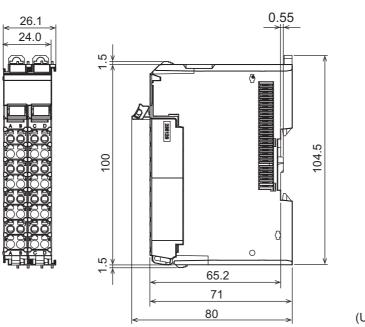
# A-2-1 Screwless Clamping Terminal Block Type

# 12 mm Width

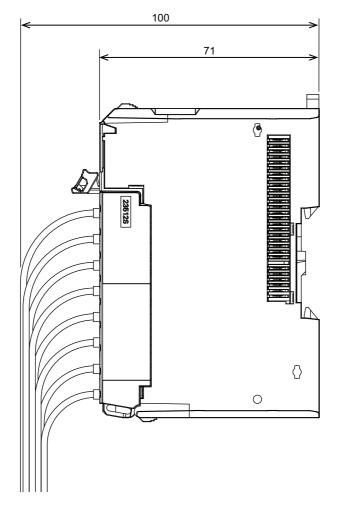


\*1. The dimension is 1.35 mm for Units with lot numbers through December 2014.

# 24 mm Width

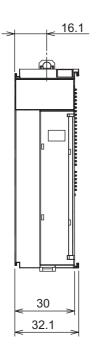


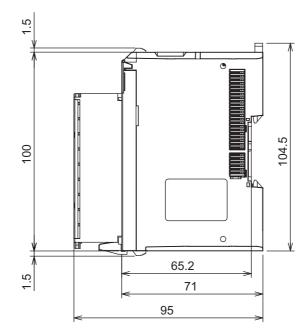
# Installation Height



# A-2-2 M3 Screw Terminal Block Type

# 30 mm Width

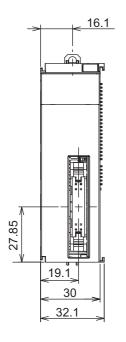


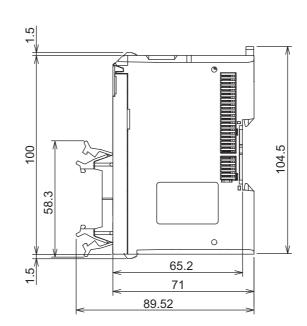


## **A-2-3** Connector Types

# 30 mm Width

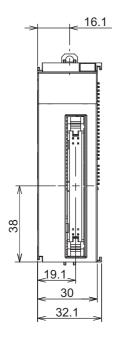
#### • Units with MIL Connectors (1 Connector with 20 Terminals)

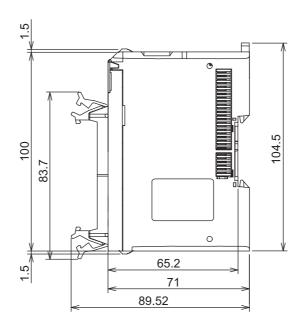




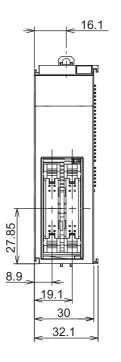
(Unit: mm)

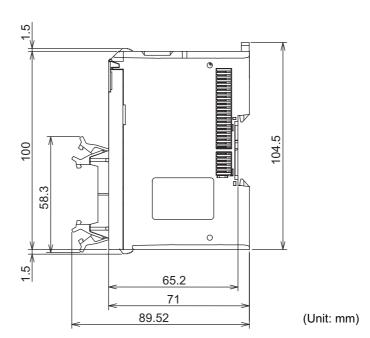
#### • Units with MIL Connectors (1 Connector with 40 Terminals)



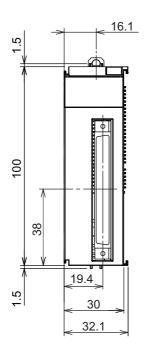


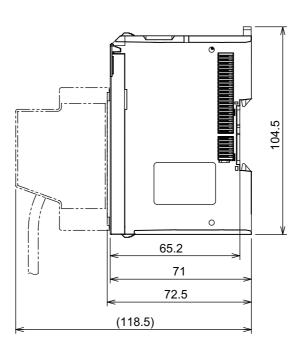
#### • Units with MIL Connectors (2 Connectors with 20 Terminals)



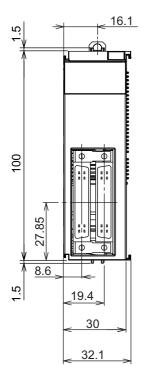


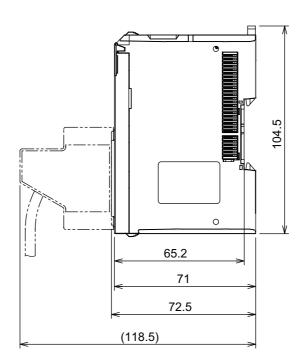
#### • Units with Fujitsu Connectors (1 Connector with 40 Terminals)





#### • Units with Fujitsu Connectors (2 Connectors with 24 Terminals)





# A-3 Connecting Connector-Terminal Block Conversion Units and I/O Relay Terminals

# A-3-1 Patterns for Combining Connector-Terminal Block Conversion Units and I/O Relay Terminals

The following patterns can be used to connect Digital I/O Units with connectors to OMRON Connector-Terminal Block Conversion Units and I/O Relay Terminals using OMRON Connecting Cables.

# **Connection Patterns for Connector-Terminal Block Conversion Units**

Pattern	Configuration	Number of connectors	Branching
A	Connecting Cable Connector-Terminal Block Conversion Unit 20 or 40 terminals	1	None
В	Connecting Cable with two branches Connector-Terminal Block Conversion Unit 20 terminals 20 terminals	-	2 branches
С	Connecting Cable Connector-Terminal Block Conversion Unit 20 terminals 20 terminals	2	None

# Connection Patterns for I/O Relay Terminals

Pattern	Configuration			
Α	Connecting Cable  I/O Relay Terminal			
E	I/O Relay Terminal Connecting Cable			
F	Connecting Cable  I/O Relay Terminal			

#### A-3-2 Combinations of Connections

Combinations of OMRON Connecting Cables with Connector-Terminal Block Conversion Units and I/O Relay Terminals are shown below.

#### **Connections to Connector-Terminal Block Conversion Units**

Unit	I/O capac- ity	Num- ber of connec- tors	Polar- ity	Con- nec- tion pat- tern	Num ber of bran ches	Connecting Cable	Connector-Terminal Block Conversion Unit	Com- mon termi- nal	Con- nection diagram
				Α	None	XW2Z-□□□X	XW2B-20G4	None	
NX-ID5142-5	1 16	1 MIL connec-	NPN/P	Α	None	XW2Z-□□□X	XW2B-20G5	None	
NA-ID5142-5	inputs	tor	NP	Α	None	XW2Z-□□□X	XW2D-20G6	None	P. A-116
			Α	None	XW2Z-□□□X	XW2R-J20G-T	None	P. A-116	
				Α	None	XW2Z-□□□K	XW2B-40G4	None	
				Α	None	XW2Z-□□□K	XW2B-40G5	None	
				Α	None	XW2Z-□□□K	XW2D-40G6	None	P. A-117
			Α	None	XW2Z-□□□K	XW2D-40G6-RM*1	None P. A-117		
			Α	None	XW2Z-□□□K	XW2R-J40G-T	None	P. A-117	
				В	2	XW2Z-□□□N	XW2B-20G4 (2 Units)	None	
				В	2	XW2Z-□□□N	XW2B-20G5 (2 Units)	None	
	32	1 MIL	NPN/P	В	2	XW2Z-□□□N	XW2C-20G5-IN16 (2 Units) *2	Yes	
NX-ID6142-5	inputs	connec- tor	NP	В	2	XW2Z-□□□N	XW2C-20G6-IO16 (2 Units)	Yes	P. A-118
				В	2	XW2Z-□□□N	XW2D-20G6 (2 Units)	None	
				В	2	XW2Z-□□□N	XW2E-20G5-IN16 (2 Units) *2	Yes	
				В	2	XW2Z-□□□N	XW2F-20G7-IN16 (2 Units) *2	Yes	
				В	2	XW2Z-□□□N	XW2N-20G8-IN16 (2 Units) *2	Yes	
				В	2	XW2Z-□□□N	XW2R-J20G-T (2 Units)	None	P. A-118

<sup>\*1.</sup> Bleeder resistor (5.6 k $\Omega$ ) is built in.

<sup>\*2.</sup> The inputs are NPN. For PNP inputs, reverse the polarity of the external power supply connections to the power supply terminals on the Connector-Terminal Block Conversion Unit.

Unit	I/O capac- ity	Num- ber of connec- tors	Polar- ity	Con- nec- tion pat- tern	Num ber of bran ches	Connecting Cable	Connector-Terminal Block Conversion Unit	Com- mon termi- nal	Con- nection diagram	
				Α	None	XW2Z-□□□B	XW2B-40G4	None		
				Α	None	XW2Z-□□□B	XW2B-40G5	None		
				Α	None	XW2Z-□□□B	XW2D-40G6	None	P. A-119	
				Α	None	XW2Z-□□□B	XW2D-40G6-RF*1	None	P. A-119	
				Α	None	XW2Z-□□□B	XW2R-J40G-T	None	P. A-119	
					None	XW2Z-□□□BU	XW2D-40C6	None		
		1 Fujitsu connec- tor	NPN/P NP			2	XW2Z-□□□D	XW2B-20G4 (2 Units)	None	
				В	2	XW2Z-□□□D	XW2B-20G5 (2 Units)	None		
NX-ID6142-6	32			В	2	XW2Z-□□□D	XW2C-20G5-IN16 (2 Units) *2	Yes		
	inputs			В	2	XW2Z-□□□D	XW2C-20G6-IO16 (2 Units)	Yes	P. A-120	
				В	2	XW2Z-□□□D	XW2D-20G6 (2 Units)	None		
				В	2	XW2Z-□□□D	XW2E-20G5-IN16 (2 Units) *2	Yes		
				В	2	XW2Z-□□□D	XW2F-20G7-IN16 (2 Units) *2	Yes		
				В	2	XW2Z-□□□D	XW2N-20G8-IN16 (2 Units) *2	Yes		
				В	2	XW2Z-□□□D	XW2R-J20G-T (2 Units)	None	P. A-120	

<sup>\*1.</sup> Bleeder resistor (5.6  $k\Omega$ ) is built in.

<sup>\*2.</sup> The inputs are NPN. For PNP inputs, reverse the polarity of the external power supply connections to the power supply terminals on the Connector-Terminal Block Conversion Unit.

Unit	I/O capac- ity	Num- ber of connec- tors	Polar- ity	Con- nec- tion pat- tern	Num ber of bran ches	Connecting Cable	Connector-Terminal Block Conversion Unit	Com- mon termi- nal	Con- nection diagram
				Α	None	XW2Z-□□□X	XW2B-20G4	None	
NX-OD5121-5	16 out-	1 MIL connec-	NPN	Α	None	XW2Z-□□□X	XW2B-20G5	None	
NX-0D3121-3	puts	tor	INI IN	Α	None	XW2Z-□□□X	XW2D-20G6	None	P. A-121
				Α	None	XW2Z-□□□X	XW2R-J20G-T	None	P. A-121
				Α	None	XW2Z-□□□X	XW2B-20G4	None	
NX-OD5256-5	16 out-	1 MIL connec-	PNP	Α	None	XW2Z-□□□X	XW2B-20G5	None	
1474-0150250-5	puts	tor	1 131	Α	None	XW2Z-□□□X	XW2D-20G6	None	P. A-122
				Α	None	XW2Z-□□□X	XW2R-J20G-T	None	P. A-122
				Α	None	XW2Z-□□□K	XW2B-40G4	None	
				Α	None	XW2Z-□□□K	XW2B-40G5	None	
				Α	None	XW2Z-□□□K	XW2D-40G6	None	P. A-123
			Α	None	XW2Z-□□□K	XW2R-J40G-T	None	P. A-123	
	1.00	1 MIL		В	2	XW2Z-□□□N	XW2B-20G4 (2 Units)	None	
32 out-	connec-	NPN	В	2	XW2Z-□□□N	XW2B-20G5 (2 Units)	None		
	tor		В	2	XW2Z-□□□N	XW2C-20G6-IO16 (2 Units)	Yes	P. A-124	
			В	2	XW2Z-□□□N	XW2D-20G6 (2 Units)	None		
				В	2	XW2Z-□□□N	XW2F-20G7-OUT16 (2 Units)	Yes	
				В	2	XW2Z-□□□N	XW2R-J20G-T (2 Units)	None	P. A-124
				Α	None	XW2Z-□□□B	XW2B-40G4	None	
				Α	None	XW2Z-□□□B	XW2B-40G5	None	
				Α	None	XW2Z-□□□B	XW2D-40G6	None	P. A-125
				Α	None	XW2Z-□□□B	XW2R-J40G-T	None	P. A-125
				Α	None	XW2Z-□□□BU	XW2D-40C6	None	
	32 out-	1 Fujitsu		В	2	XW2Z-□□□L	XW2B-20G4 (2 Units)	None	
NX-OD6121-6	puts	connec- tor	NPN	В	2	XW2Z-□□□L	XW2B-20G5 (2 Units)	None	
		toi		В	2	XW2Z-□□□L	XW2C-20G6-IO16 (2 Units)	Yes	P. A-126
				В	2	XW2Z-□□□L	XW2D-20G6 (2 Units)	None	
				В	2	XW2Z-□□□L	XW2F-20G7-OUT16 (2 Units)	Yes	
				В	2	XW2Z-□□□L	XW2R-J20G-T (2 Units)	None	P. A-126
				Α	None	XW2Z-□□□K	XW2B-40G4	None	
				Α	None	XW2Z-□□□K	XW2B-40G5	None	
				Α	None	XW2Z-□□□K	XW2D-40G6	None	P. A-127
				Α	None	XW2Z-□□□K	XW2R-J40G-T	None	P. A-127
NX-OD6256-5 32 outputs		1 MIL		В	2	XW2Z-□□□N	XW2B-20G4 (2 Units)	None	
	32 out-	connec-	PNP	В	2	XW2Z-□□□N	XW2B-20G5 (2 Units)	None	
	puts	tor		В	2	XW2Z-□□□N	XW2C-20G6-IO16 (2 Units)	Yes	P. A-128
			[	В	2	XW2Z-□□□N	XW2D-20G6 (2 Units)	None	
				В	2	XW2Z-□□□N	XW2F-20G7-OUT16 (2 Units)	Yes	
				В	2	XW2Z-□□□N	XW2R-J20G-T (2 Units)	None	P. A-128

Unit	I/O capac- ity	Num- ber of connec- tors	Polar- ity	Con- nec- tion pat- tern	Num ber of bran ches	Connecting Cable	Connector-Terminal Block Conversion Unit	Com- mon termi- nal	Con- nection diagram
				С	None	XW2Z-□□□X	XW2B-20G4	None	
	16	1 MIL connec-	NPN/P	С	None	XW2Z-□□□X	XW2B-20G5	None	
	inputs	tor	NP	С	None	XW2Z-□□□X	XW2D-20G6	None	P. A-129
NX-MD6121-5				С	None	XW2Z-□□□X	XW2R-J20G-T	None	P. A-129
1474-1411111111111111111111111111111111				С	None	XW2Z-□□□X	XW2B-20G4	None	
	16 out-	1 MIL connec-	NPN	С	None	XW2Z-□□□X	XW2B-20G5	None	
	puts	tor	INI IN	С	None	XW2Z-□□□X	XW2D-20G6	None	P. A-129
				С	None	XW2Z-□□□X	XW2R-J20G-T	None	P. A-129
				С	None	XW2Z-□□□A	XW2B-20G4	None	
				С	None	XW2Z-□□□A	XW2B-20G5	None	
			NPN/P NP	С	None	XW2Z-□□□A	XW2C-20G5-IN16 *1	Yes	
		1 Fujitsu		С	None	XW2Z-□□□A	XW2C-20G6-IO16	Yes	P. A-130
	16 inputs	connec- tor		С	None	XW2Z-□□□A	XW2D-20G6	None	P. A-130
	iriputs			С	None	XW2Z-□□□A	XW2E-20G5-IN16 *1	Yes	
				С	None	XW2Z-□□□A	XW2F-20G7-IN16 *1	Yes	
NX-MD6121-6				С	None	XW2Z-□□□A	XW2N-20G8-IN16 *1	Yes	
				С	None	XW2Z-□□□A	XW2R-J20G-T	None	P. A-131
				С	None	XW2Z-□□□A	XW2B-20G4	None	
				С	None	XW2Z-□□□A	XW2B-20G5	None	
	16 out-	1 Fujitsu	NPN	С	None	XW2Z-□□□A	XW2C-20G6-IO16	Yes	P. A-130
	puts	connec- tor	INPIN	С	None	XW2Z-□□□A	XW2D-20G6	None	P. A-130
				С	None	XW2Z-□□□A	XW2F-20G7-OUT16	Yes	
				С	None	XW2Z-□□□A	XW2R-J20G-T	None	P. A-131
				С	None	XW2Z-□□□X	XW2B-20G4	None	
	16	1 MIL	NPN/P	С	None	XW2Z-□□□X	XW2B-20G5	None	
'	inputs	connec- tor	NP	С	None	XW2Z-□□□X	XW2D-20G6	None	P. A-132
				С	None	XW2Z-□□□X	XW2R-J20G-T	None	P. A-132
NX-MD6256-5				С	None	XW2Z-□□□X	XW2B-20G4	None	
	16 out-	1 MIL connec-	PNP	С	None	XW2Z-□□□X	XW2B-20G5	None	
	puts	tor	PNP	С	None	XW2Z-□□□X	XW2D-20G6	None	P. A-132
				С	None	XW2Z-□□□X	XW2R-J20G-T	None	P. A-132

<sup>\*1.</sup> The inputs are NPN. For PNP inputs, reverse the polarity of the external power supply connections to the power supply terminals on the Connector-Terminal Block Conversion Unit.

# Connections to I/O Relay Terminals

Unit	I/O capacity	Number of connectors	Polar- ity	Connection pattern	Number of branches	Connecting Cable	I/O Relay Terminal	Con- nection diagram																		
				F	None	XW2Z-RO□C	G7TC-ID16	P. A-133																		
			NPN	F	None	XW2Z-RO□C	G7TC-IA16	F. A-133																		
NX-ID5142-5	NX-ID5142-5 16 inputs	1 MIL con-	INFIN	F	None	XW2Z-RO□C	G70V-SID16P																			
NX-1D3142-3	10 iriputs	nector		F	None	XW2Z-RO□C	G70V-SID16P-C16																			
			PNP	F	None	XW2Z-RO□C	G70V-SID16P-1																			
				FINE	F	None	XW2Z-RO□C	G70V-SID16P-1-C16																		
				Α	2	XW2Z-RO□-□-D1	G7TC-ID16	P. A-133																		
			NPN	Α	2	XW2Z-RO□-□-D1	G7TC-IA16	F. A-133																		
NX-ID6142-5	32 inputs	1 MIL con-	INFIN	Α	2	XW2Z-RO□-□-D1	G70V-SID16P																			
NX-1D0142-3	32 iriputs	nector		Α	2	XW2Z-RO□-□-D1	G70V-SID16P-C16																			
			PNP	Α	2	XW2Z-RO□-□-D1	G70V-SID16P-1																			
			PNP	Α	2	XW2Z-RO□-□-D1	G70V-SID16P-1-C16																			
				Α	2	XW2Z-RI□C-□	G7TC-ID16	P. A-133																		
			NIDNI	Α	2	XW2Z-RI□C-□	G7TC-IA16	P. A-133																		
NV IDC440.0	20 :	1 Fujitsu	NPN	Α	2	XW2Z-RI□C-□	G70V-SID16P																			
NX-ID6142-6	11)6142-6 132 inputs 1	connector		Α	2	XW2Z-RI□C-□	G70V-SID16P-C16																			
			DND	Α	2	XW2Z-RI□C-□	G70V-SID16P-1																			
			PNP	Α	2	XW2Z-RI□C-□	G70V-SID16P-1-C16																			
				F	None	XW2Z-RO□C	G7TC-OC08	P. A-137																		
						F	None	XW2Z-RO□C	G70D-SOC08	P. A-135																
				F	None	XW2Z-RO□C	G70R-SOC08	P. A-136																		
				F	None	XW2Z-RO□C	G7TC-OC16	P. A-137																		
				F	None	XW2Z-RO□C	G70D-SOC16	P. A-135																		
NX-OD5121-5	16 out-		1 MIL con- nector				NPN	F	None	XW2Z-RO□C	G70D-VSOC16	P. A-134														
	puts	nector					nector	nector	HECIOI	HECIOI	HECIOI	HECIOI	HECIOI	HECIOI	HECIUI	nector		F								
				F	None	XW2Z-RO□C	G70D-VFOM16																			
				F	None	XW2Z-RO□C	G70A-ZOC16-3																			
				F	None	XW2Z-RO□C	G70V-SOC16P																			
				F	None	XW2Z-RO□C	G70V-SOC16P-C4																			
				F	None	XW2Z-RI□C	G7TC-OC16-1	P. A-137																		
				F	None	XW2Z-RO□C	G70D-SOC16-1	P. A-136																		
	16 out-	1 MIL con-		F	None	XW2Z-RO□C	G70D-FOM16-1																			
NX-OD5256-5	puts	nector	PNP	F	None	XW2Z-RO□C	G70A-ZOC16-4																			
				F	None	XW2Z-RO□C	G70V-SOC16P-1																			
				F	None	XW2Z-RO□C	G70V-SOC16P-1-C4																			
				Α	2	XW2Z-RO□-□-D1	G7TC-OC16																			
				Α	2	XW2Z-RO□-□-D1	G7TC-OC08	P. A-137																		
				Α	2	XW2Z-RO□-□-D1	G70D-SOC16	P. A-135																		
				A	2	XW2Z-RO□-□-D1	G70D-FOM16																			
				Α	2	XW2Z-RO□-□-D1	G70D-VSOC16	P. A-134																		
NV ODOLOL E	32 out-	1 MIL con-	NIES!	A	2	XW2Z-RO□-□-D1	G70D-VFOM16																			
NX-OD6121-5 puts	puts	nector	NPN	А	2	XW2Z-RO□-□-D1	G70A-ZOC16-3 and Relay	P. A-138																		
				Α	2	XW2Z-RO□-□-D1	G70R-SOC08	P. A-136																		
				Α	2	XW2Z-RO□-□-D1	G70D-SOC08	P. A-135																		
				Α	2	XW2Z-RO□-□-D1	G70V-SOC16P																			
				A	2	XW2Z-RO□-□-D1	G70V-SOC16P-C4																			

Unit	I/O capacity	Number of connectors	Polar- ity	Connection pattern	Number of branches	Connecting Cable	I/O Relay Terminal	Con- nection diagram			
				Α	2	XW2Z-RO□C-□	G7TC-OC16	P. A-137			
				Α	2	XW2Z-RO□C-□	G7TC-OC08	F. A-131			
				Α	2	XW2Z-RO□C-□	G70D-SOC16	P. A-135			
				Α	2	XW2Z-RO□C-□	G70D-FOM16				
				Α	2	XW2Z-RO□C-□	G70D-VSOC16	P. A-134			
NX-OD6121-6	32 out-	1 Fujitsu	NPN	Α	2	XW2Z-RO□C-□	G70D-VFOM16				
100 000121 0	puts	connector		Α	2	XW2Z-RO□C-□	G70A-ZOC16-3 and Relay	P. A-138			
				Α	2	XW2Z-RO□C-□	G70R-SOC08	P. A-136			
				Α	2	XW2Z-RO□C-□	G70D-SOC08	P. A-135			
				Α	2	XW2Z-RO□C-□	G70V-SOC16P				
				Α	2	XW2Z-RO□C-□	G70V-SOC16P-C4				
				Α	2	XW2Z-RI□-□-D1	G7TC-OC16-1	P. A-137			
				Α	2	XW2Z-RO□-□-D1	G70D-SOC16-1	P. A-136			
	22 out	1 MIL con		Α	2	XW2Z-RO□-□-D1	G70D-FOM16-1				
NX-OD6256-5	32 out- puts	1 MIL con- nector	PNP	Α	2	XW2Z-RO□-□-D1	G70A-ZOC16-4 and Relay				
				Α	2	XW2Z-RO□-□-D1	G70V-SOC16P-1				
				Α	2	XW2Z-RO□-□-D1	G70V-SOC16P-1-C4				
				E	None	XW2Z-RO□C	G7TC-ID16	D 4 400			
	40 in	1 MIL con-	1 MIL con-	1 MIL con-	1 MIL con-	NIDNI	Е	None	XW2Z-RO□C	G7TC-IA16	P. A-133
	16 inputs	nector	NPN	Е	None	XW2Z-RO□C	G70V-SID16P				
				Е	None	XW2Z-RO□C	G70V-SID16P-C16				
				Е	None	XW2Z-RO□C	G7TC-OC16	D 4 407			
				Е	None	XW2Z-RO□C	G7TC-OC08	P. A-137			
				Е	None	XW2Z-RO□C	G70D-SOC16	P. A-135			
NX-MD6121-5				Е	None	XW2Z-RO□C	G70D-FOM16				
INX-IVIDO121-3				Е	None	XW2Z-RO□C	G70D-VSOC16	P. A-134			
	16 out-	1 MIL con-	NPN	Е	None	XW2Z-RO□C	G70D-VFOM16				
	puts	nector	NPN	Е	None	XW2Z-RO□C	G70A-ZOC16-3 and Relay	P. A-138			
				Е	None	XW2Z-RO□C	G70R-SOC08	P. A-136			
				Е	None	XW2Z-RO□C	G70D-SOC08	P. A-135			
				Е	None	XW2Z-RO□C	G70V-SOC16P				
				Е	None	XW2Z-RO□C	G70V-SOC16P-C4				
				Е	None	XW2Z-R□C	G7TC-ID16	5 4 400			
		1 Fujitsu		Е	None	XW2Z-R□C	G7TC-IA16	P. A-133			
	16 inputs	connector	NPN	Е	None	XW2Z-R□C	G70V-SID16P				
				Е	None	XW2Z-R□C	G70V-SID16P-C16				
				Е	None	XW2Z-R□C	G7TC-OC16				
				Е	None	XW2Z-R□C	G7TC-OC08	P. A-137			
				Е	None	XW2Z-R□C	G70D-SOC16	P. A-135			
NV MD6121 6				Е	None	XW2Z-R□C	G70D-FOM16				
NX-MD6121-6  16 outputs				Е	None	XW2Z-R□C	G70D-VSOC16	P. A-134			
	16 out-	1 Fujitsu	NIDA	Е	None	XW2Z-R□C	G70D-VFOM16				
	puts	connector	NPN .	E	None	XW2Z-R□C	G70A-ZOC16-3 and Relay	P. A-138			
				Е	None	XW2Z-R□C	G70R-SOC08	P. A-136			
				Е	None	XW2Z-R□C	G70D-SOC08	P. A-135			
				Е	None	XW2Z-R□C	G70V-SOC16P				
				Е	None	XW2Z-R□C	G70V-SOC16P-C4				

Unit	I/O capacity	Number of connectors	Polar- ity	Connection pattern	Number of branches	Connecting Cable	I/O Relay Terminal	Con- nection diagram
	16 inpute	1 MIL con-	PNP	Е	None	XW2Z-RO□C	G70V-SID16P-1	
	16 inputs nector	nector	PNP	Е	None	XW2Z-RO□C	G70V-SID16P-1-C16	
		1 MIL con- nector	PNP	Е	None	XW2Z-RO□C	G7TC-OC16-1	P. A-137
				Е	None	XW2Z-RI□C	G70D-SOC16-1	P. A-136
NX-MD6256-5	16 out-			Е	None	XW2Z-RI□C	G70D-FOM16-1	
	puts			E	None	XW2Z-RI□C	G70A-ZOC16-4 and Relay	
			E	None	XW2Z-RI□C	G70V-SOC16P-1		
				E	None	XW2Z-RI□C	G70V-SOC16P-1-C4	

#### A-3-3 Connector-Terminal Block Conversion Unit Connection Diagrams

The applicable terminals on the Connector-Terminal Block Conversion Unit and external connection diagrams are provided below for Digital I/O Unit connections to Connector-Terminal Block Conversion Units.

In the connection diagrams here, 1 word consists of 16 points of the I/O terminals and the first word is called Wd m.

#### Inputs

Digital I/O Unit	NX-ID5142-5
Connector-Terminal Block Conversion Unit	XW2D-20G6
Connecting Cable	XW2Z-□□□X
Connection diagram	

Note 1. The polarity for input power supply connections indicated with dotted lines (----) can be connected in either direction.

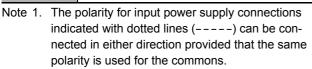
2. The COM terminals are internally connected inside the Unit, but they must all be wired.

Digital I/O Unit	NX-ID5142-5
Connector-Terminal Block Conversion Unit	XW2R-J20G-T
Connecting Cable	XW2Z-□□□X
Connection diagram	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0

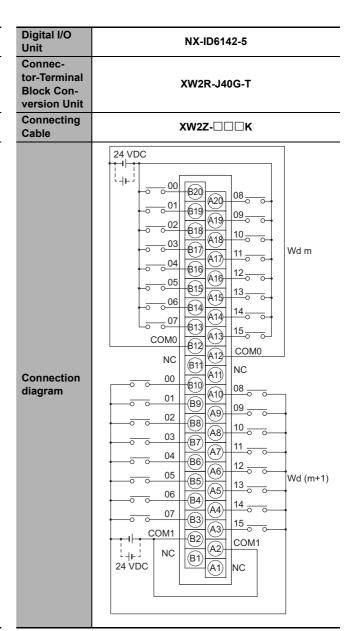
Note 1. The polarity for input power supply connections indicated with dotted lines (- - - - -) can be connected in either direction.

2. The COM terminals are internally connected inside the Unit, but they must all be wired.

Digital I/O Unit	NX-ID6142-5							
Connector-Terminal Block Conversion Unit	XW2D-40G6 XW2D-40G6-RM							
Connecting Cable	XW2Z-□□□K							
Connection diagram	24 VDC							

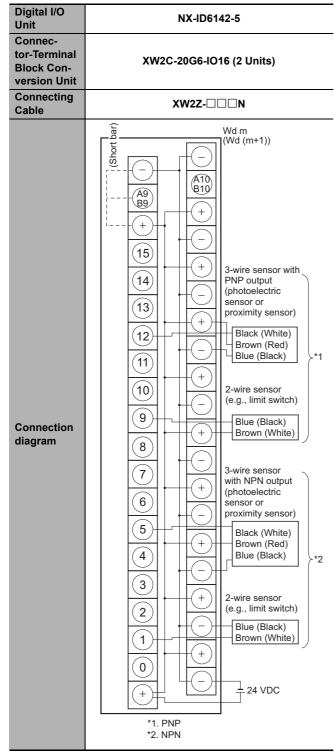


Both COM0 and COM1 have two pins each. They are internally connected inside the Unit, but they must all be wired.



Note 1. The polarity for input power supply connections indicated with dotted lines (----) can be connected in either direction provided that the same polarity is used for the commons.

Both COM0 and COM1 have two pins each. They are internally connected inside the Unit, but they must all be wired.

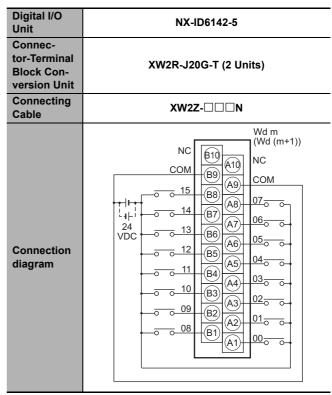


Note 1. Connect the A9/B9 terminal and the  $\oplus$  terminal for NPN.

Connect the A9/B9 terminal and the  $\ominus$  terminal for PNP.

(Use the enclosed short bar.)

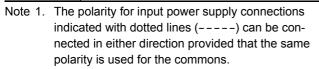
The COM terminals are wired inside the Connector-Terminal Block Conversion Unit.



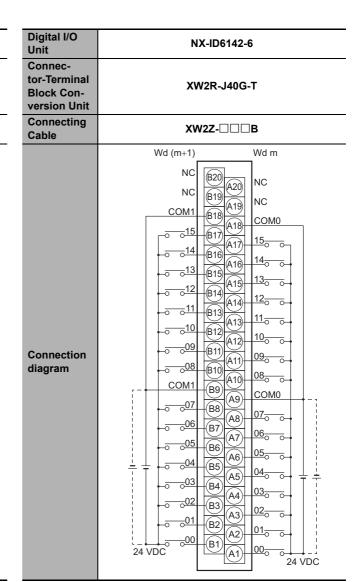
Note 1. The polarity for input power supply connections indicated with dotted lines (----) can be connected in either direction.

2. The COM terminals are internally connected inside the Unit, but they must all be wired.

Digital I/O Unit	NX-ID6142-6
Connec- tor-Terminal Block Con- version Unit	XW2D-40G6 XW2D-40G6-RF
Connecting Cable	XW2Z-□□□B
Connection	Wd m Wd (m+1)  NC (A2) (B19)  COM0 (A13) (B13) (COM1)  COM0 (A13) (B13) (A14) (B14) (A16) (B15) (A17) (B14) (A18)
	001 (B2) 01 00 00



2. Both COM0 and COM1 have two pins each. They are internally connected inside the Unit, but they must all be wired.



Note 1. The polarity for input power supply connections indicated with dotted lines (----) can be connected in either direction provided that the same polarity is used for the commons.

2. Both COM0 and COM1 have two pins each. They are internally connected inside the Unit, but they must all be wired.

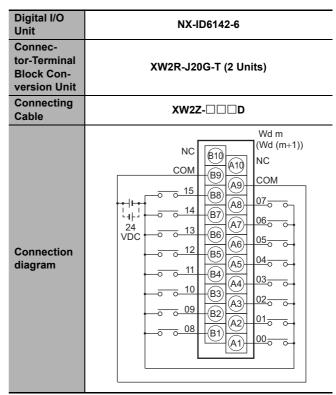
Digital I/O Unit	NX-ID6142-6
Connector-Terminal Block Conversion Unit	XW2C-20G6-IO16 (2 Units)
Connecting Cable	XW2Z-□□□D
Connection diagram	Wd m (Wd (m+1))  A10 B10 B9 ++   15  14  15  14  15  14  15  14  15  14  15  14  15  14  15  16  17  18  18  19  10  2-wire sensor or proximity sensor)  Blue (Black) Brown (Red) Blue (Black) Brown (White)  Brown (Red) Brown (White)   3-wire sensor (e.g., limit switch) Blue (Black) Brown (Red) Blue (Black) Brown (Red) Blue (Black) Brown (White)   2-wire sensor or proximity sensor)  Black (White) Brown (Red) Blue (Black) Brown (White)   2-wire sensor (e.g., limit switch) Blue (Black) Brown (White)   24 VDC  *1. PNP *2. NPN

Note 1. Connect the A9/B9 terminal and the  $\oplus$  terminal for NPN.

Connect the A9/B9 terminal and the  $\ominus$  terminal for PNP.

(Use the enclosed short bar.)

2. The COM terminals are wired inside the Connector-Terminal Block Conversion Unit.



Note 1. The polarity for input power supply connections indicated with dotted lines (----) can be connected in either direction.

2. The COM terminals are internally connected inside the Unit, but they must all be wired.

# Outputs

Digital I/O Unit	NX-OD5121-5
Connec- tor-Terminal Block Con- version Unit	XW2D-20G6
Connecting Cable	XW2Z-□□□X
Connection diagram	L 08 A10 B9 01 L 09 A9 B8 02 L 01 L 11 A7 B6 04 L 05 L 13 A5 B4 06 L 07 L 05 A3 COM A2 B2 +V A1 B1 12 to 24 VDC

Note The COM terminals and +V terminals are internally
connected inside the Unit, but they must all be wired.

Digital I/O Unit	NX-OD5121-5
Connector-Terminal Block Conversion Unit	XW2R-J20G-T
Connecting Cable	XW2Z-□□□X
Connection diagram	L 00 810 08 L 09

Note The COM terminals and +V terminals are internally connected inside the Unit, but they must all be wired.

Digital I/O Unit	NX-OD5256-5
Connector-Terminal Block Conversion Unit	XW2D-20G6
Connecting Cable	XW2Z-□□□X
Connection diagram	L 08 (A10) (B10) 00 (L 09) (A10) (B9) 01 (L 09) (A10) (B9) 02 (L 09) (A10) (B10) (A10) (B10) (A10) (A1

Note	The COM (+V) terminals and 0 V terminals are inter-
	nally connected inside the Unit, but they must all be
	wired

Digital I/O Unit	NX-OD5256-5
Connector-Terminal Block Conversion Unit	XW2R-J20G-T
Connecting Cable	XW2Z-□□□X
Connection diagram	L 00 810 08 L 02 88 A9 09 L 03 87 A7 11 L 04 86 A6 12 L 05 85 A5 13 L 07 83 A3 15 L 00  82 A3 00 COM (+V) 81 A1 COM (+V) B1 A1 COM (+V) L 24 VDC

Note The COM (+V) terminals and 0 V terminals are internally connected inside the Unit, but they must all be wired.

Digital I/O Unit	NX-OD6121-5
Connec- tor-Terminal Block Con- version Unit	XW2D-40G6
Connecting Cable	XW2Z-□□□K
Connection diagram	12 to 24 VDC

Digital I/O Unit	NX-OD6121-5
Connector-Terminal Block Conversion Unit	XW2R-J40G-T
Connecting Cable	XW2Z-□□□K
Connection	12 to

Note The COM terminals and +V terminals are internally connected inside the Unit, but they must all be wired.

Note The COM terminals and +V terminals are internally connected inside the Unit, but they must all be wired.

Digital I/O Unit	NX-OD6121-5
Connector-Terminal Block Conversion Unit Connecting Cable	XW2C-20G6-IO16 (2 Units)  XW2Z-□□□N
	(S) (COM1) (COM1
Connection diagram	15 14 14 14 14 15 16 17 18 18 19 19 10 10 10 10 10 10 10 10 10 10 10 10 10
	00

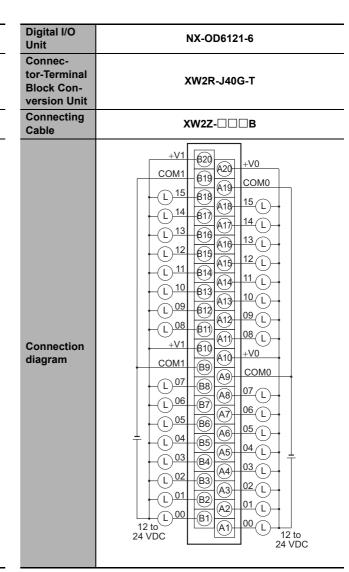
Note 1. Connect the A9/B9 terminal and the  $\ominus$  terminal. Connect the A10/B10 terminal and the  $\oplus$  terminal. (Use the enclosed short bar.)

Digital I/O Unit	NX-OD6121-5
Connector-Terminal Block Conversion Unit	XW2R-J20G-T (2 Units)
Connecting Cable	XW2Z-□□□N
Connection diagram	COM B9 A9 COM (Wd (m+1)) +V COM B8 A8 O7 L D13 B6 A6 O5 L D14 B7 A7 O6 L D15 B8 A8 O2 L D16 B2 A2 O1 L D8 B1 A1 O0 L D8 B2 A2 O1 L D8 B1 A1 O0 L D8 B2 A2 O1 L D8 B1 A1 O0 L D8 B2 A2 O1 L D8 B2 A2 O1 L D8 B1 A1 O0 L D8 B2 A2 O1 L D8 B1 A1 O0 L D8 B2 A2 O1 L D8 B1 A1 O0 L D8 B2 A2 O1 L D8 B1 A1 O0 L D8 B2 A2 O1 L D8 B2 A2 O1 L D8 B1 A1 O0 L D8 B2 A2 O1 L D8 B1 A1 O0 L D8 B2 A2 O1 L D8 B1 A1 O0 L D8 B2 A2 O1 L D8 B1 A1 O0 L D8 B2 A2 O1 L D8 B1 A1 O0 L D8 B2 A2 O1 L D8 A2 O1 L D8 B2 A2 O1 L D8

Note The COM terminals and +V terminals are internally connected inside the Unit, but they must all be wired.

Digital I/O Unit	NX-OD6121-6
Connec- tor-Terminal Block Con- version Unit	XW2D-40G6
Connecting Cable	XW2Z-□□B
Connection diagram	Wd m

Note	The COM terminals and +V terminals are internally
	connected inside the Unit but they must all be wired



Note The COM terminals and +V terminals are internally connected inside the Unit, but they must all be wired.

NX-OD6121-6
XW2C-20G6-IO16 (2 Units)
XW2Z-□□□L
(xe to your field of the field

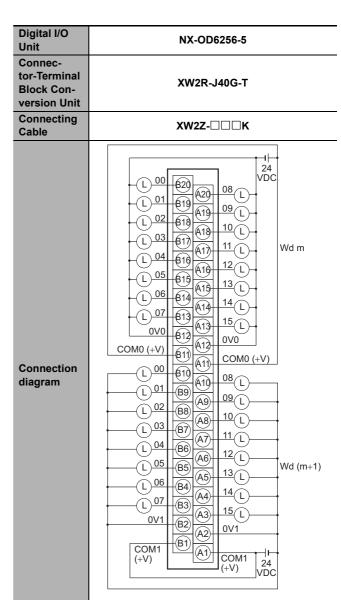
Note 1. Connect the A9/B9 terminal and the  $\ominus$  terminal. Connect the A10/B10 terminal and the  $\oplus$  terminal. (Use the enclosed short bar.)

Digital I/O Unit	NX-OD6121-6
Connec- tor-Terminal Block Con- version Unit	XW2R-J20G-T (2 Units)
Connecting Cable	XW2Z-□□□L
Connection diagram	Wd m (Wd (m+1))  12 to 24

Note The COM terminals and +V terminals are internally connected inside the Unit, but they must all be wired.

Digital I/O Unit	NX-OD6256-5
Connector-Terminal Block Conversion Unit	XW2D-40G6
Connecting Cable	XW2Z-□□□K
Connection diagram	

Note The COM (+V) terminals and 0 V terminals are inter-	_
nally connected inside the Unit, but they must all be	
wired.	



Note The COM (+V) terminals and 0 V terminals are internally connected inside the Unit, but they must all be wired.

Xw2C-20G6-IO16 (2 Units)   Xw2C-20G6-IO16 (2 U	Digital I/O Unit	NX-OD6256-5
Connection diagram  Cable  AW22-DINN  Wd m (Wd (m+1))  A 10	tor-Terminal Block Con- version Unit	XW2C-20G6-IO16 (2 Units)
Connection diagram  Connec		XW2Z-□□□N
		COM0 (COM1) + + + + + + + + + + + + + + + + + + +

Note 1. Connect the A9/B9 terminal and the  $\ominus$  terminal. Connect the A10/B10 terminal and the  $\oplus$  terminal. (Use the enclosed short bar.)

Digital I/O Unit	NX-OD6256-5
Connector-Terminal Block Conversion Unit	XW2R-J20G-T (2 Units)
Connecting Cable	XW2Z-□□□N
Connection diagram	COM

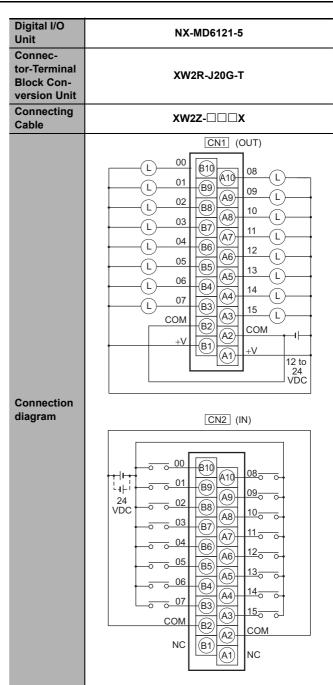
Note The COM (+V) terminals and 0 V terminals are internally connected inside the Unit, but they must all be wired.

#### **Inputs and Outputs**

Digital I/O Unit	NX-MD6121-5
Connector-Terminal Block Conversion Unit	XW2D-20G6
Connecting Cable	XW2Z-□□□X
	CN1 (OUT)    CN1 (OUT)
Connection diagram	CN2 (IN)  CN3 (B1)  COM (A8)  COM (A2)  COM (A2)  COM (A1)  CN2 (IN)  COM (A2)  COM (A3)  COM (A3)  COM (A4)  COM (A4)  COM (A5)  COM (A5)  COM (A5)  COM (A5)  COM (A5)  COM (A1)

Note 1. The polarity for input power supply connections indicated with dotted lines (----) can be connected in either direction.

The COM terminals and +V terminals are internally connected inside the Unit, but they must all be wired.



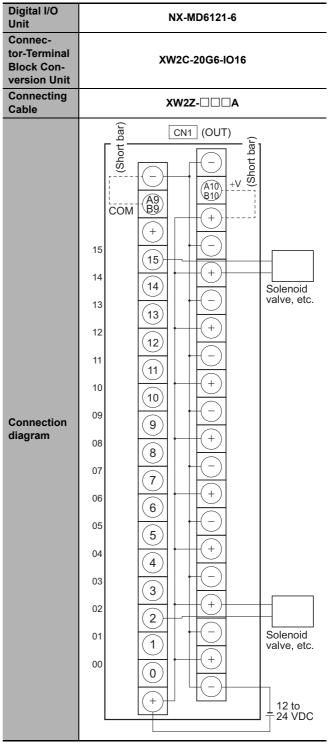
Note 1. The polarity for input power supply connections indicated with dotted lines (----) can be connected in either direction.

2. The COM terminals and +V terminals are internally connected inside the Unit, but they must all be wired.

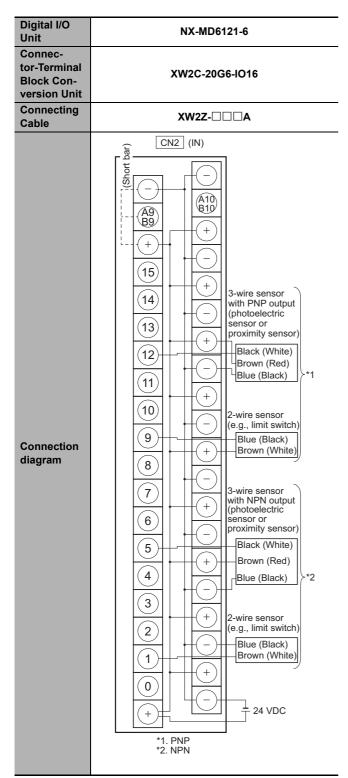
Digital I/O Unit	NX-MD6121-6
Connector-Terminal Block Conversion Unit	XW2D-20G6
Connecting Cable	XW2Z-□□□A
Connection diagram	CN1 (OUT)  +V (A10) (B10) +V  COM (A3) (B3) (COM (A3) (B3) (A4) (B4) (COM (A3) (COM (A3) (B4) (COM (A3) (C

Note 1. The polarity for input power supply connections indicated with dotted lines (----) can be connected in either direction.

2. The COM terminals and +V terminals are internally connected inside the Unit, but they must all be wired.



Note 1. Connect the A9/B9 terminal and the  $\ominus$  terminal. Connect the A10/B10 terminal and the  $\oplus$  terminal. (Use the enclosed short bar.)

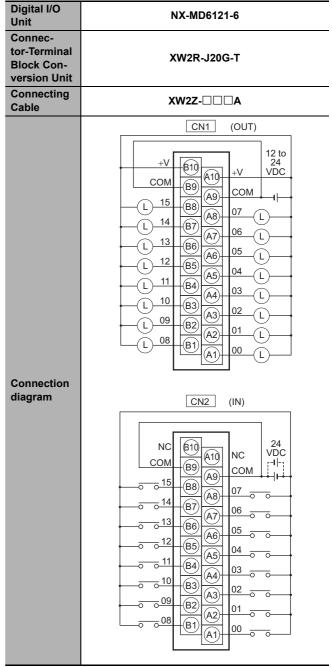


Note 1. Connect the A9/B9 terminal and the  $\oplus$  terminal for NPN.

Connect the A9/B9 terminal and the  $\ominus$  terminal for PNP.

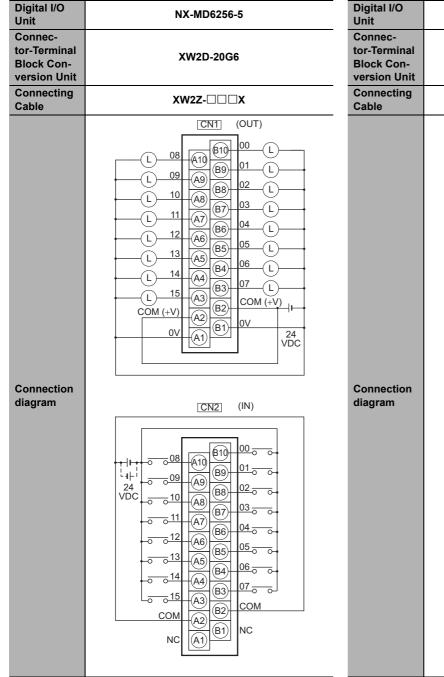
(Use the enclosed short bar.)

The COM terminals are wired inside the Connector-Terminal Block Conversion Unit.



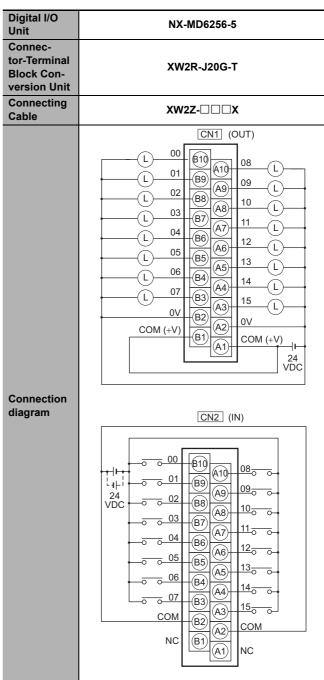
lote 1. The polarity for input power supply connections indicated with dotted lines (----) can be connected in either direction.

2. The COM terminals and +V terminals are internally connected inside the Unit, but they must all be wired.



Note 1. The polarity for input power supply connections indicated with dotted lines (----) can be connected in either direction.

2. The COM terminals and 0 V terminals are internally connected inside the Unit, but they must all be wired.



Note 1. The polarity for input power supply connections indicated with dotted lines (----) can be connected in either direction.

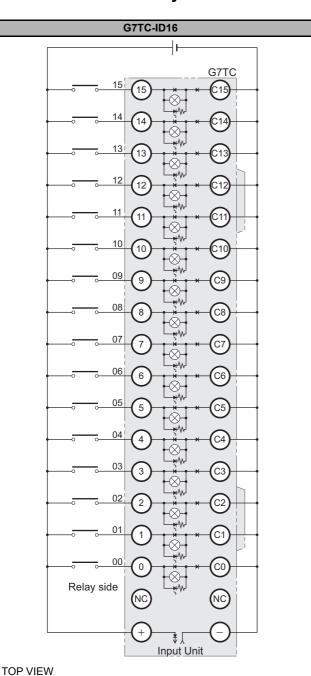
2. The COM terminals and 0 V terminals are internally connected inside the Unit, but they must all be wired.

## A-3-4 Connection Diagrams for I/O Relay Terminals

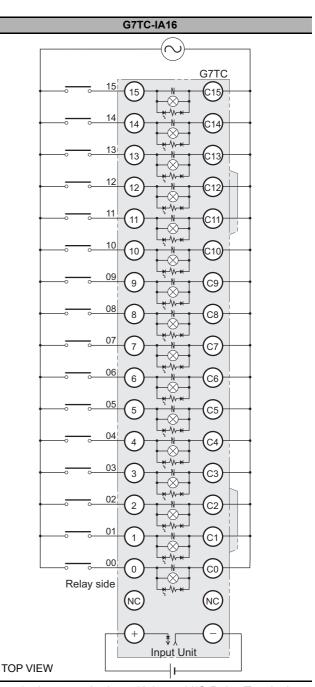
Connection examples and internal connection diagrams for I/O Relay Terminals connected to Digital I/O Units are shown below.

#### **Inputs**

#### G7TC I/O Relay Terminals



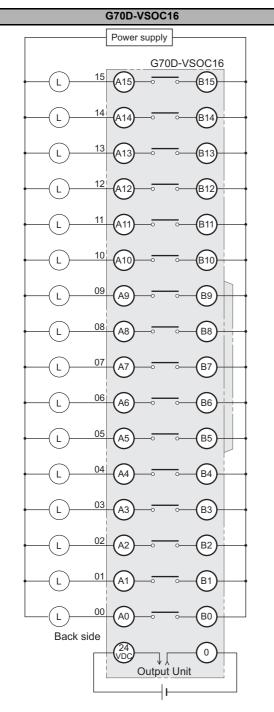
- Note 1. Inputs to the Input Units and I/O Relay Terminals use isolated contacts. "00" to "15" are the input bit numbers for the Input Unit and the I/O Relay Terminal
  - Use the G78-04 short bar to short to the common terminal.



- Note 1. Inputs to the Input Units and I/O Relay Terminals use isolated contacts. "00" to "15" are the input bit numbers for the Input Unit and the I/O Relay Terminal.
  - 2. Use the G78-04 short bar to short to the common terminal.

## Outputs

#### G70D-V Relay Terminals



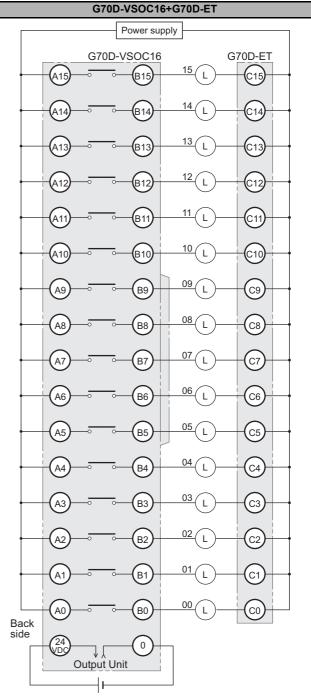
TOP VIEW

Note 1. All outputs are independent.

They are also isolated from the Output Unit and I/O Relay Terminal.

"00" to "15" are the output numbers for the Output Unit and the I/O Relay Terminal.

2. Use the G6D-4-SB short bar to short to the common terminal.



TOP VIEW

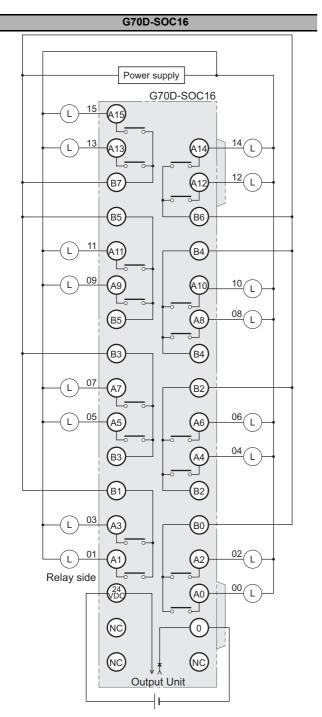
Note 1. All outputs are independent.

They are also isolated from the Output Unit and I/O Relay Terminal.

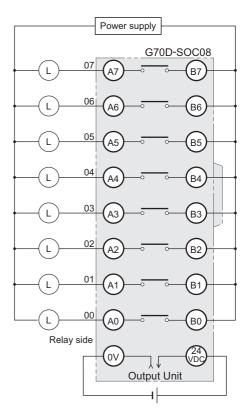
"00" to "15" are the output numbers for the Output Unit and the I/O Relay Terminal.

2. Use the G6D-4-SB short bar to short to the common terminal.

#### • G70D Relay Terminals



G70D-SOC08



TOP VIEW

Note 1. Every two outputs share a common. The current supplied is 3 A per common.

They are also isolated from the Output Unit and I/O Relay Terminal.

"00" to "15" are the output numbers for the Output Unit and the I/O Relay Terminal.

#### TOP VIEW

Note 1. All outputs are independent.

They are also isolated from the Output Unit and I/O Relay Terminal.

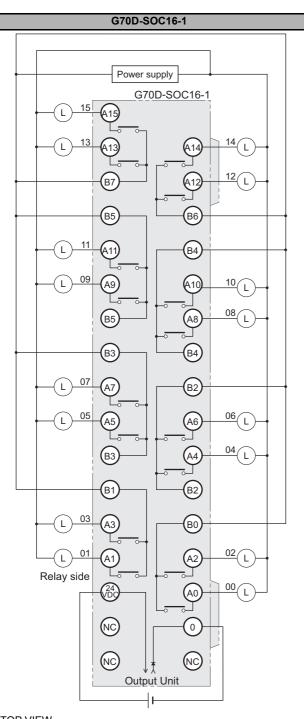
"00" to "07" are the output numbers for the Output Unit and the I/O Relay Terminal.

2. Use the G6D-4-SB short bar to short to the common terminal.

#### • G70D Relay Terminals

#### • G70R Relay Terminals

G70R-SOC08



Power supply G70R-SOC08 В6 B2 В0 **Output Unit** 

TOP VIEW

Note 1. Every two outputs share a common. The current supplied is 3 A per common.

> They are also isolated from the Output Unit and I/O Relay Terminal.

"00" to "15" are the output numbers for the Output Unit and the I/O Relay Terminal.

#### **TOP VIEW**

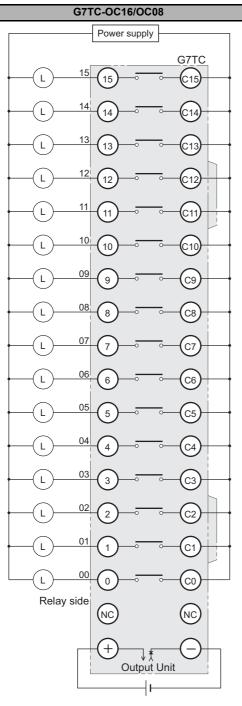
Note 1. All outputs are independent.

They are also isolated from the Output Unit and I/O Relay Terminal.

"00" to "07" are the output numbers for the Output Unit and the I/O Relay Terminal.

2. Use the G6D-4-SB short bar to short to the common terminal.

#### • G7TC I/O Relay Terminals



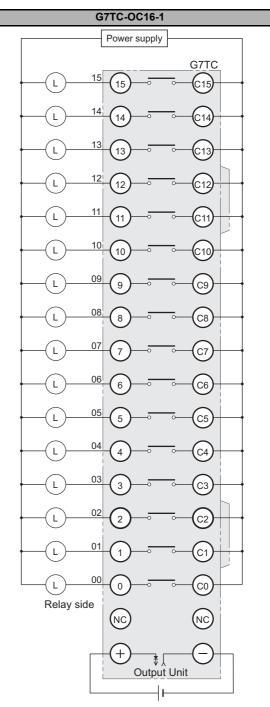
TOP VIEW

Note 1. All outputs are independent.

They are also isolated from the Output Unit and I/O Relay Terminal.

"00" to "15" are the output numbers for the Output Unit and the I/O Relay Terminal.

- 2. The G7TC-OC08 has only 8 outputs and therefore does not have 8 to 15 and C8 to C15.
- 3. Use the G78-04 short bar to short to the common terminal.



#### TOP VIEW

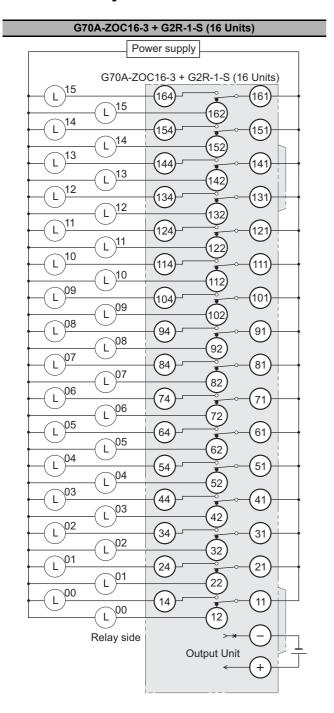
Note 1. All outputs are independent.

They are also isolated from the Output Unit and I/O Relay Terminal.

"00" to "15" are the output numbers for the Output Unit and the I/O Relay Terminal.

2. Use the G78-04 short bar to short to the common terminal.

## G70A-ZOC16 Relay Terminal Socket



**TOP VIEW** 

Note 1. The above diagram is an example with the G2R-1-S (N) mounted to the G70A-ZOC16-3.

2. All outputs are independent.

They are also isolated from the Output Unit and I/O Relay Terminal.

"00" to "15" are the output numbers for the Output Unit and the I/O Relay Terminal.

## A-4 EMC Directive Measures for Relay Outputs

#### Conformance to EC Directives

The NX-series I/O Units conform to the Common Emission Standards (EN 61131-2) of the EMC Directives. However, when incorporating in the system, noise generated by relay output switching may not satisfy these Standards.

In such a case, appropriate countermeasures must be provided externally to the Output Unit, such as by connecting a contact protection circuit. Countermeasures taken to satisfy the standards vary depending on the devices on the load side, wiring, configuration of machines, etc.

#### Countermeasures

- Countermeasures are not required: the switching frequency of the entire system incorporating the Output Unit is less than 5 times per minute
- Countermeasures are required: the switching frequency of the entire system incorporating the Output Unit is more than 5 times per minute

Refer to EN 61131-2 for details.

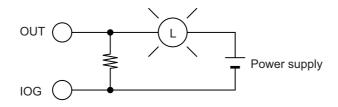
#### Countermeasure Example

The following measures must be taken.

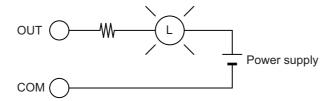
Use the measures to reduce the noises that are occurred.

- When switching an inductive load, connect a contact protection circuit in parallel with the load or contact. (Refer to *Inductive Load* on page 7-21.)
- When switching a load with a high inrush current such as an incandescent lamp, use either of the following methods to reduce the inrush current.

<Method 1. Draw about 1/3 of the current consumed by the load.>



<Method 2. Mount a limiting resistor.>



## A-5 List of NX Objects

This section describes the NX objects of the Digital I/O Units.

The method to access NX objects through instructions or other messages depends on where the NX Unit is connected.

If the NX Unit is connected to a CPU Unit, access is possible with the Read NX Unit Object instruction and the Write NX Unit Object instruction.

When the NX Unit is connected to a Communications Coupler Unit, the method depends on the connected communications master and Communications Coupler Unit.

Refer to the user's manual for the connected Communications Coupler Unit for method to use messages to access NX objects on Slave Terminals.

Refer to the user's manual for the Communication Control Unit for the method to use messages to access NX objects of NX Units connected to a Communication Control Unit.

#### A-5-1 Format of Object Descriptions

In this manual, NX objects are described with the following format.

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute

Index (Hex) : This is the index of the NX object that is expressed as a four-digit hexadecimal

number

Subindex (Hex) : This is the subindex of the NX object that is expressed as a two-digit hexadeci-

mal number.

Object name : This is the name of the object. For a subindex, this is the name of the subindex.

Default value : This is the value that is set by default.

Data range : For a read-only (RO) NX object, this is the range of the data you can read. For a

read-write (RW) NX object, this is the setting range of the data.

Unit : The unit is the physical units.

Data type : This is the data type of the object.

Access : This data tells if the object is read-only or read/write.

RO: Read only RW: Read/write

I/O allocation : This tells whether I/O allocation is allowed.

Data attribute : This is the timing when changes to writable NX objects are enabled.

Y: Enabled by restarting
N: Enabled at all times
---: Write-prohibited

#### A-5-2 Digital Input Units

### **Unit Information Objects**

This object gives the product information.

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cation	Data attri- bute
1000		NX Bus Identity							
	00	Number of Entries	7	7		USINT	RO	Not possible	
	02	Model	*1			ARRAY [011]OF BYTE	RO	Not possible	
	03	Device Type	*2			UDINT	RO	Not possible	
	04	Product Code	*3			UDINT	RO	Not possible	
	05	Vendor Code	00000001 hex *4			UDINT	RO	Not possible	
	06	Unit Version	*5			UDINT	RO	Not possible	
	07	Serial Number	*6	00000000 to FFFFFFF hex		UDINT	RO	Not possible	
1001		Production Info							
	00	Number of Entries	2	2		USINT	RO	Not possible	
	01	Lot Number	*7	00000000 to FFFFFFF hex		UDINT	RO	Not possible	
	02	Hardware Version	*8			ARRAY [019] OF BYTE	RO	Not possible	

<sup>\*1.</sup> The product models are assigned in ascending order from the lowest number of array elements. Any remainder elements are filled with spaces.

Bits 0 to 31: Device type

\*3. The product codes are assigned for each product model.

Bits 0 to 31: Product code

- \*4. OMRON vendor code
- \*5. Bits 24 to 31: Integer part of the Unit version.

Bits 16 to 23: Fractional part of the Unit version.

Bits 0 to 15: Reserved

(Example) For Ver.1.0, 0100□□□□ hex

\*6. A unique serial number is assigned for each product unit.

Bits 0 to 31: Serial number

\*7. The year, month, and day of production are assigned to the "lot number".

Bits 24 to 31: Date of production

Bits 16 to 23: Month of production

Bits 8 to 15: Year of production

Bits 0 to 7: Reserved

\*8. The hardware version is assigned in ascending order from the earliest number of array elements. Any remainder elements are filled with spaces.

<sup>\*2.</sup> The device types are assigned for each product Unit type.

## Objects That Accept I/O Allocations

These objects accept I/O allocations.

You cannot access the objects that are described below with the Read NX Unit Object instruction, Write NX Unit Object instruction, or other messages.

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
6000		Bit Input							
	00	Number of Entries	*1	*1		USINT	RO	Not pos- sible	
	01	Input Bit 00	FALSE	TRUE or FALSE		BOOL	RO	Pos- sible	
	02	Input Bit 01	FALSE	TRUE or FALSE		BOOL	RO	Pos- sible	
	03	Input Bit 02	FALSE	TRUE or FALSE		BOOL	RO	Pos- sible	
	04	Input Bit 03	FALSE	TRUE or FALSE		BOOL	RO	Pos- sible	

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-ID3317/ID3343/ID3417/ID3443/	4	4 (fixed)
ID3344/ID3444/IA3117		
Other models	0	0 (fixed)

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
6001		BYTE Input							
	00	Number of Entries	*1	*1		USINT	RO	Not	
								pos-	
								sible	
	01	Input Bit 8 bits	00 hex	00 to FF hex *2		BYTE	RO	Pos-	
								sible	

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-ID4342/ID4442	1	1 (fixed)
Other models	0	0 (fixed)

\*2. Detailed data for Input Bit 8 bits are as follows.

Bit 0: Input Bit 00 Bit 1: Input Bit 01

.

Bit 7: Input Bit 07

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
6002		Word Input							
	00	Number of Entries	*1	*1		USINT	RO	Not	
								pos-	
								sible	
	01	Input Bit 16 bits	0000 hex	0000 to FFFF		WORD	RO	Pos-	
				hex *2				sible	

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-ID5142-1/ID5142-5/ID5342/ID5442	1	1 (fixed)
Other models	0	0 (fixed)

\*2. Detailed data for Input Bit 16 bits are as follows.

Bit 0: Input Bit 00 Bit 1: Input Bit 01

.

Bit 15: Input Bit 15

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
6003		DWORD Input							
	00	Number of Entries	*1	*1		USINT	RO	Not possi ble	
	01	Input Bit 32 bits	00000000 hex	00000000 to FFFFFFF hex <sup>*2</sup>		DWORD	RO	Possi ble	

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range		
NX-ID6142-5/ID6142-6	1	1 (fixed)		
Other models	0	0 (fixed)		

\*2. Detailed data for Input Bit 32 bits are as follows.

Bit 0: Input Bit 00 Bit 1: Input Bit 01

.

Bit 31: Input Bit 31

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
6010		Time Stamp							
	00	Number of Entries	*1	*1		USINT	RO	Not	
								pos-	
								sible	
	01	Input Bit 00 Time Stamp	0	0 to	ns	ULINT	RO	Pos-	
				+18446744073				sible	
	02	Input Bit 01 Time Stamp		709551615		ULINT	RO	Pos-	
								sible	
	03	Input Bit 02 Time Stamp				ULINT	RO	Pos-	
								sible	
	04	Input Bit 03 Time Stamp				ULINT	RO	Pos-	
								sible	

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range		
NX-ID3344/ID3444	4	4 (fixed)		
Other models	0	0 (fixed)		

## Other Objects

This section lists other objects.

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
5000		Input Filter Setting							
	00	Number of Entries	*1	*1		USINT	RO	Not	
								pos-	
								sible	
	01	Input Filter Value Setting	3	0 to 11 *2		USINT	RW	Not	Υ
								pos-	
								sible	
	02	Input Filter Mode Setting	0	0/1 *3		USINT	RW	Not	Υ
								pos-	
								sible	

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-ID3317/ID3417/ID4342/ID4442/ID5142-1/	2	2 (fixed)
ID5142-5/ID5342/ID5442/ID6142-5/ID6142-6/		
IA3117		
Other models	0	0 (fixed)

\*2. The meaning of the set values for Input Filter Value Setting is as follows.

Set value	Meaning
0	No Filter
1	0.25 ms
2	0.5 ms
3	1 ms
4	2 ms
5	4 ms
6	8 ms
7	16 ms
8	32 ms
9	64 ms
10	128 ms
11	256 ms

\*3. The meaning of the set values for Input Filter Mode Setting is as follows.

Set value	Meaning				
0	Enable ON Filter and OFF Filter				
1	Enable Only OFF Filter				

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
5001		Input Filter Setting							
	00	Number of Entries	*1	*1		USINT	RO	Not	
								pos-	
								sible	
	01	Input Filter Value Setting	4	0 to 9 *2		USINT	RW	Not	Υ
								pos-	
								sible	
	02	Input Filter Mode Setting	0	0/1 *3		USINT	RW	Not	Υ
								pos-	
								sible	

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-ID3343/ID3443	2	2 (fixed)
Other models	0	0 (fixed)

\*2. The meaning of the set values for Input Filter Value Setting is as follows.

Set value	Meaning
0	No Filter
1	1 µs
2	2 µs
3	4 μs
4	8 µs
5	16 µs
6	32 µs
7	64 µs
8	128 µs
9	256 μs

\*3. The meaning of the set values for Input Filter Mode Setting is as follows.

Set value	Meaning				
0	Enable ON Filter and OFF Filter				
1	Enable Only OFF Filter				

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
5005		Time Stamp (Trigger Setting)							
	00	Number of Entries	*1	*1		USINT	RO	Not pos- sible	
	01	Input Bit 00 Trigger Setting	FALSE	TRUE or FALSE *2		BOOL	RW	Not pos- sible	Y
	02	Input Bit 01 Trigger Setting	FALSE			BOOL	RW	Not pos- sible	Y
	03	Input Bit 02 Trigger Setting	FALSE			BOOL	RW	Not pos- sible	Y
	04	Input Bit 03 Trigger Setting	FALSE			BOOL	RW	Not pos- sible	Υ

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-ID3344/ID3444	4	4 (fixed)
Other models	0	0 (fixed)

\*2. The meaning of the set values for Input Bit  $\Box\Box$  Trigger Setting is as follows.

Set value	Meaning
FALSE	Rising Edge
TRUE	Falling Edge

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
5006		Time Stamp (Mode Setting)							
	00	Number of Entries	*1	*1		USINT	RO	Not pos- sible	
	01	Input Bit 00 Mode Setting	FALSE	TRUE or FALSE *2		BOOL	RW	Not pos- sible	Y
	02	Input Bit 01 Mode Setting	FALSE			BOOL	RW	Not pos- sible	Υ
	03	Input Bit 02 Mode Setting	FALSE			BOOL	RW	Not pos- sible	Y
	04	Input Bit 03 Mode Setting	FALSE			BOOL	RW	Not pos- sible	Y

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-ID3344/ID3444	4	4 (fixed)
Other models	0	0 (fixed)

\*2. The meaning of the set values for Input Bit  $\Box\Box$  Mode Setting is as follows.

Set value	Meaning
FALSE	Continuous (Last changed time)
TRUE	One-shot (First changed time)

#### A-5-3 Digital Output Units

### **Unit Information Objects**

This object gives the product information.

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cation	Data attri- bute
1000		NX Bus Identity							
	00	Number of Entries	7	7		USINT	RO	Not possible	
	02	Model	*1			ARRAY [011]OF BYTE	RO	Not possible	
	03	Device Type	*2			UDINT	RO	Not possible	
	04	Product Code	*3			UDINT	RO	Not possible	
	05	Vendor Code	00000001 hex *4			UDINT	RO	Not possible	
	06	Unit Version	*5			UDINT	RO	Not possible	
	07	Serial Number	*6	00000000 to FFFFFFF hex		UDINT	RO	Not possible	
1001		Production Info							
	00	Number of Entries	2	2		USINT	RO	Not possible	
	01	Lot Number	*7	00000000 to FFFFFFF hex		UDINT	RO	Not possible	
	02	Hardware Version	*8			ARRAY [019] OF BYTE	RO	Not possible	

<sup>\*1.</sup> The product models are assigned in ascending order from the lowest number of array elements. Any remainder elements are filled with spaces.

Bits 0 to 31: Device type

\*3. The product codes are assigned for each product model.

Bits 0 to 31: Product code

- \*4. OMRON vendor code
- \*5. Bits 24 to 31: Integer part of the Unit version.

Bits 16 to 23: Fractional part of the Unit version.

Bits 0 to 15: Reserved

(Example) For Ver.1.0, 0100□□□□ hex

\*6. A unique serial number is assigned for each product unit.

Bits 0 to 31: Serial number

\*7. The year, month, and day of production are assigned to the "lot number".

Bits 24 to 31: Date of production

Bits 16 to 23: Month of production

Bits 8 to 15: Year of production

Bits 0 to 7: Reserved

\*8. The hardware version is assigned in ascending order from the earliest number of array elements. Any remainder elements are filled with spaces.

<sup>\*2.</sup> The device types are assigned for each product Unit type.

## Objects That Accept I/O Allocations

These objects accept I/O allocations.

You cannot access the objects that are described below with the Read NX Unit Object instruction, Write NX Unit Object instruction, or other messages.

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
7000		Bit Output							
	00	Number of Entries	*1	*1		USINT	RO	Not pos- sible	
	01	Output Bit 00	FALSE	TRUE or FALSE		BOOL	RW	Pos- sible	N
	02	Output Bit 01	FALSE	TRUE or FALSE		BOOL	RW	Pos- sible	N
	03	Output Bit 02	FALSE	TRUE or FALSE		BOOL	RW	Pos- sible	N
	04	Output Bit 03	FALSE	TRUE or FALSE		BOOL	RW	Pos- sible	N

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-OD3121/OD3153/OD3256/OD3257/ OD3268	4	4 (fixed)
NX-OD2154/OD2258/OC2633/OC2733	2	2 (fixed)
Other models	0	0 (fixed)

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
7001		BYTE Output							
	00	Number of Entries	*1	*1		USINT	RO	Not pos- sible	
	01	Output Bit 8 bits	00 hex	00 to FF hex		BYTE	RW	Pos- sible	N

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-OD4121/OD4256/OC4633	1	1 (fixed)
Other models	0	0 (fixed)

\*2. Detailed data for Output Bit 8 bits are as follows.

Bit 0: Output Bit 00 Bit 1: Output Bit 01

.

Bit 7: Output Bit 07

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
7002		Word Output							
	00	Number of Entries	*1	*1		USINT	RO	Not	
								pos-	
								sible	
	01	Output Bit 16 bits	0000 hex	0000 to FFFF		WORD	RW	Pos-	N
				hex				sible	

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-OD5121/OD5121-1/OD5121-5/OD5256/	1	1 (fixed)
OD5256-1/OD5256-5		
Other models	0	0 (fixed)

\*2. Detailed data for Output Bit 16 bits are as follows.

Bit 0: Output Bit 00 Bit 1: Output Bit 01

.

Bit 15: Output Bit 15

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
7003		DWORD Output							
	00	Number of Entries	*1	*1		USINT	RO	Not possi ble	
	01	Output Bit 32 bits	00000000 hex	00000000 to FFFFFFF hex*2		DWORD	RW	Possi ble	N

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-OD6121-5/OD6121-6/OD6256-5	1	1 (fixed)
Other models	0	0 (fixed)

\*2. Detailed data for Output Bit 32 bits are as follows.

Bit 0: Output Bit 00 Bit 1: Output Bit 01

.

Bit 31: Output Bit 31

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
7010		Time Stamp							
	00	Number of Entries	*1	*1		USINT	RO	Not	
								pos-	
								sible	
	01	Output Bit 00 Time Stamp	0	0 to	ns	ULINT	RW	Pos-	N
				+18446744073				sible	
	02	Output Bit 01 Time Stamp	1	709551615		ULINT	RW	Pos-	N
								sible	

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-OD2154/OD2258	2	2 (fixed)
Other models	0	0 (fixed)

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
6011		Specified Time Stamp Output Status							
	00	Number of Entries	*1	*1		USINT	RO	Not pos- sible	
	01	Output Bit 00 Output Status	FALSE	TRUE or FALSE *2		BOOL	RO	Pos- sible	N
	02	Output Bit 01 Output Status				BOOL	RO	Pos- sible	N

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-OD2154/OD2258	2	2 (fixed)
Other models	0	0 (fixed)

\*2. The meaning of the set values for Output Bit  $\square$  Output Status is as follows.

Set value	Meaning
FALSE	Output completion
TRUE	Waiting for output to refresh

## Other Objects

This section lists other objects.

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
5010		Load Rejection Output Setting							
	00	Number of Entries	*1	*1		USINT	RO	Not pos- sible	
	01	Load Rejection Output for Output Bit 00	FALSE	TRUE or FALSE *2		BOOL	RW	Not pos- sible	Y
	02	Load Rejection Output for Output Bit 01	FALSE			BOOL	RW	Not pos- sible	Y
	03	Load Rejection Output for Output Bit 02	FALSE			BOOL	RW	Not pos- sible	Υ
	04	Load Rejection Output for Output Bit 03	FALSE			BOOL	RW	Not pos- sible	Y

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-OD3121/OD3153/OD3256/OD3257/	4	4 (fixed)
OD3268		
NX-OC2633/OC2733	2	2 (fixed)
Other models	0	0 (fixed)

\*2. The meaning of the set values for Load Rejection Output for Output Bit  $\Box\Box$  is as follows.

Set value	Meaning
FALSE	OFF
TRUE	Hold the present value.

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
5011		Load Rejection Byte Set-							
		ting							
	00	Number of Entries	*1	*1		USINT	RO	Not	
								pos-	
								sible	
	01	Load Rejection Output for	00 hex	00 to FF hex*2		BYTE	RW	Not	Υ
		Output Bit (8 bits)						pos-	
								sible	

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-OD4121/OD4256/OC4633	1	1 (fixed)
Other models	0	0 (fixed)

\*2. The detailed data and meaning of the set values for Load Rejection Output for Output Bit (8 bits) are as follows.

Bit 0: Load Rejection Output for Output Bit 00

Bit 1: Load Rejection Output for Output Bit 01

.

Bit 7: Load Rejection Output for Output Bit 07

Set value	Meaning
0	OFF
1	Hold the present value.

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
5012		Load Rejection Word Set-							
		ting							
	00	Number of Entries	*1	*1		USINT	RO	Not	
								pos-	
								sible	
	01	Load Rejection Output for	0000 hex	0000 to FFFF		WORD	RW	Not	Υ
		Output Bit (16 bits)		hex*2				pos-	
								sible	

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-OD5121/OD5121-1/OD5121-5/OD5256/	1	1 (fixed)
OD5256-1/OD5256-5		
Other models	0	0 (fixed)

\*2. The detailed data and meaning of the set values for Load Rejection Output for Output Bit (16 bits) are as follows.

Bit 0: Load Rejection Output for Output Bit 00

Bit 1: Load Rejection Output for Output Bit 01

.

Bit 15: Load Rejection Output for Output Bit 15

Set value	Meaning
0	OFF
1	Hold the present value.

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
5013		Load Rejection DWord							
		Setting							
	00	Number of Entries	*1	*1		USINT	RO	Not	
								possi	
								ble	
	01	Load Rejection Output for	00000000	00000000 to		DWORD	RW	Not	Υ
		Output Bit (32 bits)	hex	FFFFFFF hex				possi	
				*2				ble	

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-OD6121-5/OD6121-6/OD6256-5	1	1 (fixed)
Other models	0	0 (fixed)

\*2. The detailed data and meaning of the set values for Load Rejection Output for Output Bit (32 bits) are as follows.

Bit 0: Load Rejection Output for Output Bit 00

Bit 1: Load Rejection Output for Output Bit 01

.

Bit 31: Load Rejection Output for Output Bit 31

Set value	Meaning
0	OFF
1	Hold the present value.

#### A-5-4 Digital Mixed I/O Units

## Unit Information Objects

This object gives the product information.

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
1000		NX Bus Identity							
	00	Number of Entries	7	7		USINT	RO	Not pos- sible	
	02	Model	*1			ARRAY [011] OF BYTE	RO	Not pos- sible	
	03	Device Type	*2			UDINT	RO	Not pos- sible	
	04	Product Code	*3			UDINT	RO	Not pos- sible	
	05	Vendor Code	00000001 hex *4			UDINT	RO	Not pos- sible	
	06	Unit Version	*5			UDINT	RO	Not pos- sible	
	07	Serial Number	*6	00000000 to FFFFFFF hex		UDINT	RO	Not pos- sible	
1001		Production Info							
	00	Number of Entries	2	2		USINT	RO	Not pos- sible	
	01	Lot Number	*7	00000000 to FFFFFFF hex		UDINT	RO	Not pos- sible	
	02	Hardware Version	*8			ARRAY [019] OF BYTE	RO	Not pos- sible	

<sup>\*1.</sup> The product models are assigned in ascending order from the lowest number of array elements. Any remainder elements are filled with spaces.

Bits 0 to 31: Device type

\*3. The product codes are assigned for each product model.

Bits 0 to 31: Product code

\*4. OMRON vendor code

\*5. Bits 24 to 31: Integer part of the Unit version.

Bits 16 to 23: Fractional part of the Unit version.

Bits 0 to 15: Reserved

(Example) For Ver.1.0, 0100□□□□ hex

\*6. A unique serial number is assigned for each product unit.

Bits 0 to 31: Serial number

<sup>\*2.</sup> The device types are assigned for each product Unit type.

\*7. The year, month, and day of production are assigned to the "lot number".

Bits 24 to 31: Date of production Bits 16 to 23: Month of production Bits 8 to 15: Year of production Bits 0 to 7: Reserved

\*8. The hardware version is assigned in ascending order from the earliest number of array elements. Any remainder elements are filled with spaces.

## Objects That Accept I/O Allocations

These objects accept I/O allocations.

You cannot access the objects that are described below with the Read NX Unit Object instruction, Write NX Unit Object instruction, or other messages.

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
6002		WORD Input							
	00	Number of Entries	*1	*1		USINT	RO	Not	
								pos-	
								sible	
	01	Input Bit 16 bits	0000 hex	0000 to FFFF		WORD	RO	Pos-	
				hex *2				sible	

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-MD6121-5/MD6121-6/MD6256-5	1	1 (fixed)
Other models	0	0 (fixed)

\*2. Detailed data for Input Bit 16 bits are as follows.

Bit 0: Input Bit 00 Bit 1: Input Bit 01

Bit 15: Input Bit 15

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
7002		WORD Output							
	00	Number of Entries	*1	*1		USINT	RO	Not	
								pos-	
								sible	
	01	Output Bit 16 bits	0000 hex	0000 to FFFF		WORD	RW	Pos-	N
				hex *2				sible	

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-MD6121-5/MD6121-6/MD6256-5	1	1 (fixed)
Other models	0	0 (fixed)

\*2. Detailed data for Output Bit 16 bits are as follows.

Bit 0: Output Bit 00 Bit 1: Output Bit 01

.

Bit 15: Output Bit 15

## Other Objects

This section lists other objects.

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
5000		Input Filter Setting							
	00	Number of Entries	*1	*1		USINT	RO	Not	
								pos-	
								sible	
	01	Input Filter Value Setting	3	0 to 11 *2		USINT	RW	Not	Υ
								pos-	
								sible	
	02	Input Filter Mode Setting	0	0/1 *3		USINT	RW	Not	Υ
								pos-	
								sible	

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-MD6121-5/MD6121-6/MD6256-5	2	2 (fixed)
Other models	0	0 (fixed)

\*2. The meaning of the set values for Input Filter Value Setting is as follows.

Set value	Meaning
0	No Filter
1	0.25 ms
2	0.5 ms
3	1 ms
4	2 ms
5	4 ms
6	8 ms
7	16 ms
8	32 ms
9	64 ms
10	128 ms
11	256 ms

\*3. The meaning of the set values for Input Filter Mode Setting is as follows.

Set value	Meaning
0	Enable ON Filter and OFF Filter
1	Enable Only OFF Filter

Index (hex)	Subindex (hex)	Object name	Default value	Data range	Unit	Data type	Acc ess	I/O allo- cat- ion	Data attri- bute
5012		Load Rejection Word Set-							
		ting							
	00	Number of Entries	*1	*1		USINT	RO	Not	
								pos-	
								sible	
	01	Load Rejection Output for	0000 hex	0000 to FFFF		WORD	RW	Not	Υ
		Output Bit (16 bits)		hex *2				pos-	
								sible	

<sup>\*1.</sup> The default value and data range for Number of Entries are as follows.

NX Units	Default value	Data range
NX-MD6121-5/MD6121-6/MD6256-5	1	1 (fixed)
Other models	0	0 (fixed)

\*2. The detailed data and meaning of the set values for Load Rejection Output for Output Bit (16 bits) are as follows.

Bit 0: Load Rejection Output for Output Bit 00

Bit 1: Load Rejection Output for Output Bit 01

.

Bit 15: Load Rejection Output for Output Bit 15

Set value	Meaning
0	OFF
1	Hold the present value.

# A-6 List of Screwless Clamping Terminal Block Models

This section explains how to read the screwless clamping terminal block model numbers and shows the model number table.

#### A-6-1 Model Notation

The screwless clamping terminal block models are assigned based on the following rules.

	$NX-TB \square \square \square \square$
Product type ————————————————————————————————————	
Terminal specifications  A: Column letter indication A/B, without fu B: Column letter indication C/D, without fu C: Column letter indication A/B, with funct	inctional ground terminal
Number of terminals  08: 8 terminals  12: 12 terminals  16: 16 terminals	
Other specifications	

#### A-6-2 List of Terminal Block Models

1: Terminal current capacity of 4 A2: Terminal current capacity of 10 A

The following table shows a list of screwless clamping terminal blocks.

Terminal block model	Number of terminals	Ground terminal mark	Terminal current capacity
NX-TBA081	8	Not provided	4 A
NX-TBA121	12	1	
NX-TBA161	16	1	
NX-TBB121	12	1	
NX-TBB161	16	1	
NX-TBA082	8		10 A
NX-TBA122	12	1	
NX-TBA162	16	1	
NX-TBB082	8	1	
NX-TBB122	12	1	
NX-TBB162	16	1	
NX-TBC082	8	Provided	1
NX-TBC162	16		

Note When you purchase a terminal block, purchase an NX-TB $\square\square\square$ 2.

## A-7 Version Information with CPU Units

This section provides version-related information when connecting Units to a CPU Unit.

This section describes the relationship between the unit versions of each Unit and the CPU Unit, and Sysmac Studio version, and the specification changes for each unit version of each Unit.

#### A-7-1 Relationship between Unit Versions of Units

The relationship between the unit versions of each Unit and the CPU Unit, and Sysmac Studio version are shown below.

#### **Interpreting the Version Combination Tables**

The items that are used in the version combination tables are given below.

Refer to the user's manual for the CPU Unit for the models of CPU Unit to which NX Units can be connected.

NX	Unit	Corresponding unit versions/versions			
Model	Unit version	CPU Unit	Sysmac Studio		
Model number of NX Units.	Unit versions of NX Units.	Unit versions of the CPU that are compatible with the NX Units.	Sysmac Studio versions that are compatible with the NX Units and CPU Unit.		

#### **Version Combination Tables**

- With the combinations of the unit versions/versions shown below, you can use the functions that are supported by the unit version of the Unit model. Use the unit versions/versions (or the later/higher unit versions/versions) that correspond to the NX Unit models and the unit versions. You cannot use the specifications that were added or changed for the relevant NX Unit models and the unit versions unless you use the corresponding unit versions/versions.
- Depending on the type and model of the Unit to which the NX Unit is connected, some Units do not have the corresponding versions given in the table. If a Unit does not have the specified version, support is provided by the oldest available version after the specified version. Refer to the user's manuals for the specific Units for the relation between models and versions.
- If you use the corresponding unit versions/versions given in the following table or later/higher versions, refer to the version information in the user's manual for the CPU Unit.

NX Un	-		t versions/versions
Model	Unit version	CPU Unit	Sysmac Studio
NX-ID3317	Ver.1.0	Ver.1.13	Ver.1.17
NX-ID3343			
NX-ID3344			
NX-ID3417			
NX-ID3443			
NX-ID3444			
NX-ID4342			
NX-ID4442	_		
NX-ID5142-1			
NX-ID5142-5			
NX-ID5342			
NX-ID5442			
NX-ID6142-5			
NX-ID6142-6			
NX-IA3117			
NX-OD2154			
NX-OD2258			
NX-OD3121			
NX-OD3153			
NX-OD3256			
NX-OD3257			
NX-OD3268			
NX-OD4121			
NX-OD4256			
NX-OD5121			
NX-OD5121-1			
NX-OD5121-5			
NX-OD5256			
NX-OD5256-1			
NX-OD5256-5			
NX-OD6121-5			
NX-OD6121-6			
NX-OD6256-5			
NX-OC2633			
NX-OC2733			
NX-OC4633	1		
NX-MD6121-5	1		
NX-MD6121-6	1		
NX-MD6256-5			

# A-8 Version Information with Communications Coupler Units

This section provides version-related information when connecting Units to a Communications Coupler Unit

Version information is provided separately for each Communications Coupler Unit that an NX Unit is connected to.

#### A-8-1 Connection to an EtherCAT Coupler Unit

The relationship between the unit versions of each Unit, EtherCAT Coupler Unit, CPU Unit and Industrial PC, and versions of the Sysmac Studio are shown below.

#### **Relationship between Unit Versions of Units**

The items that are used in the version combination tables are given below.

NX	Unit	Corresponding unit versions/versions				
Model Unit version		EtherCAT Coupler Unit	CPU Unit or Indus- trial PC	Sysmac Studio		
Model numbers of NX Units.	Unit versions of NX Units.	Unit versions of EherCAT Coupler Units that are com- patible with the NX Units.	Unit versions of NJ/NX-series CPU Units or NY-series Industrial PCs that are compatible with the EtherCAT Coupler Units.	Sysmac Studio versions that are compatible with the NX Units, EtherCAT Coupler Units, CPU Units, and Industrial PCs.		

The version combination table is given below.

- With the combinations of the unit versions/versions shown below, you can use the functions that are supported by the unit version of the Unit model. Use the unit versions/versions (or the later/higher unit versions/versions) that correspond to the NX Unit models and the unit versions. You cannot use the specifications that were added or changed for the relevant NX Unit models and the unit versions unless you use the corresponding unit versions/versions.
- Depending on the type and model of the Unit to which the NX Unit is connected, some Units do not
  have the corresponding versions given in the table. If a Unit does not have the specified version, support is provided by the oldest available version after the specified version. Refer to the user's manuals for the specific Units for the relation between models and versions.
- You cannot connect the relevant NX Unit to the target Communications Coupler Unit if "---" is shown in the corresponding unit versions/versions column.
- If you use the corresponding unit versions/versions given in the following table or later/higher versions, refer to the version information in the user's manual for the Communications Coupler Unit, CPU Unit, and Industrial PC.

N	X Unit	Corresponding unit versions/versions				
Model	Unit version	EtherCAT Coupler Unit	CPU Unit or Industrial PC	Sysmac Studio		
NX-ID3317	Ver.1.0	Ver.1.0	Ver.1.05	Ver.1.06		
NX-ID3343						
NX-ID3344		Ver.1.1	Ver.1.06*1	Ver.1.07		
NX-ID3417		Ver.1.0	Ver.1.05	Ver.1.06		
NX-ID3443						
NX-ID3444		Ver.1.1	Ver.1.06*1	Ver.1.07		
NX-ID4342		Ver.1.0	Ver.1.05	Ver.1.06		
NX-ID4442						
NX-ID5142-1				Ver.1.13		
NX-ID5142-5				Ver.1.10		
NX-ID5342				Ver.1.06		
NX-ID5442						
NX-DA3603				Ver.1.10		
NX-DA3603				Ver.1.13		
NX-IA3117				Ver.1.08		
NX-OD2154		Ver.1.1	Ver.1.06*1	Ver.1.07		
NX-OD2258						
NX-OD3121		Ver.1.0	Ver.1.05	Ver.1.06		
NX-OD3153						
NX-OD3256						
NX-OD3257						
NX-OD3268				Ver.1.13		
NX-OD4121				Ver.1.06		
NX-OD4256						
NX-OD5121						
NX-OD5121-1				Ver.1.13		
NX-OD5121-5				Ver.1.10		
NX-OD5256				Ver.1.06		
NX-OD5256-1				Ver.1.13		
NX-OD5256-5				Ver.1.10		
NX-OD6121-5						
NX-OD6121-6				Ver.1.13		
NX-OD6256-5				Ver.1.10		
NX-OC2633				Ver.1.06		
NX-OC2733				Ver.1.08		
NX-OC4633				Ver.1.17		
NX-MD6121-5				Ver.1.10		
NX-MD6121-6				Ver.1.13		
NX-MD6256-5				Ver.1.10		

<sup>\*1.</sup> If you use a CPU Unit, the instructions for time stamp refreshing are supported by CPU Units with unit version 1.06 or later. If you do not use instructions for time stamp refreshing, you can use version 1.05. Refer to the instructions reference manual for the connected CPU Unit or Industrial PC for details on the instructions for time stamp refreshing.

#### A-8-2 Connection to an EtherNet/IP Coupler Unit

The relationship between the unit versions of each Unit, EtherNet/IP Coupler Unit, CPU Unit and Industrial PC, and versions of the Sysmac Studio and NX-IO Configurator are shown below.

### Relationship between Unit Versions of Units

The items that are used in the version combination tables are given below.

NX Unit		Corresponding unit versions/versions						
		Application with an NJ/NX/NY-series Controller			Application with a CS/CJ/CP-series PLC			
Model	Unit version	EtherNet/IP Coupler Unit	CPU Unit or Industrial PC	Sysmac Stu- dio	EtherNet/IP Coupler Unit	Sysmac Stu- dio	NX-IO Con- figurator	
Model num- ber of NX Unit	Unit version of the NX Unit	Unit version of Ether- Net/IP Cou- pler Unit that is compati- ble with the NX Unit	Unit version of NJ/NX-series CPU Unit or NY-series Industrial PC that is com- patible with the Ether- Net/IP Cou- pler Unit	Sysmac Studio version that is compatible with the NX Unit, EtherNet/IP Coupler Unit, CPU Unit, and Industrial PC	Unit version of Ether- Net/IP Cou- pler Unit that is compati- ble with the NX Unit	Sysmac Stu- dio version that is com- patible with the NX Unit, EtherNet/IP Coupler Unit, and CPU Unit	NX-IO Configurator version that is compatible with the NX Unit, Ether-Net/IP Coupler Unit, and CPU Unit	

The version combination table is given below.

- With the combinations of the unit versions/versions shown below, you can use the functions that are supported by the unit version of the Unit model. Use the unit versions/versions (or the later/higher unit version/versions) that correspond to the NX Unit models and the unit versions. You cannot use the specifications that were added or changed for the relevant NX Unit models and the unit versions unless you use the corresponding unit versions/versions.
- Depending on the type and model of the Unit to which the NX Unit is connected, some Units do not
  have the corresponding versions given in the table. If a Unit does not have the specified version, support is provided by the oldest available version after the specified version. Refer to the user's manuals for the specific Units for the relation between models and versions.
- You cannot connect the relevant NX Unit to the target Communications Coupler Unit if "---" is shown in the corresponding unit versions/versions column.
- If you use the corresponding unit versions/versions given in the following table or later/higher versions, refer to the version information in the user's manual for the Communications Coupler Unit, CPU Unit, and Industrial PC.

NX Uı	nit	Corresponding unit versions/versions						
Model	Unit ver-	Application	n with an NJ/NX/l Controller *1				P-series PLC *2	
Wodei	sion	EtherNet/IP Coupler Unit	CPU Unit or Industrial PC	Sysmac Studio	EtherNet/IP Coupler Unit	Sysmac Studio	NX-IO Config- urator *3	
NX-ID3317	Ver. 1.0	Ver. 1.2	Ver. 1.14	Ver. 1.19	Ver. 1.0	Ver. 1.10	Ver. 1.00	
NX-ID3343								
NX-ID3344								
NX-ID3417		Ver. 1.2	Ver. 1.14	Ver. 1.19	Ver. 1.0	Ver. 1.10	Ver. 1.00	
NX-ID3443								
NX-ID3444								
NX-ID4342		Ver. 1.2	Ver. 1.14	Ver. 1.19	Ver. 1.0	Ver. 1.10	Ver. 1.00	
NX-ID4442								
NX-ID5142-1						Ver. 1.13		
NX-ID5142-5						Ver. 1.10		
NX-ID5342								
NX-ID5442								
NX-ID6142-5								
NX-ID6142-6						Ver. 1.13		
NX-IA3117						Ver. 1.10		
NX-OD2154								
NX-OD2258								
NX-OD3121		Ver. 1.2	Ver. 1.14	Ver. 1.19	Ver. 1.0	Ver. 1.10	Ver. 1.00	
NX-OD3153								
NX-OD3256								
NX-OD3257								
NX-OD3268						Ver. 1.13		
NX-OD4121						Ver. 1.10		
NX-OD4256								
NX-OD5121								
NX-OD5121-1						Ver. 1.13		
NX-OD5121-5						Ver. 1.10		
NX-OD5256								
NX-OD5256-1						Ver. 1.13		
NX-OD5256-5						Ver. 1.10		
NX-OD6121-5								
NX-OD6121-6						Ver. 1.13		
NX-OD6256-5						Ver. 1.10		
NX-OC2633								
NX-OC2733								
NX-OC4633						Ver. 1.17		
NX-MD6121-5						Ver. 1.10		
NX-MD6121-6						Ver. 1.13		
NX-MD6256-5						Ver. 1.10		

<sup>\*1.</sup> Refer to the user's manual for the EtherNet/IP Coupler Units for information on the unit versions of EtherNet/IP Units that are compatible with EtherNet/IP Coupler Units.

<sup>\*2.</sup> Refer to the user's manual for the EtherNet/IP Coupler Units for information on the unit versions of CPU Units and EtherNet/IP Units that are compatible with EtherNet/IP Coupler Units.

<sup>\*3.</sup> For connection to an EtherNet/IP Coupler Unit with unit version 1.0, connection is supported only for a connection to the peripheral USB port on the EtherNet/IP Coupler Unit. You cannot connect by any other path. If you need to connect by another path, use an EtherNet/IP Coupler Unit with unit version 1.2 or later.

# A-9 Version Information with Communication Control Units

This section provides version-related information when connecting Units to a Communication Control Unit. This section describes the relationship between the unit versions of each Unit and the Communication Control Unit, and Sysmac Studio version, and the specification changes for each unit version of each Unit.

#### A-9-1 Relationship between Unit Versions of Units

The relationship between the unit versions of each Unit and the Communication Control Unit, and Sysmac Studio version are shown below.

### **Interpreting the Version Combination Tables**

The items that are used in the version combination tables are given below.

NX Unit		Corresponding unit versions/versions	
Model	Unit version	Communication Control Unit	Sysmac Studio
Model numbers of NX Units	Unit versions of NX Units	Unit versions of the Com- munication Control Unit that are compatible with the NX Units	Sysmac Studio versions that are compatible with the NX Units and Commu- nication Control Unit

#### Version Combination Tables

- With the combinations of the unit versions/versions shown below, you can use the functions that are supported by the unit version of the Unit model. Use the unit versions/versions (or the later/higher unit versions/versions) that correspond to the NX Unit models and the unit versions. You cannot use the specifications that were added or changed for the relevant NX Unit models and the unit versions unless you use the corresponding unit versions/versions.
- Depending on the type and model of the Unit to which the NX Unit is connected, some Units do not
  have the corresponding versions given in the table. If a Unit does not have the specified version, support is provided by the oldest available version after the specified version. Refer to the user's manuals for the specific Units for the relation between models and versions.
- You cannot connect the relevant NX Unit to the Communication Control Unit if "---" is shown in the corresponding unit versions/versions column.
- If you use the corresponding unit versions/versions given in the following table or later/higher versions, refer to the version information in the user's manual for the Communication Control Unit.

NX Unit		Corresponding unit versions/versions		
Model	Unit version	Communication Control Unit	Sysmac Studio	
NX-ID3317	Ver. 1.0	Ver. 1.00	Ver. 1.24	
NX-ID3343				
NX-ID3344	1			
NX-ID3417		Ver. 1.00	Ver. 1.24	
NX-ID3443	1			
NX-ID3444	Ver. 1.0			
NX-ID4342		Ver. 1.00	Ver. 1.24	
NX-ID4442				
NX-ID5142-1				
NX-ID5142-5				
NX-ID5342				
NX-ID5442				
NX-ID6142-5				
NX-ID6142-6				
NX-IA3117				
NX-OD2154				
NX-OD2258				
NX-OD3121		Ver. 1.00	Ver. 1.24	
NX-OD3153				
NX-OD3256				
NX-OD3257				
NX-OD3268				
NX-OD4121				
NX-OD4256				
NX-OD5121				
NX-OD5121-1				
NX-OD5121-5				
NX-OD5256				
NX-OD5256-1				
NX-OD5256-5				
NX-OD6121-5				
NX-OD6121-6				
NX-OD6256-5				
NX-OC2633				
NX-OC2733				
NX-OC4633				
NX-MD6121-5				
NX-MD6121-6				
NX-MD6256-5				

# A-10 Displaying the Edit Unit Operation Settings Tab Page

#### A-10-1 Connection to the CPU Unit or the Communication Control Unit

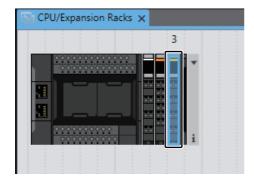
This section describes how to display the Edit Unit Operation Settings Tab Page that is used to create Unit operation settings on the Sysmac Studio for the NX Units connected to the CPU Unit or Communication Control Unit.

You can use the methods described below to display the Edit Unit Operation Settings Tab Page on the CPU and Expansion Racks Tab Page for the CPU Unit or Communication Control Unit on the Sysmac Studio.

Refer to the *Sysmac Studio Version 1 Operation Manual* (Cat. No. W504) for the method of displaying the CPU and Expansion Racks Tab Page.

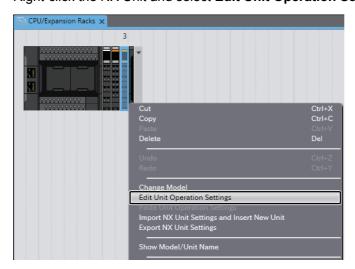
#### Method 1

Double-click the NX Unit to set.



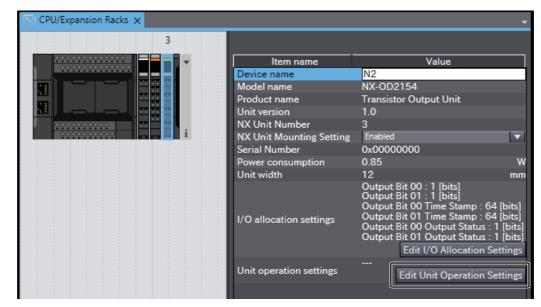
#### Method 2

Right-click the NX Unit and select Edit Unit Operation Settings from the menu.



#### Method 3

Select the NX Unit and click the **Edit Unit Operation Settings** Button.



#### A-10-2 Slave Terminal

This section describes how to display the Edit Unit Operation Settings Tab Page that is used to create Unit operation settings on the Sysmac Studio for NX Units in the Slave Terminal.

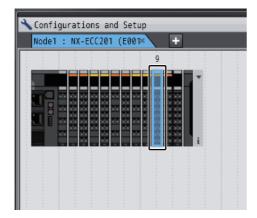
You can use the methods described below to display the Edit Unit Operation Settings Tab Page on the Edit Slave Terminal Configuration Tab Page on the Sysmac Studio.

Refer to the *Sysmac Studio Version 1 Operation Manual* (Cat. No. W504) for the method of displaying the Edit Slave Terminal Configuration Tab Page.

Refer to the operation manual for the Support Software that you are using for the method of displaying the Edit Slave Terminal Configuration Tab Page or Edit Unit Operation Settings Tab Page with Support Software other than Sysmac Studio.

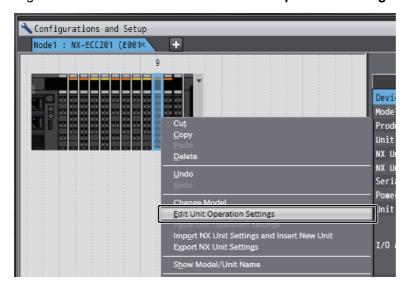
#### Method 1

Double-click the NX Unit to set.



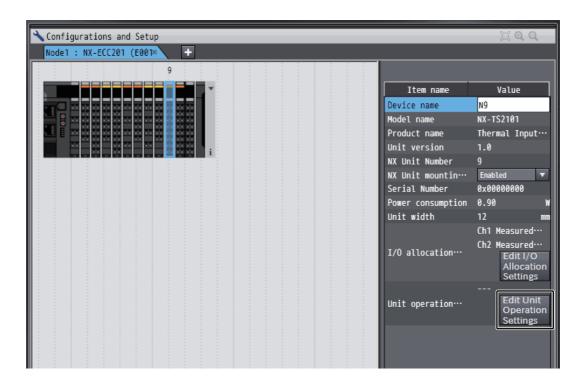
#### Method 2

Right-click the NX Unit and select Edit Unit Operation Settings from the menu.



#### Method 3

Select the NX Unit and click the **Edit Unit Operation Settings** Button.



٨			- 13	
ΑI	กท	er	าตเ	ices



## Index

## Index

Α	1
AC Input UnitA-40	I/O allocation
AccessA-140	I/O allocation setting6-4, 7-5, 8-3
Additional I/O Power Supply Unit4-10	I/O entry6-4, 7-5, 8-3
Additional NX Unit Power Supply Unit4-10	I/O entry mapping6-4, 7-5, 8-3
Applicable Wires4-14	I/O power supply4-9
Assumed cause9-7	I/O Power Supply Connection Unit 4-10
	I/O power supply terminal4-9
В	incorrect attachment prevention hole 4-27
	Index A-140
built-in EtherCAT port10	Indicator3-2, 3-3, 3-7, 3-8, 3-9, 3-10, 3-11, 3-12
	Inductive Load7-21
C	Industrial PC
	input changed time5-21
Coding Pin4-28	
<u> </u>	J
Communications Coupler Unit	
Communications Master Unit5-3	iunation temperature 7 17
Connector 3-8, 3-9, 3-10, 3-11, 3-12	junction temperature7-17
Contact Protection Circuit7-21	1
CPU Rack 1-6	L
CPU Unit5-3	
crimping tool4-15	Log of Error9-6
Current Error9-5	
D	Marker
Data attributeA-140	Marker attachment location
Data rangeA-140	3-2, 3-3, 3-7, 3-8, 3-9, 3-10, 3-11, 3-12
Data type	maximum current of I/O power supply4-11
DC enable5-8	maximum I/O power supply current4-11
DC Input Unit	
·	Model number indication3-14
DC Input/Transistor Output Unit	N
Default valueA-140	N
delay time	
DIN Track mounting hook	NX bus connector 3-2, 3-3, 3-7, 3-8, 3-9, 3-10, 3-11, 3-12
3-2, 3-3, 3-7, 3-8, 3-9, 3-10, 3-11, 3-12	NX ObjectA-140
_	NX Unit power supply4-9
E	NX_DOutTimeStamp5-30, 5-32
Front and	0
Event code	O
Event name9-7	
-	Object nameA-140
F	Objects That Accept I/O AllocationsA-142, A-150, A-159
	Other ObjectsA-145, A-154, A-161
Ferrule4-15	
forced refreshing4-40	Р
G	Destruction them.
•	Periodic Inspection Item
	Preventing Incorrect Attachment
Ground terminal4-15, 4-16	Protrusions for removing the Unit

#### R

Refresh cycle of the NX bus Relay Output Unit Release hole	A-81, A-85
s	
Screw terminal	
securing wire	
Slave Terminal	
Solid Wire	
specified time	
Subindex	
supply from external source	
supply from the NX bus	
Sync0synchronization timing	
synchronization timing	5-13, 5-17
Т	
Terminal block	2222427
Terminal block cover	
Terminal block lever	
Terminal hole	
Terminal number indication	
thermal shutdown temperature	
timing to read inputs	
timing to refresh outputs	
Transistor Output Unit	
Twisted Wire	4-16
U	
Unit	
Unit hookup guide 3-2, 3-3, 3-7, 3	
Unit Information Object	
Unit specifications 3-2, 3-3, 3-7,	3-8, 3-9, 3-10, 3-11, 3-12
W	
Wiring Terminals	A 12
**************************************	+-13

Index

**OMRON Corporation Industrial Automation Company** 

Kyoto, JAPAN

Contact: www.ia.omron.com

Regional Headquarters
OMRON EUROPE B.V.

Wegalaan 67-69, 2132 JD Hoofddorp The Netherlands Tel: (31)2356-81-300/Fax: (31)2356-81-388

OMRON ASIA PACIFIC PTE. LTD.
No. 438A Alexandra Road # 05-05/08 (Lobby 2),
Alexandra Technopark,
Singapore 119967
Tel: (65) 6835-3011/Fax: (65) 6835-2711

**OMRON ELECTRONICS LLC** 

2895 Greenspoint Parkway, Suite 200 Hoffman Estates, IL 60169 U.S.A. Tel: (1) 847-843-7900/Fax: (1) 847-843-7787

OMRON (CHINA) CO., LTD.
Room 2211, Bank of China Tower,
200 Yin Cheng Zhong Road,
PuDong New Area, Shanghai, 200120, China
Tel: (86) 21-5037-2222/Fax: (86) 21-5037-2200

**Authorized Distributor:** 

© OMRON Corporation 2013-2018 All Rights Reserved. In the interest of product improvement, specifications are subject to change without notice.

Cat. No. W521-E1-10